NI MATRIXx[™]

Xmath™ User Guide



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Appendix A Xmath HP-GL Driver

Appendix B Xmath for Users of the MathWorks, Inc. MATLAB® Software

Appendix C Xmath to Mathematica Interface

Appendix D Technical Support and Professional Services

Index

About This Manual

This manual introduces you to many features of Xmath. This manual focuses primarily on creating, manipulating, analyzing, and plotting data in Xmath. This manual also contains information about writing custom scripts.

This manual assumes you are familiar with navigating the MATRIXx Integrated Development Environment (IDE) and the project system. For more information about these topics, refer to the *MATRIXx Getting Started Guide*, available by selecting **Help»MATRIXx Bookshelf**.

For descriptions of individual functions and commands, refer to the *MATRIXx Help*, available by entering help in the Xmath command area. This help is also available by selecting **Help»MATRIXx Help**.

Conventions

The following conventions appear in this manual:

The » symbol leads you through nested menu items and dialog box options

to a final action. The sequence **File»Page Setup»Options** directs you to pull down the **File** menu, select the **Page Setup** item, and select **Options**

from the last dialog box.

This icon denotes a note, which alerts you to important information.

bold Bold text denotes items that you must select or click in the software, such

as menu items and dialog box options. Bold text also denotes parameter

names.

italic Italic text denotes variables, emphasis, a cross-reference, or an introduction

to a key concept. Italic text also denotes text that is a placeholder for a word

or value that you must supply.

monospace Text in this font denotes text or characters that you should enter from the

keyboard, sections of code, programming examples, and syntax examples. This font is also used for the proper names of disk drives, paths, directories, programs, subprograms, subroutines, device names, functions, operations,

variables, filenames, and extensions.

monospace bold

Bold text in this font denotes the messages and responses that the computer automatically prints to the screen. This font also emphasizes lines of code that are different from the other examples.

monospace italic

Italic text in this font denotes text that is a placeholder for a word or value that you must supply.

Platform

Text in this font denotes a specific platform and indicates that the text following it applies only to that platform.

Related Documentation

You might find the following resources helpful as you use this manual. Access these resources by selecting **Help»MATRIXx Bookshelf**.

- MATRIXx Getting Started Guide
- Xmath Interactive Control Design Module
- Xmath Interactive System Identification Module, Part 1
- Xmath Interactive System Identification Module, Part 2
- Xmath Optimization Module User Guide
- Xmath X\mu Manual

Introduction

Xmath is a mathematical analysis, visualization, and scripting package that is one of the five main products of the MATRIXx product family. Complementing SystemBuild, another member of the MATRIXx product family, Xmath serves not only as an analytical tool, but also as a working environment and visualization tool for simulation data. Xmath and SystemBuild run concurrently, which allows you to simultaneously edit SystemBuild models, perform Xmath analysis or SystemBuild simulations, and display 2D and 3D graphics in presentation quality.

MathScript, the Xmath programming language, provides unique object-oriented capabilities that facilitate design analysis. Xmath also offers an interactive debugger, a programmable graphical user interface (GUI) layer, and an extensive library of mathematical, system modeling, and analysis functions.

Chapter 3 of this document contains information about getting started with Xmath.

This chapter begins with an outline of the *Xmath User Guide*, and some use notes. It continues with topics for helping you to get started in Xmath. These basic tasks are divided into the following topics:

- Environment Variables
- Opening and Closing Xmath
- Licensing
- Xmath Commands Window
- Getting Help

To complete the exercises in this chapter, Xmath must be properly installed according to the *System Administrator Guide* for your operating system and platform.

Commonly Used Nomenclature

This manual uses the following general nomenclature:

- Matrix variables are generally denoted with capital letters; vectors are represented in lowercase.
- G(s) is used to denote a transfer function of a system where s is the Laplace variable. G(q) is used when both continuous and discrete systems are allowed.
- H(s) is used to denote the frequency response, over some range of frequencies of a system where s is the Laplace variable. H(q) is used to indicate that the system can be continuous or discrete.
- A single apostrophe following a matrix variable, for example, x',
 denotes the transpose of that variable. An asterisk following a matrix
 variable (for example, A*) indicates the complex conjugate, or
 Hermitian, transpose of that variable.

MATRIXx Help

Xmath function reference information is available in the *MATRIXx Help*. Each topic explains the function inputs, outputs, and keywords in detail.

Environment Variables

This section defines several important environment variables.



Note The following conventions are used in this manual when referring to environment variables:

- When an environment variable appears in a pathname with its appropriate system dependent environment variable designator (\$NAME for UNIX and \$NAME for Windows), then you can use the environment variable as shown.
- When NAME appears without the environment variable designator, then you must substitute the pathname (value of the variable) in the command.

Xmath defines the MTXHOME and XMATH environment variables. It also recognizes the other environment variables discussed below. You can define them in your (UNIX).cshrc file or in your (Windows) autoexec.bat file. Alternatively, you can define them in each session in a Terminal or Command Prompt window.

MTXHOME

MTXHOME is an environment variable representing the installation directory for MATRIXx. This variable is used in pathnames.

XMATH

XMATH is an environment variable representing the directory in which Xmath is installed. XMATH is used in pathnames.

XMATH_STARTUP

XMATH_STARTUP is an environment variable you can use to specify a directory in which the startup MathScript file (startup.ms) is located. When you launch Xmath, the startup MathScript file (startup.ms) in the specified directory is executed.

XMATH_PRINT

XMATH_PRINT is an environment variable that lets you set up a default printer. When you run Xmath and use the HARDCOPY command, Xmath uses the value of XMATH_PRINT to send the graphics to the printer.

To define XMATH_PRINT for a SunOS system using the print command lpr and a printer named hp0, define XMATH_PRINT:

```
setenv XMATH_PRINT "lpr -Php0"
```

If you are on an SGI or HP system, set XMATH_PRINT with an entry similar to the following:

```
setenv XMATH_PRINT "lp -dhp0 -c"
```

If you are on a Windows operating system, set XMATH_PRINT with an entry similar to the following:

```
set XMATH_PRINT=MTXHOME\xmath\bin\xmprint your_printer
```

where your_printer is the name of your selected printer.

You can place this command in the autoexec.bat file in the root directory of your C drive.



Note If you specify the XMATH_PRINT environment variable, you do not need to set the PRINTER environment variable. (Xmath ignores it.)

PRINTER

PRINTER is an environment variable that lets you specify a default printer (if XMATH_PRINT) is not defined.

For example, to define PRINTER on a SunOS system, for a printer named hp0, define the PRINTER environment variable in your .cshrc file with the following:

setenv PRINTER "hp0"

The next time you run Xmath and use the HARDCOPY command, Xmath will use the value of PRINTER to send the graphics to the printer.



Note National Instruments recommends the XMATH_PRINT environment variable because it allows for platform-specific parameters. PRINTER may fail to work on some systems.

Opening and Closing Xmath

This section provides information about opening and closing Xmath from within MATRIXx.

Starting Xmath

After you launch MATRIXx, you can display an **Xmath Commands** window in two contexts: within a project and outside the project. To display the Xmath window associated with an open project, right-click that project in the **Solution Explorer** view and select **Show Xmath**. To display a stand-alone Xmath window that is not associated with any project, select **Tools»Xmath»Open Main Xmath Window**.

Interrupting or Terminating Xmath

To interrupt interactive execution of an Xmath function or command, press (UNIX) <Ctrl-C> or (Windows) <Ctrl-Break> from any Xmath window.



Note Intrinsic commands (for example, save or load; refer to the *Using Predefined Functions and Commands* section of Chapter 3, *MathScript Basics*) are noninterruptible. The same is true for window, dialog, or plot creation.

On UNIX systems, if either the windowing version or the tty version is not responding, terminate your Xmath session by pressing <Ctrl-\>. This key sequence terminates Xmath properly in unusual circumstances.

Exiting Xmath

From a windowing version of Xmath, use any one of the following methods to exit Xmath:

- Type quit in the **Xmath Commands** window command area (the only part of the **Xmath Commands** window that accepts input).
- Choose File»Quit from the menu bar.
- With the cursor over the **Xmath Commands** window, press <Ctrl-q>.
- On UNIX systems, select Close from the X Windows Default Menu in the Xmath Commands window.
- On Windows systems, click the X (Close) button in the upper right corner of the Xmath Commands window, or click the Xmath icon in the upper left corner of the Xmath Commands window and select Close from the system menu, or use its keyboard equivalent of <Alt-F4>.

In all cases above, you are given the opportunity to save before exiting. Selecting **Save** here saves all current variables to a file named save.xmd in the current working directory. The session terminates after the file is saved.

If you are using the tty version, type quit. You may see the following warning:

Modified variables that have not been saved exist; quit anyway? (y/n)

Type y (yes) or n (no) as desired. For more information, refer to the *Saving* and *Loading Data* section of Chapter 3, *MathScript Basics*.

Stopping and Restarting Xmath

You can quit Xmath at any time. To resume at the same point, type save in the **Xmath Commands** window command area before quitting, or select **Save** in the Quit dialog box. This saves all existing data to a file called save.xmd in the current working directory.



Note The Save command overwrites any previous save. xmd file in the current working directory.

To resume a session:

- 1. Restart Xmath from the same directory
- Type load in the command area.
 The default save file save.xmd is loaded.

Licensing

When Xmath starts, it checks out the Xmath Core license. The license for each module is checked out when that module is started; for example, the Control Design Module is checked out when that module is started. If your site has a floating license or counted node-locked license, you may be unable to check out a particular module.

If a Core license is available, the **Xmath Commands** window appears after a few seconds (refer to Figure 1-1 for the UNIX version).

To get license information for your current version:

• In the **Xmath Commands** window command area, type:

licenseinfo

A list of modules for which your site is licensed and their expiration dates appear in the log area.

For additional information about your Xmath license, refer to the *System Administrator Guide* for your operating system.

Xmath Commands Window

The **Xmath Commands** window appears when you start Xmath. This is your primary interface to Xmath. Figure 1-1 shows the **Xmath Commands** window.

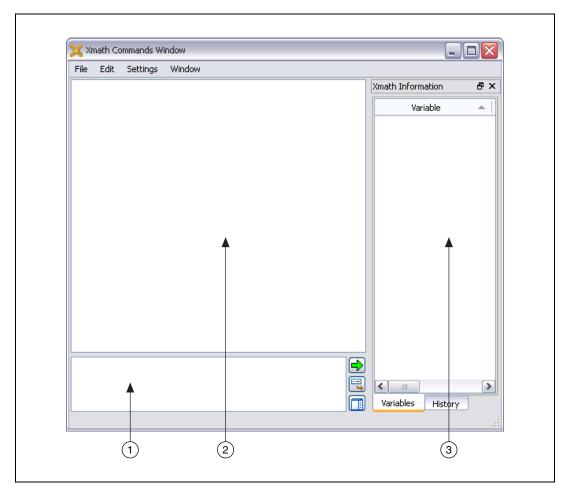


Figure 1-1. The Xmath Commands Window

The command area (1) is where you enter functions and commands. Xmath displays the results of these commands in the log area (2). You use the **Xmath Information** view (3) to display partitions, variables, and a history of commands you entered during the current session. The following sections describe the command area, log area, and **Xmath Information** view.

Command Area



To use the command area, enter a valid command and press <Enter>. You can also click the **Evaluate** button, shown at left. This button is located to the right of the command area.

The following sections provide more information about using the command area.

Entering Multiple Lines of Information

The command area has two command modes: single-line and multiline. Use multiline mode to execute multiple commands at once. In single-line mode, pressing <Enter> executes the command you entered. In multiline mode, pressing <Enter> creates a new line in the command area.



Note In either mode, pressing <Ctrl-Enter> executes the command you entered.



To enter multiline mode, click the **Multiline Mode** button, shown at left. This button is to the right of the command area. You can also select **Edit»Toggle Multiline Mode** or press <Shift-Enter>.

Recalling Previous Commands

Xmath has a command area recall feature based on keystrokes, as shown in Table 1-1.

Table 1-1. Command Area Recall Keystrokes

Keystrokes	Action
<ctrl-↑></ctrl-↑>	Moving backwards, print recorded inputs in the command area.
<ctrl-↓></ctrl-↓>	Moving forward, print recorded inputs in the command area.
<@@>	Execute the last command.
<@@:p>	Print the last input in the command area.
<@str>	Execute the last input starting with str.
<@str:p>	Print the last input starting with str.
<@n>	Execute the <i>n</i> th input.
<@:l>	List all inputs in the log area.

Table 1-1. Command Area Recall Keystrokes (Continued)

Keystrokes	Action
<@str>:1	List all inputs starting with str in the log area.
<@>	List the last 10 inputs. If @ is issued again (without an intervening Xmath command) 10 inputs back from that point will be listed.

The following rules apply to the command area.

- Only syntactically correct inputs are recorded.
- @ commands are not recorded as inputs.
- Multiline inputs are recorded and recalled as one line.
- One hundred inputs are recorded; the oldest are automatically discarded to make room for new inputs.
- An @ command can only be entered in the Xmath Commands window command area on a line by itself. It cannot be issued from a MathScript batch file.

Log Area

The log area keeps a record of your interactions with Xmath. Both inputs and outputs are displayed in the log area. Certain actions in the user interface also cause Xmath to write to this area.

To control the number of lines written to the log area, type

set logarea N

where *N* is the number of lines; *N* is also limited by the buffer size, which is machine dependent. Using this command truncates the current contents to that number of lines.

To set the lines to the maximum, type

set logarea max

This limit is dependent upon hardware and the operating system resources available.

To turn writing to the log area off, type

set logarea off

Current contents of the log area are discarded. While logging is turned off, the data is not being buffered, and it is lost. When you are running batch and simulation jobs in SystemBuild, setting logging off speeds up their execution slightly.

To turn writing to the log area on, type

set logarea on

All subsequent log data is displayed up to the limit; the limit is what you set previously or the default (maximum).

The command

show logarea

displays both the number of lines (or ALL) and the state of logging—On or Off.

To erase the log area, select **Edit»Clear Log Area**, or type erase {logarea}

This action is not reversible, although you still have access to command recall to retrieve previous entries.

If a file is executed, the file contents are not written to the log area unless set echo on is specified (the default is off).

Xmath Information View



The **Xmath Information** view, located on the right side of the **Xmath Commands** window, displays all partitions and variable in the current Xmath session. To toggle the **Xmath Information** view on and off, click the Information button, shown at left. This button is located to the right of the command area.

For information about this view, refer to the *Xmath Information View* section of Chapter 3, *MathScript Basics*.

Getting Help

To get help for a specific command or function, enter help <code>command_name</code> in the Xmath command area, where <code>command_name</code> is the name of the command or function for which you want to access help. This action launches the <code>MATRIXx Help</code> in a separate window. You can also access the <code>MATRIXx Help</code> by selecting <code>Help>MATRIXx Help</code>.

For information about using the the *MATRIXx Help*, enter help using in the command area.

Tutorial: Creating and Manipulating Xmath Data

This tutorial introduces basic Xmath features. It highlights some of the ways Xmath is different from other tools. After getting you started, this chapter provides the following major topics; the times shown are estimates of how long it takes to complete each section.

Торіс	Time to Complete
Basic Data-Handling	15 minutes
Functions and Commands	10 minutes
Graphics	30 minutes
Objects	60 minutes
MathScript	15 minutes



Note Before starting this tutorial, ensure you are familiar with the concepts presented in Chapter 1, *Introduction*.

To use this tutorial, you must have a properly installed version of Xmath. You should also be familiar with the following:

- Your operating system
- A text editor
- **(UNIX)** Your window manager

We assume that workstation users have X Windows and a window manager running before starting this tutorial. The Jump Start is very basic and you will be able to complete it even if you are unfamiliar with the workstation environment.

This tutorial contains many cross-references to other parts of the document. It is not necessary to consult the cross references to complete this tutorial. After completing the tutorial, you may want to look into some of the advanced features in Chapters 6 through 9.

Starting Xmath for the Tutorial

In this section, we want you to create a directory called jumpstart, make that directory your working directory, and start Xmath. (UNIX) From a Terminal window (Windows) or the Command Prompt window, enter the following commands:

```
% mkdir jumpstart
% cd jumpstart
```

Then start Xmath using one of the methods provided in the *Opening and Closing Xmath* section of Chapter 1, *Introduction*.

You may stop or interrupt the tutorial at any point. Remember to save your work before you quit and to reload it upon startup again. Refer to the *Stopping and Restarting Xmath* section of Chapter 1, *Introduction*.

Basic Data-Handling

This portion of the tutorial discusses creating and organizing variables, as well as saving, deleting, and retrieving them.

Creating Variables

A variable is named information. To create a variable, you must type into the Xmath command area. You can assign a name to data:

```
a=3.14
a (a scalar) = 3.14
```

b=a+expm([1,2;3,4])

and assign the results of expressions or the output of an Xmath function:

```
b (a square matrix) =

55.109 77.8766

115.245 167.214
```

Pressing <Return> or <Enter> executes everything in the command area. By default, your input is displayed in the log area, followed by the output. To suppress output display, terminate inputs with a semicolon (refer to Table 3-1 for a way to change display behavior).

b;

If you input more than one statement on a line, a semicolon or question mark, which forces output, must be used as a separator. Type:

```
c=b^a; d=b/a? c=d-a;
d (a square matrix)=
    17.5506 24.8015
    36.7022 53.2528
```

The only output displayed is the value of d, but c exists.

When entering multiple lines of text in the command area, use the <Line Feed> key or <Shift-Return> to start a new line, and press <Return> when you are finished. If your keyboard does not have a Line Feed key select **Edit>Insert New Line** from the **Xmath Commands** window, or use the key combination appropriate to your platform. Refer to the *Entering Multiple Lines of Information* section of Chapter 1, *Introduction*.

In the following example, press <Line Feed> after inputting the numbers 3 and 6, and press <Return> after the right square bracket:

```
e=[1,2,3
    4,5,6
    ,8,9]
e (a square matrix) =
    1    2    3
    4    5    6
    7    8    9
```

If you do not assign a variable name to a valid statement, Xmath assigns the value to the temporary variable ans. The following expression uses the permanent variable jay to create a matrix of complex numbers and assign the matrix to ans:

ans will be changed the next time a statement output is not assigned to a variable.

To comment an existing variable use the comment command:

```
comment b "combined an expression and a function"
```

You must enclose the comment string, like all other strings in Xmath, in double quotes:

To retrieve the comment, use the commentof () function:

```
commentof(b)
```

```
ans (a string) = combined an expression and a function
```

Xmath also displays the comment when you view the variable in the **Xmath Information** view, which is discussed in the *Viewing Data* section.

If you make an error, Xmath attempts to highlight the incorrect input. For example, type:

```
max(E)
```

What you typed remains in the command area with the E in reverse video. The message area displays E undefined in this scope.

Go to the command area and replace the capital ${\tt E}$ with a lowercase ${\tt e}$:

```
max(e)
```

```
ans (a scalar) = 9
```

The max () function now finds the largest value in the variable e.

Using Command Recall

To print previous inputs to the command area, hold down the Control key and press the up arrow <Ctrl-|>. For more on command area recall, refer to the *Recalling Previous Commands* section of Chapter 1, *Introduction*.

Sending Multiple Lines of Data at Once

Use the **Multiline Mode** button to toggle multiline mode on and off. For information about this button and multiline mode, refer to the *Entering Multiple Lines of Information* section of Chapter 1, *Introduction*.

Variables and Partitions

Xmath variable names are case-sensitive (for example, MyVar, myvar, and MYVAR are different variables).

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A *partition* is a named non-hierarchical directory that contains variables. Partition names are also case-sensitive.

Xmath always starts in the default partition main. You can verify this by typing show partition in the command area. The full name of a variable includes its partition, so the variable a, found in partition main, is named main.a. However, you do not need to supply a prefix when handling variables in the current partition.

Use the command new partition to create partitions. Other commands used for partition handling are set, show, and delete.

1. Create new partitions:

```
new partition data1 new partition data2
```

2. Using variables in the current partition (the default partition main), create new variables for the partition data1:

```
data1.a=a\b;
data1.b=lyapunov(b,c);
```

3. Go to the new partition data1 and display a list of the variables in that partition to the log area:

set partition data1 who

List variables in the current partition

data1:

a -- 2x2 b -- 2x2

4. Attach a comment to a partition in the same way you comment variables, except that you must put a period after the partition name to distinguish it from a variable name:

```
comment data1. "vault"
commentof(data1.)
ans (a string) = vault
```

5. Use the same variable name in other partitions:

data2:

a -- 4x4

6. Look at all the partitions and all existing variables:

show partitions who *.*

Shows all partitions

Show all variables in all partitions

7. Delete a partition (data1).

To delete a partition, you must first empty it:

delete data1.*

Delete variables in data1.

To delete a partition you are in, change to another partition first:

set partition main delete data1.

Delete the partition data1

Viewing Data

The **Xmath Information** view, located on the right side of the **Xmath Commands** window, displays all partitions and variable in the current Xmath session.



Note If you do not see this view, click the **Information** button, which is located to the right of the command area.

Complete the following steps to use this view.

- 1. Right-click an empty area in this view and select **Update**. MATRIXx refreshes this view to display all current partitions and variables.
- 2. Resize the view by dragging the left border of the view. Notice the different columns that appear. Click a column to sort the list by that column.

For more information about the **Xmath Information** view, refer to the *Xmath Information View* section of Chapter 3, *MathScript Basics*.

Saving Data

The commands and functions in Table 2-1 save data to files.

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Table 2-1. Save Commands and Functions

SAVE	Save variables in Xmath or MATRIXx format to a binary or ASCII file. This is the standard way of saving data.
PRINT	Print the values of a list of variables to an ASCII file.
fprintf()	Convert numeric values to a string representation, and then write the string(s) to an ASCII file.

You can perform save operations from the command area and from the File menu of most windows.

Save Command

The easiest save method is to type SAVE in the command area. When you do, Xmath saves *all* variables to a file named save.xmd in the current working directory. By default, SAVE produces a binary file with the variables saved in Xmath format.

You can specify a list of variables, a filename, or a format. For example, save main.* file="main" {ascii}

saves all variables in the partition main to an ASCII file named main.xmd in the current partition. Note that SAVE adds the .xmd extension for you.

Complete the following steps to save all variables to a binary data file via the **Xmath Information** view.

- Right-click in the Xmath Information view and select Save All.
 The Save Variables dialog comes into view.
- 2. Select a directory and then specify a filename in the **File name** field of the dialog box.
- 3. Click Save. MATRIXx saves the data.

Print Command

The print command writes a variable in a text format you can read.

To print a specific variable to a text file:

```
set seed =0;
x=(rand(2,2))*sin([5,1;4,2]);
print x file="x.dat"
```

The function oscmd() lets you use an operating system command to display the contents of the file you created to the **Xmath Commands** window log area:

```
oscmd("cat x.dat")  # UNIX
oscmd("type x.dat")  # Windows
main.x =
-0.77482  0.865292
-0.250204  0.300552
ans (a scalar) = 0
```

Loading Data

Load Command

If you type load (with no file specified) in the command area, Xmath looks for the default file save.xmd in the working directory and loads it if it exists.

To test this, go to the command area and input the sequence below; these instructions assume you are in partition main.

```
a=1; b=2; c=3; d=4;
                       # Create variables a, b, c, and d
                       # Save all variables to save.xmd
save
who *.*
                       # Verify that the variables are in main
delete *.*
                       # Delete variables in main
who *.*
                       # Verify that the variables have been deleted
You can then retrieve selected variables or all saved data:
load c d "save"
                       # Load variables c and d from save.xmd
                    or
                       # Load all variables in save.xmd
load
who *.*
                       # Verify that the variables have been loaded
```

Xmath supplies the default filename extension xmd when you do not supply one. Another way to load saved data is to go to the commands or right-click in the **Xmath Information** view and select **Load**.

Read Command

The READ command copies the contents of a file into an Xmath matrix. This function is particularly useful for loading externally generated data into Xmath. The data can be character, integer, or floating-point types, as well as ASCII.

For information about this command, enter help read in the command area. Notice that the arguments are a filename, the rows and columns of the data, the type (or format), and the number of bytes in the file you want to skip before reading.

Read in the file you made with the print command (refer to the *Print Command* section).

- Specify the input filename (x.dat), give the row and column dimensions of the data, and specify the input file format (ascii).
- Specify an offset of 1; this instructs Xmath to skip the first line (main.x =).

We do not have to worry about the last line in the file, (ans (a scalar) = 0), because read stops after the two rows and columns you specified have been read.

```
xx=read("x.dat",2,2,"ascii",1)
xx (a square matrix) =
-0.77482     0.865292
-0.250204     0.300552
```

Cleanup

This concludes the section on basic data-handling. You can delete the variables and partitions you created, as you do not need them later. Do not, however, delete the partition main; delete only its contents.

Functions and Commands

If you have been working through the tutorial, you have already used several common commands and functions. In addition to discussing functions and commands, this section includes references to more detailed passages.

Function Syntax

Functions operate on a list of input values and return output values. Input arguments are passed by value (a local copy is nested inside the function scope).

Functions are called in the following form:

```
[out1,out2,...,outn] = funName(in1,in2,...inm,{options,keywords})
```

For examples of this syntax, refer to the MATRIXx Help Functions topic.

- Input and output arguments are separated by commas.
- Keywords are enclosed in braces and separated by commas.
- When a string is required, it must be enclosed in double quotes; for example, line_color="blue".
- If a function has multiple outputs, by default only the first output is returned. You must use the brackets if you wish to acquire more than one output.

The following example shows two possible syntaxes for residue. Input the following data to see the default output behavior:

```
sys=(makepoly([2:4:6])/makepoly([3,5]));
Rp=Residue(sys,[5,10,inf],{tol=.5})
```

To see both outputs, use square brackets and assign the outputs to variables:

```
[Rp,C]=Residue(sys,[5,10,inf],{tol=.5})
```

For additional information, refer to the *Using Predefined Functions and Commands* section of Chapter 3, *MathScript Basics*. Xmath function syntax is detailed for each function in the *MATRIXx Help*. For a detailed description of how to use MathScript to define your own functions, refer to Chapter 6, *MathScript Programming*.

Command Syntax

Like functions, commands operate on inputs. However, command inputs are passed by *reference* and can be changed within the command.

In the MathScript language, command syntax is as follows:

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```
command arg1, arg2, ...argN, {keywords}
```

For examples of this syntax, enter help commands in the command area.

If you have been working through the tutorial, you might realize that intrinsic commands have a special syntax. Syntaxes we have used are:

```
new partition part_name
set partition part_name
delete part_name
save "filename" var_1 var_2 var_n
load "filename" var_1 var_2 var_n
```

The most obvious difference is that these commands require spaces rather than commas as separators. The whatis command reveals a fundamental difference between these commands and other MathScript commands (MSCs):

```
whatis save
```

```
save: intrinsic command
```

Xmath includes many *intrinsic* commands and functions. These commands and functions are part of the Xmath executable.

Refer to the *MATRIXx Help* for descriptions of Xmath commands. For a detailed description of how to use MathScript to define your own commands, refer to Chapter 6, *MathScript Programming*.

Graphics

The Xmath plot () function provides two and three-dimensional graphics that you can manipulate interactively while they are displayed in the **Xmath Graphics** window. This section introduces plot () and several types of plots it can create.

Two additional general purpose plotting functions, uiPlot() and plot2d(), complement the capabilities of plot(). A brief description of these functions can be found in the *Xmath Plotting Functions and Commands* section of Chapter 4, *Graphics*.

Plot()

The plot() function creates a graph object that Xmath displays in the **Xmath Graphics** window. The most complete syntax for plot() is:

```
graphObj = plot(x,y,z,colorindex,{keywords})
```

2D graphs are produced with y, or x, y as arguments, while 3D graphs require x, y, and z. For other plot () syntaxes refer to the *Using the plot*() *Function* section of Chapter 4, *Graphics*.

plot () behaves like other Xmath functions in the following ways. Functions are discussed in *Functions and Commands* section.

- If no output variable name is assigned, Xmath assigns the output (graph object) to the temporary variable ans.
- Xmath displays a graph object in the Xmath Graphics window when
 it is created unless you use a semicolon as a terminator. If you create
 a graph object within a MathScript, only a ? terminator causes it to
 display.
- You can display a graph object with the ? terminator anytime after creation.
- You can save and load a graph object.

Keywords

Keywords define a graph's labeling, layout, and appearance. This tutorial introduces basic keyword use. For a complete keyword listing, refer to Table 4-5 or enter help plot in the Xmath command area. You can create or change many of the features for which keywords are used interactively using the **Xmath Graphics** window menus or the **Xmath Palette**.

Graph Objects

plot() is the only function that outputs a graph object. Xmath creates a graph object whenever it displays the output of the plot() function in the **Xmath Graphics** window. If you specify an output variable name, Xmath writes the contents of the **Xmath Graphics** window to the variable; otherwise, Xmath writes the contents to the default variable ans. If you suppress plot with a semicolon, Xmath writes nothing to the **Xmath Graphics** window. (Other functions may display plots in the **Xmath Graphics** window, for example, windowing functions such as firwind(), but their actual function output is numeric. Only plot() allows you to name the contents of the **Xmath Graphics** window.)

You can copy, save, display, and reload a graph object like any other variable. Additionally, it can be altered or used in a new graph if you use the keywords keep or copy. We explore the implications of the graph object later in the tutorial.

Working in the Xmath Graphics Window

When you use the plot function without suppressing its output, Xmath opens the **Xmath Graphics** window. The following mouse actions are defined for this window:

• To select an object, click it.

An object can be a text string, label, grid, data, and so forth.

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 Double click an object to select the object and bring up the Xmath Palette.

The palette title area (center top) gives information on the object you have selected. For example, the title **Xmath Palette** (tics:axis line) indicates that you have selected an axis line.

Different menu items and palette locations on the **Xmath Palette** are enabled based on your selection. For example, if a label is selected, the Font and Point menus are enabled, and the text color can be changed from the palette.

 If you have difficulty selecting an object (for example, you attempt to select a tic mark, but you keep getting the axis), then hold down the <Shift> key while clicking.

Xmath cycles through selecting the objects closest to the cursor. A glance at the palette title area reveals the selected object.

Click and drag to move objects.

Objects that you can move independently are the legend, date, time, free text, and graphics that you create with the graph tools in the **Xmath Graphics** window icon bar. You cannot move a graph and its associated plot data, grids, labels, axis information, and so forth interactively, but you can move the entire graph with the plot () keyword position.

Using Plot and Graph Objects

You can plot objects in two- or three-dimensional plots.

Using 2D Plotting Capabilities

Before continuing, generate a few waveforms:

Here graph_b1 is a graphical object with b1 plotted versus a time sequence:

```
t=0:0.01:2.24;
graph_b1=plot(t, b1,{title="xy plot",x_lab="time(sec)"})?
```

Plot b2 with specific labels and titles:

```
graph_b2=plot(b2, {y_lab="volts",x_lab="sample",
title = "sample display",legend = "noisy wave"})?
```

You can plot the original noise-free waveform b1 over the existing plot by copying the graph object graph_b1 into the current graph. In the command area type:

```
both_b=plot(b1,{copy=graph_b2,line_style=3,
line_width=2,legend = "original wave",!grid})?
```

Figure 2-1 shows the result. b1 is plotted as a thicker dotted line added to graph_b2, a new entry is added to the legend box, the grid is suppressed by the ! negator, and the image is given the name both_b.

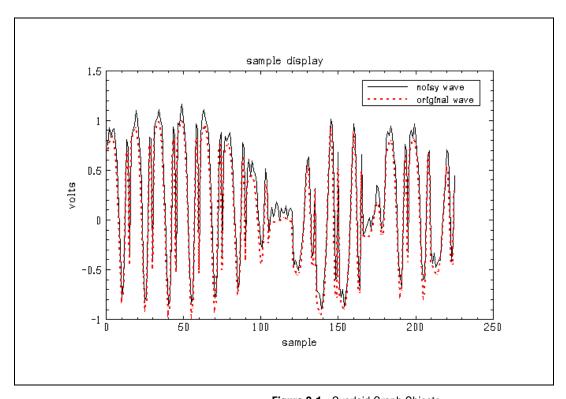


Figure 2-1. Overlaid Graph Objects

To see the first plot, type:

graph_b1?

You do not need to execute the previous plot call to see the graph. graph_b1 is unchanged because the keyword copy was used and the current contents of the window were given a new name (both_b). If you are adding to a plot and it is not important to retrieve your previous efforts, use keep instead of copy, keep is much faster than copy.

When you make interactive changes to a graph object displayed in the **Xmath Graphics** window, the changes immediately become part of the current graph object. To preserve graph_b1 as it is, rename the graph before making changes in one of following ways:

- From the Xmath Graphics window menu bar select File»Bind to variable and save the contents of the Xmath Graphics window to the name g1.
- From the **Xmath Commands** window command line, type:

```
g1=plot()
```

Calling plot () with no arguments binds the contents of the **Xmath Graphics** window to the output variable name.

To illustrate that changes immediately become a part of the current graph object, go to the **Options** menu and turn on the timestamp and datestamp; then move them to new locations. Double-click a text string, and then change the font and point size using the **Xmath Palette**. Double-click a curve either in the data or in the legend, and then go to the **Xmath Palette** and change the marker and line styles.

Display the object graph_b1 and then the object g1:

```
graph_b1?
g1?
```

Using 3D Plotting Capabilities

To demonstrate some of the 3D plotting capabilities, create x, y, and z:

```
x= [-2*pi:.65:2*pi]';
y= logspace(1,2*pi,20);
z= sin(x)./x*(sin(y)./y);
plot(x,-y,z,{title="A 3D Plot",xlab="the xlabel",ylab="the ylabel",zlab="the zlabel",!grid})?
```

Figure 2-2 shows these results.

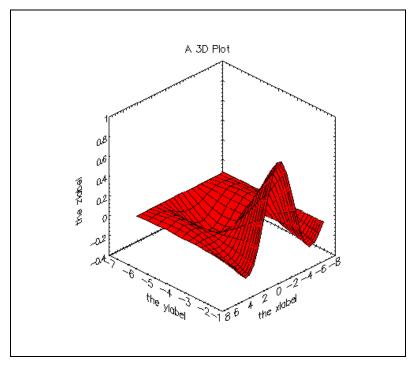


Figure 2-2. 3D Plot with Labels and Title

You can rotate 3D plots with the rotation tools on the far right of the menu bar in the **Xmath Graphics** window. The first tool allows you to rotate in all directions (unconstrained); the remaining tools rotate about the three principal axes. Select a rotation tool in the icon bar, and then move to the plotting area. When the tool is active, just the grids are shown; click and drag the cursor until the grid is in the position you want to see, and then release the mouse. Xmath redraws your graph in the new position.

Complete the following steps to return to the initial plot position.

- Select View»Reset.
- 2. To turn off the rotation tool click the arrow (selection tool) on the far left of the menu bar.

Using Different Plot Types

This section discusses the use of different kinds of plots: strip, polar, bar, and contour.

Strip Plots

The strip keyword aligns two or more waveforms in stacked graphs sharing a common x-axis. Optionally, you can specify the number of curves you want in each graph. (Strip plots, like all other multiple graph plots, cannot be rotated or zoomed.) The example below plots four variables; strip=2 specifies that each graph should contain two curves (refer to Figure 2-3). We specify an optional line_style vector with legend to distinguish the original values of b from the absolute values.

```
set seed = 0  # Set random seed
a = sin(logspace(1,10,10));
b1 = kronecker(a,a);
b2 = b1 + random(1,100);
t=.1:0.05:5.05;
plot (t, [b1;b2;abs(b1);abs(b2)]',{strip=2,
    title ="strip chart",line_style=[2,1],
    legend=["volts","abs"],xmax=5.1,
    ylab=["b1 volts","b2 volts"],xlab="time"})?
```

Xmath creates a single legend, and the two plots share the title and xlab. Strip chart data is linked; to illustrate this, select a curve in one of the plots; the corresponding curve in the other plot is also highlighted.

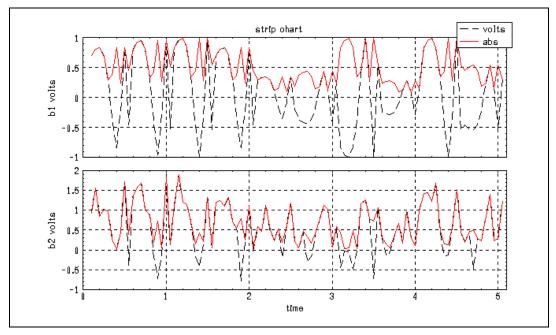


Figure 2-3. Strip Plot with Two Curves in Each Strip

Polar Plots

Xmath can display data in polar plots (refer to Figure 2-4). For example,

```
r = abs(sin(0:.1:35.9));
theta = 0:1:359;
plot(theta,r,{polar, fg_color="gray2",
line_color="royal purple", line_width=2})?
```

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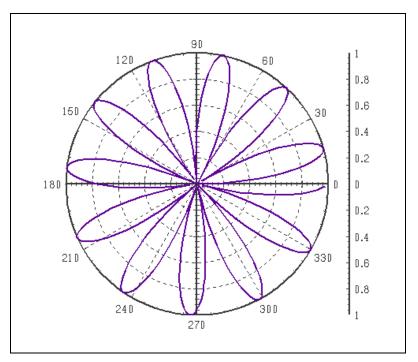


Figure 2-4. Polar Plot

Bar Plots

Xmath also has bar graph capabilities.

Bar plots can be overlaid using the keep keyword. If a variable name is not specified, keep adds what you specify to the current contents of the **Xmath Graphics** window. The results of the example below appear in Figure 2-5.

```
plot(10:-1:1, {bar})?
plot([8,4.5,2,6,4.5,5,1.5,2,.5,.7],
{keep,bar,!xgrid,legend})?
```

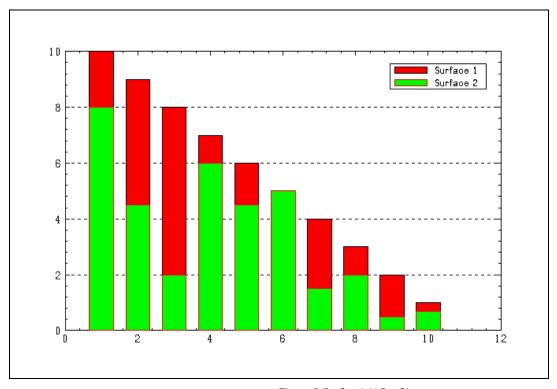


Figure 2-5. Overlaid Bar Plots

Contour Plots

```
x= [-2*pi:.6:7]'; y=x;
z=1.2 + sin(x)./x*(sin(y))';
```

The first graph is a 3D surface plot, with grids suppressed:

```
plot (x,y,z,{!grid})?
```

With the keep keyword, you can overlay a 2D contour plot of the same surface (refer to Figure 2-6):

```
plot(x,y,z, {keep,contour2d,!face,contour_interval =
0.5})?
```

Alternatively, you can display a 3D contour plot:

```
plot (x,y,z, {contour3d})?
```

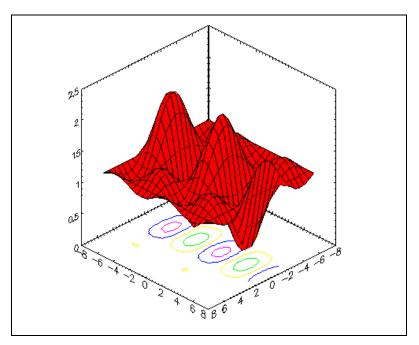


Figure 2-6. 3D Plot with 2D Contour

Displaying Multiple Plots at Once

The rows and columns keywords allow you to display up to 25 different 2D and 3D graphs at once. The values you assign to rows and columns determine how the screen is subdivided. Plots are then positioned on the screen with a combination of row and column numbers or a graph_number. The rows and columns keywords are *initiators*. This means they remain in effect until a plot call that does not contain a row or column keyword is issued; at this point the default values rows=1, columns=1 are reset.

The following example places four plots on the screen in two rows and two columns. Note that you do not need to specify row=1 or column=1; these are default values. The result is shown in Figure 2-7.

```
set seed 0
h=histogram(rand(1:100), {nbins=7,noplot});
plot (b1, {rows=2,columns=2, line_color="blue"})?
plot (theta,r, {polar,row=2, fg_color="gray2",
line_color="royal purple", line_width=2})?
plot (h, {bar,column=2,!xlab})?
```

plot (x,y,z, {contour3d, xinc=4, yinc=4,!grid, graph_number=4})?

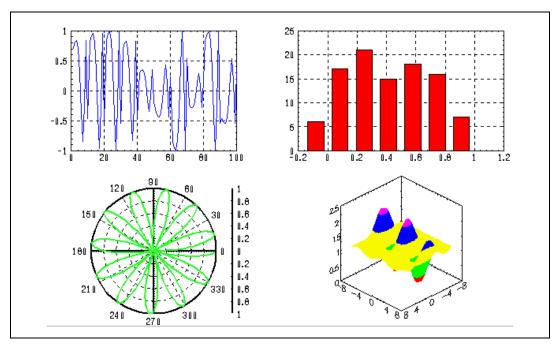


Figure 2-7. Different Plot Types Positioned with row and column Keywords

Animating Plots

Given a series of plots, the animate keyword draws each plot as fast as possible so the progression looks like movement. For the following example, create a vector:

```
an1=sin(logspace(1,10,25));
an2=an1(25:-1:1);
an3=kronecker(an1,an2);
```

We will be looking at an3 using 100 points at a time. First, we plot the entire vector using animate and a fixed axis (axisfix). By default, axes are adjusted to the current plot range, so, if animate is enabled, axes may change while plotting. In this call, axisfix holds the axes of the current plot (until they are changed), ensures that the plot background remains the same, and (since the whole vector is plotted) that the plot area is not too small for the plot.

```
plot(an3,{animate,axisfix,xmax=100})?
```

The animate keyword stays active until it is disabled explicitly.

Use a loop to plot portions of the data while animate is enabled:

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```
for i=1:7:524
    plot(an3(1,i:i+100))
endfor
```

To turn off animate type:

```
plot({!animate})
```

Alternatively, you can use plot ({reset}) to reset *all* plot defaults.

If you are curious about axisfix, repeat the above example without it, and watch the axes.

Finishing the Graphics Tutorial

The above examples show only a sampling of the options available for plot().

For more information on plot () graphics, first ensure that animate is switched off. Then run the graphics demo:

```
plot({!animate})
execute file = "$XMATH/demos/graphics"
```

Also refer to the *Interactive Xmath Graphics Window* section of Chapter 4, *Graphics*, and the *Plotting* topic of the *MATRIXx Help*. This topic is available by entering help plotting in the command area.

This ends the graphics portion of the tutorial. Before moving on, you should delete the variables you created in this section:

```
delete *.* # Delete all variables in all partitions
```

Objects

Unlike most numerical tools, which only deal with matrices, Xmath employs object-oriented programming principles. Refer to Figure 5-1 for a full description of the Xmath object hierarchy structure. For example, the Toeplitz matrix class is a special kind of square matrix class. It inherits all the properties of the square matrix class but automatically takes advantage of specific operations which can be performed more efficiently for Toeplitz matrices.

Benefits from Xmath's object-oriented structure include:

- Fewer variables to manage. A single variable can represent several very complex pieces of data. Therefore, you do not need as many variable names, which simplifies variable management.
- Fewer functions. For example, a single function handles continuous and discrete cases.
- Faster calculations. Many objects take advantage of optimized algorithms. This is especially true of all the specialized matrix objects. Xmath recognizes special data properties and automatically uses an optimal method if available.
- More intuitive syntax and ability to overload operators. Overloading means that a single operator can have different meanings when it interacts with different objects.
- More compact user code. Because objects have clearly defined properties, it is simpler for users to check and handle data in their programs.

This section briefly discusses the major Xmath objects. There are examples of how to create each one and, in some cases, examples of special techniques with operators or indexing. The examples create unique data for each object. Therefore, you may quit the tutorial between any of the object discussions and restart when convenient.

Strings

A string is a set of characters enclosed in double quotes. To display double quotes within a string you must provide two sets of quotes (""). You can convert numbers to strings with the string() function, while the char() function gives the ASCII character for a given integer between 0 and 255.

```
a = "The total score is ";
b = 301;
c = a + string(b)?
c (a string) = The total score is 301
```

You can create a matrix of strings using the familiar matrix-constructor syntax.

```
a = ["one", "two"; "three", "four"]
a (a square matrix of strings) =
```

```
one two
```

When entering strings in the **Xmath Commands** window command area, remember that a single string must be complete on a line. If for some reason you must break the string, create separate strings and append them with the + operator:

```
text="Xmath strings cannot be continued " +...
    "across lines, but separate strings can " +...
    "be appended with the + operator."

text (a string) = Xmath strings cannot be ...
```

Matrices and Vectors

This section demonstrates how to create and use matrix and vector objects. It also shows how Xmath's object-oriented structure improves the computational speed of matrix operations.

Creating Matrices and Vectors

You must enclose matrix specifications in square brackets; you separate elements in separate rows by commas and row elements, by semicolons or line feeds:

A vector is a single row or single column matrix. An apostrophe (') transposes a vector or a matrix.

2

Regular vectors are row vectors specified as three values in the form start:step:end.

```
time=0:0.01:10
```

```
time (a regularly spaced vector) = 0:0.01:10
```

The logspace() function creates logspaced vectors with points evenly spaced on a log scale. Like regular vectors, logspaced vectors are stored as three values.

```
log1=logspace(1,2,5)
```

```
log1 (a log-spaced vector) = 1 : 2 (5 points)
```

Transposing a vector or enclosing it in square brackets expands it:

log1'

```
ans (a column vector) =
```

```
1
```

1.18921

1.41421

1.68179

2

[time]

```
ans (a row vector) = 0 0.01 0.02 0.03 0.04...
```

To form a vector with descending values, use a negative step:

$$k2 = [2: -.25:1]$$

```
k2 (a row vector) = 2 1.75 1.5 1.25 1
```

To reverse a vector, use a negative step value:

```
k3=k2(length(k2):-1:1)
```

```
k3 (a row vector) = 1 1.25 1.5 1.75 2
```

Use vectors in expressions and to define new matrices:

```
g=[1:3;logspace(1,20,3)]
```

```
g (a rectangular matrix) =
```

```
1 2 3
1 4.47214 20
```

Matrix Index Operations

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Create the matrix testm:

To find any element in testm, give the matrix name followed by the row and column index in parentheses:

```
testm(2,3)
ans (a scalar) = 6
```

To find the second row in testm, use a colon (:) as a wildcard symbol in place of the column index to denote "second row, all columns":

```
testm(2,:)
ans (a row vector) = 4 5 6
```

To find any column in testm, use the wildcard symbol (:) in the rows position:

```
testm(:,1)
ans (a column vector) =

1
4
7
```

To find submatrices, use vector inputs:

```
testm(1:2,2:3)
ans (a square matrix) =
    2     3
    5     6
```

The function find() allows you to find indices for matrix elements that meet a certain criterion. find() returns each index in [row, column] format.

```
find(testm > 7)
```

```
ans (an index list) =

3  2
3  3
```

The output indicates that the elements found in the third row, second and third columns (3,2) and (3,3) are greater than 7.

You can incorporate find results as a special indexing scheme to perform an operation on only the elements meeting the criterion in find.

```
testm(find(testm > 7)) = 0
test_matrix (a square matrix) =
    1     2     3
    4     5     6
    7     0     0
```

Xmath changed the elements greater than 7 to zeros.

Using Matrix Functions

Matrix functions take advantage of the structure of matrix objects. The more specialized a matrix is (that is, the more properties it inherits), the greater the computational speed improvement. For example, consider computing the eigenvalues of a common matrix, a symmetric matrix, and a triangular matrix of the same size (100×100) .

The clock() function monitors elapsed CPU time. It returns the time in seconds since clock() was last called. Therefore, you should call it before and after the monitored process.

```
rmat = random(100,100);
clock({cpu});mm = eig(rmat); clock({cpu})?
```

Xmath automatically uses more efficient algorithms when the matrix fits a given structure. The above example tells how long it takes to find the eigenvalues of a general, random (100×100) matrix.

_

¹ clock() results depend on your machine's configuration.

In the following example, you can see how long it takes with a symmetric matrix of the same size. We use the transpose operator (') to ensure that the matrix is symmetric:

```
smat = rmat * rmat';
clock({cpu}); mm = eig(smat); clock({cpu})?
eig takes even more advantage of a triangular matrix:
tmat = triu(rmat);
clock({cpu}); mm = eig(tmat); clock({cpu})?
```

Xmath checks object properties before computations so that it uses the fastest algorithms and performs no unnecessary computations.

Polynomials

To create a polynomial, specify its roots with the polynomial () function, or specify its coefficients with makepoly:

The default variable name is x. Both functions have an optional string argument that specifies the variable name. For example:

```
p = polynomial([1+jay,1-jay],"s")
p (a polynomial) =
    2
    (s - 2s + 2)
```

Several operators and functions are defined differently for polynomials than they are for matrices.

Multiplying two polynomials with the * operator returns the polynomial convolution:

When adding two polynomials, the corresponding order terms of the two polynomials are added:

```
poly1+poly3
ans (a polynomial) =

4      3      2
x - 12x + 47x - 66x + 30
```

Similarly, when adding a scalar and a polynomial, the scalar is added to the scalar term of the polynomial:

```
poly1+1
ans (a polynomial) =
   2
   x - 6x + 6
```

When multiplying a polynomial and a scalar, the output format depends on the format of the polynomial:

```
poly1*2
ans (a polynomial) =
  2(x - 1)(x - 5)
```

Use roots () to find the roots of a polynomial:

```
roots(poly3)
```

```
ans (a column vector) =

1
1
5
```

Use polyval () to evaluate the polynomial with a scalar value for the variable:

```
polyval(poly2,3)
ans (a scalar) = 489.3
```

Indexing into a polynomial is similar to indexing into a matrix. To find and change the coefficient of the third element, type:

```
poly2(3)
ans (a scalar) = 2.4
poly2(3) = 9
```

Dynamic Systems

Xmath represents a dynamic system as either a transfer function or a state-space system. A transfer function consists of two polynomials; a state-space system is represented by four matrices. Transfer functions can only represent single-input single-output (SISO) systems, but state-space systems can represent multiple inputs and output (MIMO) systems. Objects for both types of systems can be either discrete or continuous, depending on the value of the object's sample rate.

Transfer Functions

A transfer function is built from numerator and denominator polynomials:

```
num = makepoly([1,-163,5.5]);
den = makepoly([1, 2.7, 5.6, 3.5, 8.1]);
Use system to create the transfer function:
sysTF = system(num, den, {dt = 1})
sysTF (a transfer function) =
         x - 163x + 5.5
          3
 x + 2.7x + 5.6x + 3.5x + 8.1
  initial delay outputs
  0
  Input Names
  Input 1
  Output Names
  _____
  Output 1
  System is discrete, sampling at 1 seconds.
```

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If you do not wish to specify a sampling rate, you can use the shorthand form: sys=num/den.

To extract the numerator or denominator of a transfer function, use numden:

```
[n,d]=numden(sysTF)
n (a polynomial) =
    2
    x - 163x + 5.5
d (a polynomial) =
    4     3     2
    x + 2.7x + 5.6x + 3.5x + 8.1
```

State-Space Systems

To create a state-space system of the form

$$\dot{x} = Ax + Bu$$
$$v = Cx + Du$$

use system with four matrices as inputs:

```
ha=[1,0,0,.1; 0,-.2,.1,0; 0,1,0,0;-.2,0,0,1];
hb=[.5,0,0,.3]';
hc=[1,0,1,0];
hSS=system(ha,hb,hc,0)
```

hSS (a state space system) =

A			
1	0	0	0.1
0	-0.2	0.1	0
0	1	0	0
-0.2	0	0	1

B 0.5 0 0 0.3

```
C
1 0 1 0
D
0

x0
0
0
```

System is continuous

Notice that Xmath creates continuous systems by default. To create a discrete system, include the keyword dt, which sets the sampling period in seconds:

```
hSSd=system(ha,hb,hc,0, {dt = .1});
```

To extract the state and initial condition matrices from a system, use abcd:

```
[A,B,C,D,X0] = abcd(hSSd)
```

The functions sys2sns() and sns2sys() might interest you:

- sns2sys() converts a system from MATRIXx to an Xmath object.
- sys2sns() converts an Xmath system object to MATRIXx format.

Analyzing Dynamic Systems

You can display the time domain response of a system using the functions in Table 2-2.

Table 2-2. Time Display Functions

impulse()	Computes the impulse response of a system.
initial()	Computes the unforced response of a system to a given initial condition.
step()	Computes the step response of a system.
defTimeRange()	Computes a default time vector for simulations.
sys*u()	Performs a general simulation, where u is a PDM representing system input.

These functions return parameter dependent matrices (PDMs), our next topic. For more on these functions, refer to the *MATRIXx Help*.

bode, nyquist, and nichols display frequency-domain response in several standard formats. For example, to see the bode plot of the continuous-time system we created earlier, type:

bode (hSS)?

Parameter Dependent Matrices

A parameter-dependent matrix (PDM) is a collection of same-size matrices, with a vector (called the *domain*) attached; each matrix depends upon a corresponding element of the domain vector. A PDM stores matrices as functions of an independent element parameter (the domain). A PDM is often a matrix of a physical parameter, such as time, frequency, or speed.

PDMs are built from string, vector, and matrix objects using the pdm() function. For example, the following PDM stores data in a legible compact format:

```
d=[95:99];
AR=[ 60.8; 59.3; 54.4; 50.7; 50.7];
CO=[ 41.2; 41.7; 36.3; 35.7; 35.3];
OR=[ 46.1; 47.5; 47.6; 46.7; 48.7];
WA=[ 45.4; 45.6; 44.0; 43.2; 43.9];
states=["AR","CO","OR","WA"]
eJobs=pdm([AR,CO,OR,WA],d,{domainName="Year",columnName s=states})
```

eJobs (a pdm) =

	AR			WA	
	60.8			45.4	•
96	59.3	41.7	47.5	45.6	
97	54.4	36.3	47.6	44	
98	50.7	35.7	46.7	43.2	
99	50.7	35.3	48.7	43.9	

The advantage of storing the data, names, and domain together is clearer when we create a plot such as Figure 2-8.

```
g2=plot(eJobs,{strip,ymax=65,ymin=32,ylab="THOUSANDS",
line_color = "mulberry", line_width = 2})
```

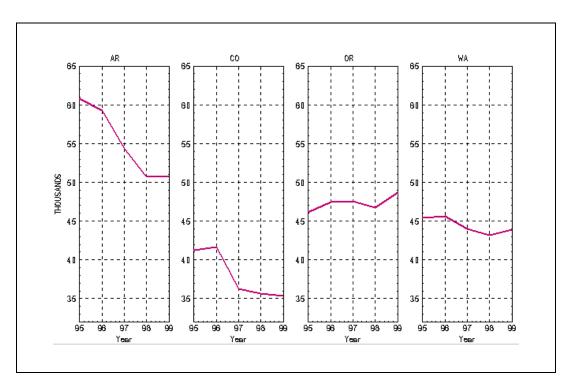


Figure 2-8. PDM Plotted with the strip Keyword

PDMs are commonly seen as outputs from functions, such as those listed in Table 2-2. If you calculate the impulse response and step response of hssd (the discrete state-space system created earlier), the responses are formatted as PDMs. The output is too long to show here, but you can view it in the log area:

```
hIm=impulse(hSSd);
hSt=step(hSSd)?
```

It is convenient to store these related PDMs together in another PDM:

```
hPdm=pdm([hIm;hSt], {rowNames=["Impulse", "Step"]})?
```

Plot the responses separately with the strip keyword:

```
plot(hPdm, {strip})
```

shows the results.

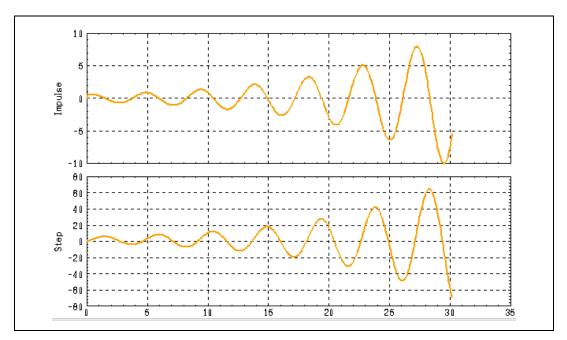


Figure 2-9. PDM Impulse and Step Responses Plotted Separately

The size of a PDM is given as rows \times columns \times length of the domain: size (hPdm)

```
ans (a row vector) = 2 1 303
```

Portions of a PDM are accessible with indexing, similar to matrices. Extract the fifth dependent matrix from hPdm:

To look at only the impulse responses, type:

hPdm(1,1)ans (a pdm) =

domain

0 | Impulse 0
0.1 | Impulse 0.5
0.2 | Impulse 0.53
0.3 | Impulse 0.55
0.4 | Impulse 0.5594
0.5 | Impulse 0.5578
: : : :

To perform a general simulation, you can multiply a system by a PDM. Here we use freq to create a PDM.

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```
u=freq(hSSd, deftimer(hSSd));
Y=hSSd*u;
plot(Y)
```

For more detailed information on PDMs, refer to the *Parameter-Dependent Matrix (PDM)* section of Chapter 5, *Data Objects and Operators*.

Lists

A list object is a named collection of elements (objects). A list can contain varied objects (including other lists). It is one-dimensional, storing your specified objects regardless of dimensions or properties. Use the list() function to create this object:

```
set seed 0
scalar1 = 1;
string1 = "This is a string object";
poly = makepoly([1,2]);
matrix = random(5,5);
a_list = list(scalar1,string1,poly,matrix)
a_list (a list with 4 elements) =
1:
  1
2:
  This is a string object
3:
 x + 2
4:
 0.211325 0.756044 0.000221135
                                   0.330327
                                               0.665381
  0.628392 0.849745 0.685731
                                   0.878216
                                               0.068374
```

```
    0.560849
    0.662357
    0.726351
    0.198514
    0.544257

    0.232075
    0.231224
    0.216463
    0.883389
    0.652513

    0.307609
    0.932962
    0.214601
    0.312642
    0.361636
```

A list containing four objects has a size of 4. To extract an element, specify its order in the list:

```
a_list(3)
ans (a polynomial) =
    x + 2
a_list(1)
ans (a scalar) = 1
```

MathScript

MathScript is the language of Xmath. Every instruction you have typed into the **Xmath Commands** window so far is a MathScript statement. With a MathScript script file, you can create and define a MathScript function, command, or object as MathScript entities, which are immediately available for use without special linking or compiling. Chapter 6, *MathScript Programming*, describes how to create, define, and debug MathScript entities.

MathScript Features

MathScript provides the following features:

- Familiar programming constructs such as for and while loops and if statements.
- Nested expressions:

```
x = 20 * log(abs(1 + 2 * jay))
```

• Functions to obtain interactive user input, such as getline() and getchoice().

```
UserIn=getline("Enter the number of states now:")
vote=getchoice("Choose or Lose", ["Repub", "Demo", "Inde"])
```

 Functions to determine whether objects possess certain properties (check and is). For example:

```
a = [1,0;0,1]
check(a, {identity})
ans (a scalar) = 1
```

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These features and more programming issues are discussed in Chapter 6, *MathScript Programming*.

Xmath Debugger Window

The **Xmath Debugger** window is referred to as "the debugger." It allows you to interactively debug MathScripts. Usually the debugger is activated because a script contains a syntax error or a runtime error. It also opens if you have set up a file to be debugged. You call debug the same way for both functions and commands:

debug program_name

The debugger opens whenever the function or command is invoked. To turn off debugging, type:

debug program_name off

When the debugger opens, the top field in the window contains the source of the MathScript function or command you are debugging. The filename is displayed below the menu bar. If you do not have write privileges to the source file, the source code may be opened read-only (not editable). The line that is about to be executed is highlighted (unless there are syntax errors in the function, in which case highlighting is used to identify the error). The message area, which displays error messages that occur during execution, is just below the source code area. You can use buttons at the top of the window in lieu of debugger commands.

Run the debugger demo. It instructs you on how to edit an MSF that contains syntax errors. From the command area, type:

execute file="\$XMATH/demos/debuggingMS1"

For more information about the **Xmath Debugger** window, refer to the *Using the Xmath Debugger* section of Chapter 6, *MathScript Programming*.

GUI Tools

Xmath offers a programmable graphical user interface (PGUI or GUI). For an introduction to the GUI, and instructions on starting and using the GUI demos and tools, refer to Chapter 9, *Graphical User Interface*.

To see some examples of GUI tools, type: quidemo

To exit Xmath, refer to the *Exiting Xmath* section of Chapter 1, *Introduction*.

Conclusion

This concludes the Xmath tutorial.

As you worked through the tutorial, you have become acquainted with the concepts and procedures necessary to use the basic Xmath features (described in Chapters 3 through 5). Chapters 6 through 9 discuss advanced topics:

- Chapter 6, *MathScript Programming*, tells how to write your own functions and commands using MathScript.
- Chapter 7, *MathScript Objects*, tells how to create your own MathScript object.
- Chapter 8, *External Program Interface*, tells how to link C, C++, or FORTRAN files to Xmath, and also details how to call Xmath from an external program.
- Chapter 9, *Graphical User Interface*, tells how to program your own graphical user interface.

MathScript Basics

MathScript is the language of Xmath. MathScript contains many of the facilities common to high-level programming languages, such as logical expressions loops, comments, conditional statements, nested functions and recursion.

MathScript Statements

A statement is the smallest independent executable instruction. Here are some examples of statements:

```
x = 7

y = ones(3,3)

who

set format long
```

The first two statements are examples of assignments. The last two statements are examples of commands.

Assignments

The most common MathScript statement is an assignment. An *assignment* is a statement that sets a variable to a specific value defined by the expression on the right-hand side:

```
variable = expression
```

- If an expression output is assigned to a variable, use the question mark (?) terminator to display the result. To suppress the output, use the semicolon (;) terminator.
- A carriage return is also a statement terminator. If set display is on, a return displays the result; if set display is off, nothing is displayed. Refer to Table 3-7 for more information.
- Variable types do not have to be declared before assignment.
- Objects can be completely or partially modified using assignment statements combined with indexing. For example:

```
y = [100, 21:24]
y (a row vector) = 100 21 22 23 24
```

$$y(1) = 0$$

y (a row vector) = 0 21 22 23 24

Rules for Names

Variable names consist of alphanumeric characters and internal underscores (_) only.

- Name components must be less than 32 characters in length. For example, variable b in partition a (a.b) could have a total of 31 characters.
- Names should not start with an underscore, because initial-underscore names are reserved for internal use.
- Variable and partition names are case sensitive. The following variables represent two partitions and four different variables:

```
a.b; A.b; a.B; A.B;
```

You can create a variable with the same name as a predefined Xmath function or command; however, you will be unable to access that pre-defined feature until you delete the variable.

Expressions

An *expression* is a combination of variable names, functions, and operators that evaluate to a single Xmath object. The Xmath object can then be assigned to a variable name. For example,

```
(1+\sin(pi/4))^2 # An expression
```

Expressions can be used as arguments to other functions or operators.

```
cep = abs(fft([1,-4,8,-2]))
```

The functions exist() and check() are exceptions. These functions require a variable name as an argument.

Logical Expressions

In MathScript, a nonzero value (with the exception NAN and Inf) is considered TRUE. All logical operators return 0 if FALSE and 1 if TRUE.

```
x = 3; x < (3 * cos(0))
ans (a scalar) = 0
```

Logical operators are "short-circuited." For example, exp1 | exp2 | exp3 will return 1 if exp1 is nonzero without evaluating exp2 or exp3.

Therefore, careful ordering of subexpressions in logical expressions may speed up execution.

Table 3-1 lists all MathScript logical operators. For a list of all Xmath operators, refer to Table 3-3.

Table 3-1. MathScript Logical Operators	natan		Effort
		Table 3-1.	MathScript Logical Operators

Operator	Effect	
<	Elementwise less than.	
>	Elementwise greater than.	
<=	Elementwise less than or equal.	
>=	Elementwise greater than or equal.	
==	Elementwise equal.	
<>	Elementwise not equal.	
&	Elementwise logical and.	
	Elementwise logical or.	
!	The logical negator (!) appears directly before an expression. For example, !expr.	

Logical Expressions with Matrices

When used with logical operators, two matrices must be equal in size; the output will be a matrix containing the element-by-element comparison results.

```
a = [1,0;1,1];b = eye(2,2);
a & b
ans (a square matrix) =

1    0
0    1
```

ans is a matrix with 1 in the locations where a and b are the same.

```
a < b
ans (a square matrix) =

0   0
0   0</pre>
```

You can also make logical comparisons with the functions <code>check()</code> and <code>is()</code>, which return a logical value. The functions <code>all()</code>, <code>any()</code>, and <code>none()</code> can also be used to return a logical value. Refer to the <code>Object Query Functions</code> section of Chapter 6, <code>MathScript Programming</code>, or the <code>MATRIXx Help</code> for more details.

Operators

An operator is a nonalphanumeric symbol that operates on its operand(s). Operators with only one operand are called *unary operators*. Operators with two operands are called *binary operators*. Table 3-2 shows how operators are used in expressions.

Format Type Example

operator operand Unary (prefix) -x

operand operator Unary (suffix) x'

Binary

х+у

Table 3-2. Uses of Operators in Expressions

Table 3-3 lists the operators available in Xmath and their intrinsic functions; overloaded functions are described in other chapters.

operand1 operator operand2

Operator	Effect	
+	addition	
_	subtraction (and the unary operator negation)	
*	multiplication	
/	right division, A/B solves the equation X*B=A	
\	left division, B\A solves the equation B*X=A	
1	transpose (unary suffix)	
* '	Hermitian (complex conjugate) transpose	
.*	element wise multiplication	
./	element wise division (left divided by right)	
.\	element wise division (right divided by left)	

Table 3-3. Xmath Operators

 Table 3-3.
 Xmath Operators (Continued)

Operator	Effect
^	raise to a power
or * *	
. ^	raisa alamanta ta a navyar
or	raise elements to a power
. * *	
.*.	Kronecker product
./.	Kronecker right division
.\	Kronecker left division
&	logical AND
	logical OR
!	logical NOT (unary operator)
<	less than
>	greater than
<=	less than or equal
>=	greater than or equal
==	equal
<>	not equal
=	assignment
()	indexing, precedence, and function reference
{ }	keyword delimiters in function references
[]	matrix construction and concatenation

Operator behavior depends on the objects involved. Special behaviors are discussed in detail in the object descriptions in Chapter 5, *Data Objects and Operators*.

Operator Precedence

You can control operator precedence with parentheses. In Table 3-4, operators are ordered with precedence from highest to lowest (reading from top to bottom).

high	non-associative	1 *1
	left–associative	** ^ .** .^
\	left–associative	* / \ .* ./
	non-associative	! unary + unary -
\downarrow	left–associative	+ -
	left–associative	:
\downarrow	left-associative	> < >= <= == <>
	left–associative	&
low	left-associative	

Table 3-4. Operator Precedence

Partitions

All variables reside in partitions. main is the default partition. You do not need to specify the partition name of a variable if it resides in the current partition; just call it by its local name.

Partitions must be created using new partition before any variables may be placed in them. To create or use a variable in another partition, you must specify the partition name. Partition names must meet the naming rules in the *Rules for Names* section. For example,

```
job2.R = job1.R
```

job1.R = R

- # Assign R in the current partition to the
- # variable R in partition job1.
- # From the current partition, perform
- # an assignment between two other
- # partitions.
- To show the current partition, use the show partition command: show partition

main

To list all defined partitions, type:

show partitions

Notice the s at the end.

Complete the following steps to get a better understanding of partitions.

1. main is the default partition that is created whenever Xmath is started. If you are in main, you can create an object in partition main by typing:

```
xx = 1
```

This is equivalent to main xx = 1.

To create a new partition named var, type:

```
new partition var
```

3. You can navigate between partitions with the set partition command:

```
set partition var
show partition
```

var

XX

xx not found.

4. Because xx is defined in partition main, its partition name must be included:

```
main.xx?
               # variable from another partition
main.xx (a scalar) =
yy = 55?
               # create variable in current partition
                  55
yy (a scalar) =
```

5. Return to the main partition. The original main.xx is in local scope, while yy exists in the partition var.

```
set partition main
ХX
xx (a scalar) =
```

var.yy

var.yy (a scalar) = 55

6. A partition must be empty before it can be deleted. To delete a partition, use the delete command. First, delete the partition contents, then the partition itself:

```
delete var.* var.
```

Listing Defined Variables

To list all defined variables in the current partition, use the who command: who

A single wildcard can be used with who:

To list all variables in all partitions, type the following:

```
who *.*
```

Wildcards

Xmath allows the asterisk (*) and percent (%) symbols to be used as wildcards for viewing, saving, loading, or deleting variables.

An asterisk denotes "any characters." Used by itself, an asterisk is a wildcard for all names. Therefore, delete * deletes all variables in the current partition. Used with other characters, an asterisk replaces any number of characters in that position. The percent sign replaces a single character in that position.

```
a3=4; a23=1; b22=144; c23=random(a3,a23);
who*
#Show variables in the current partition.
who a*
#Show variables starting with a.
who *3
#Show variables ending with 3.
who %2%"
#Show 3-character names where 2 is
#the second character(a23, b22, c23).
```



Note You cannot use the wildcard * twice in a pattern. For example, *sys* is not allowed, but *sys%% is accepted.

Variable and Partition Comments

You can attach a comment string to a variable or partition name with the comment command.

```
comment main. "this is the default partition" a=97; comment a "the first letter of the alphabet"
```

• To retrieve the comment, use commentof():

```
commentof(a)
```

```
ans (a string) = the first letter of the alphabet
commentof(main.)
```

```
ans (a string) = this is the default partition
```

• You can also view the comment for a variable if you display the **Xmath Information** view. Refer to the *Xmath Information View* section of this chapter for more information.

Permanent Variables

Permanent variables are values that have special meanings. These variables are defined in all partitions as shown in Table 3-5.

Variable	Definition
Inf	infinity
Jay	sqrt(-1)
NaN	Not a Number
eps	very small number used to initialize outputs to be near zero but not exactly zero
huge	largest finite number less than Inf
null	empty object
pi	famous Greek number
tiny	smallest possible number greater than 0
err	global error status variable (set to NaN)

Table 3-5. Permanent Variables

The name of a permanent variable or predefined function/command can be overridden in the current partition or function/command scope, although it is not recommended. When a value that has been given the name of a permanent variable is deleted, the original definition reappears:

```
eps=2
eps (a scalar) = 2
delete eps
eps?
eps (a scalar) = 2.22e-16
sin=1?
sin (a scalar) = 1
sin(pi) # argument out of range
delete sin
sin(pi)
ans (a scalar) = 1.22465e-16
```

ans

When a value returned from a function is not assigned to a variable name, it is assigned to the variable ans.

```
sin(0.5)
ans (a scalar) = 0.479426
```

The value of ans is overwritten anytime the output of a function is not assigned to a variable. Notice that the value of ans is local to the current partition.

Xmath Information View

The **Xmath Information** view is a graphical interface that simplifies variable management. This view displays variable and partition information and allows you to load and save Xmath data.

a Xmath Information Dimension Variable Туре Value Comment 🖹 main Partition Scalar 4 lxl b String hello lxl c Matrix 5x7

Figure 3-1 shows an example **Xmath Information** view.

Variables

History

Figure 3-1. The Xmath Information View

You can access many common Xmath functions by right-clicking or double-clicking in this view. For example, to change the working partition, right-click a partition and select **Set as Current**. To edit a variable, double-click its entry in the list.

To save or load information, right-click in this view and select **Save All** or **Load**, respectively. You can also save specific items by pressing <Ctrl>, clicking each item you want to save, right-clicking in the view, and selecting **Save Selected**.

To resize the view, drag the left border. To sort the variable list by **Variable** name, **Type**, **Value**, **Dimension**, or **Comment**, click the appropriate column. You can also access a history of Xmath commands by clicking the **History** tab at the bottom of this view.

To refresh this view after you add or remove a variable or partition, right-click in this view and select **Update**.



You can toggle this view on and off by clicking the **Information** button, shown at left. This button is located to the right of the command area.



Note In MATRIXx 7.x and earlier, you used the **Variable Manager** window to display partitions and variables. You can access this window by entering variablemgr in the command area.

Punctuation

MathScript has special uses for the ?, ;, ..., #, and . characters. These are illustrated in Table 3-6.

Table 3-6. Punctuation Mark Usage

?

A question mark is a statement terminator. When placed after a numeric or string object, the value is displayed in the log area; when placed after a graph object, the graph is displayed in the Graphics window.

y = eye(3,3)?x=y/2;
y (a square matrix) =

1 0 0
0 1 0
0 0 1

Interactively, the default display behavior, which can be changed with set display, is to display the output of all assignments and expressions not terminated by a semicolon. If this is the behavior, the question mark is only needed as a separator. If set display is turned off, output is suppressed unless a question mark is used. Refer to Table 3-7.

;

A semicolon (;) disables display to the log area, and acts as a separator or terminator. A semicolon disables display regardless of whether set display is on or off.

x = 1:3:10; x'
ans (a column vector) =

1
4
7
10

Table 3-6. Punctuation Mark Usage (Continued)

An ellipsis (...) is a continuation symbol that allows an Xmath statement to span multiple lines: plot ... (rand(1,50), {title="Testgraph", line_style=1}) Ellipses are not required if a line ends with a comma, or an operator: plot (x,y,z,{x_lab="Hello",y_lab="Goodbye", z_lab="Leave town before sundown!"}) However, you cannot continue all commands, even if you use the ellipsis. For example, you cannot split an output assignment; thus, the following multiple line entry results in an error: [blocknr=selectedblocks, sbname=name, sbin=inputs, sbinname=inputname, sbout=outputs,sboutname=outputsignal] = querysuperblock(); You can split this example input before or after the equal sign (=) but nowhere else. A pound sign (#) comments out everything to the right on a single line. To comment # multiple lines of text, surround them with #{ }#. #Comment a single line #{You can comment multiple lines}#

Iterative Conditional Statements

In MathScript, For and While loops have the syntax shown in Figure 3-2.

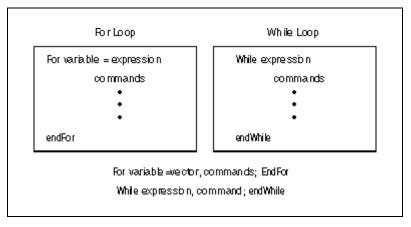


Figure 3-2. For and While Loops

If statements in MathScript have the syntax shown in Figure 3-3.

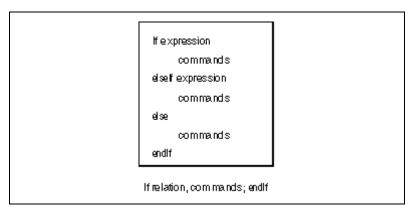


Figure 3-3. If Statements

Note that end can be used in place of endFor, endWhile, or endIf.

Using Predefined Functions and Commands

To determine the origin of a function or command use the whatis command:

whatis freq

freq : intrinsic function

whatis bode

bode : ISI function (path/bode.xf)

whatis build

build: intrinsic command

- Entities referred to as National Instruments functions and commands are written in MathScript. You can view the National Instruments function and command MathScript source in the location returned by whatis, as shown in the Previous Example.
- Intrinsic functions and commands are written in C++ and built into Xmath by National Instruments; you cannot view this source. Chapter 6, *MathScript Programming*, describes how to use MathScript to define your own functions (MSFs) and commands (MSCs). The characteristics of Xmath objects are also intrinsic; Chapter 7, *MathScript Objects*, describes how to use MathScript to define your own objects (MSOs).

Command and Function Calling Syntax

The rules described in this section are general; they apply to both intrinsic functions and commands and MathScript functions and commands.

- The names of functions, commands, and keywords are case insensitive.
- Function and command names can be abbreviated to minimum of four letters, or the minimum number of characters that uniquely identify the name.

For example:

```
cova([1,2;3,4]);

t = makep([1,2,3,4]);
```

covariance() can be called by specifying the first four characters, while makepoly() must be abbreviated to five characters (because it conflicts with makematrix()):

• Function inputs, keywords, and outputs are separated by commas.

```
[Ke, ev, P] = estimator(Sys, Qxx, Qyy)
```

Aliases

Names or strings can be aliased to a shorter string with the alias command. Refer to the *Abbreviating Command Names (alias and unalias)* section for more information. Then you can refer to the name or string by its alias. For example:

```
alias ef execute file
alias ts title="TOP SECRET";plot(A, {ts})
```

Input Arguments

 The syntax for calling intrinsic commands and MathScript commands is slightly different. Inputs for MathScript commands are separated by commas, similar to MathScript functions.¹ For example:

```
xgraph t, {tgraph, average}
```

The majority of commands supplied with the Xmath Core are intrinsic, (refer to the *Using Predefined Functions and Commands* section) and the arguments are separated by spaces:

```
save "filename" a b c
```

¹ On the other hand, SystemBuild SBA commands are all written in MathScript, and use this syntax exclusively.

Use the syntax shown in the MATRIXx Help when in doubt.

• Functions and commands cannot be called with fewer than the required number of input arguments, or more than the maximum number of inputs, as specified in the syntax shown in the MATRIXx Help.

Keywords

- Keywords are optional and case insensitive. Keywords must be placed inside curly braces, { }, but the order is not significant.
- A value can be assigned to a keyword. Keywords with no value assigned are given Boolean values.

For example, the following calls give an identical result:

```
g=plot(x,{legend,!grid})?
g=plot(x,{legend=1,grid=0})?
```

If a keyword is specified but not assigned to an expression, its value is set to 1. This is useful for Boolean keywords, because 1 is interpreted as TRUE. Preceding a keyword with the negation operator (!) causes its value to be set to zero, or logical FALSE. The plot keywords specified previously display a legend and no grid lines.

• Expressions can be used as arguments to keywords.

```
t = plot (x, {x_max = (4 * 256), x_lab="time"})
```

Single and Multiple Output Arguments

- As discussed in the *ans* section, if no output variable is specified, the output is assigned to the default variable ans.
- To view and assign multiple function outputs, an output name must be specified in square brackets on the left side of the equation for each output needed.

```
[T,S] = schur(A);
```

• If functions return multiple arguments, the output arguments will be matched left to right. Consider the function size:

```
[outputs, inputs, states] = size(aSystem)
```

If a multiple output function is called with a single output name, the output will take the value assigned to the leftmost output according to the function syntax.

```
x = size(aSystem) # returns outputs
[x,xx] = size(aSystem) # returns outputs, then inputs
```

 You can skip specific output arguments. To do this, use commas as placeholders.

```
[,,states] = size(aSystem)
```

• Functions cannot be called with fewer than the required number of input arguments or more than the maximum number of outputs, as specified in the syntax shown in the MATRIXx Help.

Refer to the *Variable Arguments* section of Chapter 6, *MathScript Programming*.

Operating System Interface

The oscmd() function lets you use operating system commands while in the Xmath environment. The output of the operating system command is displayed in the Commands window log area. For example:

```
oscmd("ls") # UNIX
oscmd("dir") # Windows
```

The return value of oscmd() is the exit code of the operating system command. For UNIX, if the command passed to oscmd() is backgrounded with &, the return status is 0, not the execution status of the background command. This behavior is consistent with UNIX calls.

Manipulate and Show Current Directory

The Xmath command set directory defines the default working directory. Use the following command to change this directory.

```
show directory # Show current working directory.
/home/usr/xmath
set directory "/home/projX"
save x y z "3dTest.ms"
```

To set the directory through a dialog box, select File»Set Directory.

Saving and Loading Data

Xmath provides commands for reading data files and writing Xmath objects in files. One pair of commands, SAVE and LOAD, works directly on Xmath objects and files. To increase the flexibility of the interface, the commands PRINT, READ, and the function fprintf() work with a wider variety of file formats.

The SAVE command writes Xmath variables to a file if entered without arguments:

save

All variables in all partitions are written to the binary file save.xmd, in the current working directory. This is equivalent to selecting **File»Save All**.

The LOAD command without arguments loads save.xmd from the current working directory:

load

Alternatively, selected objects can be saved and loaded, and you can specify a different filename:

```
a = 1:1:10; b = "this is a test";c = 55;
Save a and b in file mysave.xmd:
save a b "mysave"; b = 27000;
Save b and c in file saveagain.xmd:
save b c "saveagain"
delete *
load b "mysave"
b
b (a string) = this is a test
load b "saveagain"
b
b (a scalar) = 27000
```

The extension xmd is appended to the filename unless you specify a different extension.

Objects with the same names as objects in the loaded file are overwritten. For example:

```
a = 1:1:10;
aa = "this is a test";
save
aa = 55

aa (a scalar) = 55
load
aa
aa (a string) = this is a test
```

The data is saved in Xmath binary format by default. Alternatively, the data can be saved in an Xmath ASCII, MATRIXx binary, or MATRIXx ASCII (FSAVE) format.

```
save "mysave" {ascii}  # Xmath ASCII
save "mysave" {MATRIXx}  # MATRIXx binary
save "mysave" {MATRIXx, ascii}  # ASCII
```

Refer to the *SAVE* and *LOAD* topics in the *MATRIXx Help* for more information. For information on how to save and load files in Xmath format without starting Xmath, refer to the *LNX and UCI Functions* section of Chapter 8, *External Program Interface*.

ASCII Versus Binary Considerations

Format selection (ASCII or binary) is a trade-off between loading speed and portability.

Compared to the ASCII format, the binary format loads faster in Xmath. The larger the data file, the more noticeable the speed advantage will be. On the other hand, the binary format is typically larger in size and is not portable across different Xmath platforms. Furthermore, a binary data file must be transferred as binary, for example, through the binary mode in FTP.

Before you send a binary data file through email, you must first encode the file with uuencode (or an equivalent mail encoder), and the recipient of the email can then use uudecode to recover the original binary file.

The ASCII format is fully portable. An ASCII format save file can be transferred to any Xmath platform with NFS, FTP, or email. However, some email gateways have restrictions on the length of lines of the email content. For such systems, the save file, even though it is ASCII, should be treated as a binary file for the purpose of email transmission as mentioned above. Again, this requirement is the same for non-Xmath files that contain long lines.

Saving Data in Non-Xmath Formats

print

The PRINT command outputs Xmath data to a file.

```
a = [1.1,2.2,3.3;4.4,5.5,6.6];
print a file="print.tst"
oscmd("more print.tst") #UNIX
```

If a file of the same name exists, it will be overwritten.

fprintf()

Using the same conventions for formatting as the C language routine fprintf(), the fprintf() function converts numeric values to a string representation for display, and writes them to an external file. For example:

```
N = 3;
s=fprintf("fpr.asc","%d Laws of Motion"n",N)
```

where n is the newline escape character sequence. Refer to the *Special Characters in Strings* section of Chapter 5, *Data Objects and Operators*. If an fprintf() call uses a filename that already exists, the output will be appended to the existing file:

```
s=fprintf("fpr.asc", "%d Laws of Thermodynamics"n", N)
```



Note You can use the keyword reset to specify that the output file (if it already exists) be truncated.

Print out the contents of the newly created file to the log area:

Refer to the *MATRIXx Help* for more information about PRINT and fprintf().

Reading Non-Xmath Data Files into Xmath

The ${\tt read}(\)$ function reads data files of binary numbers or ASCII text files into an Xmath matrix. The syntax for ${\tt read}(\)$ is:

```
matrix=read(filename,out_rows,out_cols,type,seek)
```

read() can be called with just the filename argument, in which case the entire content of the file is read into an Xmath string value.

Refer to the *read* topic of the *MATRIXx Help* for more examples.

MathScript Environment

The SET, SHOW, GET, and REMOVE commands allow you to customize the MathScript environment. The SET command affects many settings, including data output format, and random distribution. Commands such as SHOW and REMOVE and the function get () support other utilities for displaying current variables and resetting conditions.

Changing Environment Settings

Certain aspects of the MathScript programming environment can be modified using the set command. For example, SET format changes the numerical output format:

```
x = 0.12345678901234567890?
x (a scalar) = 0.123457
set format longe
x
x (a scalar) = 0.1234567890123457e-01
set format shorte
x
x (a scalar) = 1.234578e-01
set echo on
show directory
/disk/math/test
```

Table 3-7 is a list of variables that SET controls.

Table 3-7. Environment Variables Controlled with SET

Variable	Effect			
autocompile	Sets automatic compilation on/off for user-defined MSFs and MSCs. Refer to the <i>MathScript Program Compilation and Execution (.xf, .xc)</i> section of Chapter 6, <i>MathScript Programming</i> . Default is On.			
break	Use from within the Xmath debugger to set a breakpoint at a specified line number. Refer to the <i>Using the Xmath Debugger</i> section of Chapter 6, <i>MathScript Programming</i> .			
buffering	Sets text buffering on/off for output to the log area. Default is Off. By default, Xmath sends output to the log area as soon as it is available. If you are looking for maximum possible speed, SET BUFFERING ON.			
commanddiary	Records command input in the file you specify. Refer to the <i>Recording an Xmath Session (Diaries)</i> section.			
debugonerror	Determines whether or not a script that contains a runtime error will be debugged. Default is On. Refer to the <i>Using the Xmath Debugger</i> section of Chapter 6, <i>MathScript Programming</i> .			
directory	Sets the working directory.			
display	When in interactive mode, if display is set to On, the result of an assignment is displayed to the log area unless a semicolon (;) is used to suppress the output. If display is set to Off, assignment outputs are not shown unless a question mark (?) is used.			
	When a MathScript file is executed, the interactive display setting is ignored. Function outputs, including plot output, are not shown unless the question mark (?) terminator is used in the MathScript.			
	Default is on.			
distribution	Sets the distribution type for the function random(). Options are uniform and normal. Default is uniform.			
echo	Sets on/off echoing of contents of executed MathScript files to the Commands window log area, or the Graphics window, as the case may be. Refer to the <i>Echoing an Executable File</i> section.			
	If you want a function output to be displayed upon execution, including plot output a ? must be used in the file, and echo must be on when it is executed.			
	Default is Off.			

 Table 3-7. Environment Variables Controlled with SET (Continued)

Variable	Effect
format	Sets numerical display output format. Choices are: compact, engineering, fixed, long, longe, scientific, short, and shorte. fixed sets the number of decimal digits in a floating point number to the value defined with set precision (see precision below). Default is compact.
partition	Sets the working partition. Refer to the <i>Partitions</i> section. The default for a new Xmath session is main.
path	Sets a search path for user-defined MSFs and MSCs. Multiple set path commands may be issued.
pause	Sets pause to on/off. If pause is set to off, the pause command is ignored. Default is On.
precision	Specify an integer representing the number of decimal digits. This number affects variable display when set format fixed is specified. Most machines cannot display more than 15 or 16 digits.
seed	Specify an integer to be the random seed. The random seed is reset to 0 at the beginning of each Xmath session. To find the current seed, use show seed or get ({seed}).
sessiondiary	Record Xmath inputs and outputs in a file. Refer to the <i>Recording an Xmath Session (Diaries)</i> section.
timestamp	Turn on/off variable timestamping whenever a variable is changed or modified. Turning timestamp off can save computational time when variables used in a loop. Default is on.
uiupdate	Turn on/off variable and partition updating whenever a variable is changed or modified. Turning uiupdate off can save computational time when variables used in a loop. Default is on.
watch	Use within the debugger to set a watchpoint for the named variable.

The REMOVE command cancels or deletes environmental settings, such as path, sessiondiary, or commanddiary to cancel or delete the function. REMOVE fills this need:

remove commanddiary

To check the current setting of any SET parameter, use the SHOW command:

```
show seed
```

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The function get () can be used to return a current setting that can then be assigned to a variable.

```
working_dir = get({directory});
working_dir
current_dir (a string) = /home/xmath/data
```

Expanding Pathnames in MathScript Files

Commonly, pathnames are represented by environment variables. You can expand them within a MathScript file in several different ways. For example:

```
set directory = $ENVIR_VAR
```

works because directory is a specific option designed for the SET command. On the other hand, if you use a general assignment, such as

```
file = "$XMATH/foo"
```

Xmath provides the result

\$XMATH/foo

because this assignment does not contain a command that was specifically designed to expand environment variables.

If you want the expected results from the previous assignment statement use the GET function with the keyword PATH. For example:

```
file = get({path="$XMATH"}) + "/foo"
```

provides the expanded pathname.

You can find additional examples of this type of usage in the following files:

```
$XMATH/modules/basic/hardcopy.msc
$XMATH/modules/basic/version.msc
```

You can also use the oscmd () with the \$ENVIR_VAR format; in this case, the operating system expands the environment variable.

Refer to the *get*, *SET*, and *oscmd* topics in the *MATRIXx Help* for more information.

Abbreviating Command Names (alias and unalias)

The ALIAS command allows you to substitute a name for a text string.

```
alias clear delete * alias mkm makematrix
```

To see all current aliases, type:

alias

An alias defined in any context is local to the defined scope. For example, an alias entered from the command line is not accessible from an MSF, MSC, or MSO. Conversely, an alias defined in an MSF, MSC, or MSO is not accessible from the command line.

Use the UNALIAS command to undo any aliases.

```
unalias clear
```

Alias substitution is performed at compilation time. Therefore, a code fragment similar to the following will not have the intended effect:

```
alias sl save
if do_load
  alias sl load
endif
sl  # Always substituted with load because that
was
  # the last alias command.
```

MathScript Batch Files

MathScript batch files contain sequences of Xmath statements. They are useful for setting up user environments, performing repetitious tasks, and processing programs in batch. MathScript batch files have no declaration statement, and therefore, no inputs or outputs.

Batch files are run using the execute file command. A MathScript batch file typically has the suffix .ms, but any suffix will do. If the suffix is .ms, you can execute the file without specifying the extension. Refer to the *Executing a Batch File* section.

If you do not want a function or command output to be displayed when the file is executed, use the semicolon terminator. If you want the output to be displayed, you must use a question mark as a terminator. This also applies to the output of the plot () function.

Executable strings must also be terminated by a semicolon (;) or question mark (?). For example, the following is incomplete:

```
test_string = "show format";
execute test_string
```

From the previous incorrect syntax, you receive the message:

Error(s) in executing show format

The correct syntax is as follows:

```
test_string = "show format;"
execute test_string
```

Executing a Batch File

You can execute a batch file from either the command area in the **Xmath Commands** window or the File menu. From the command area, use the execute file command. For example, to execute a batch file called myfile.ms in the current working directory, type:

```
execute file = "myfile"
```

Echoing an Executable File

By default, when you execute a MathScript file, the contents of the file itself are not echoed to the log area. If you specify SET ECHO ON, each statement is displayed to the log area as it is being executed. To turn this feature on, type:

```
set echo on
```

You can find out the current echo setting by typing:

```
show echo
```

To turn the echo off, type:

```
set echo off
```

startup.ms (on UNIX systems)

The environment variable XMATH_STARTUP defines the properties of the Xmath startup icon to execute the startup.ms batch file. This batch file contains MathScript statements that execute every time you start a new Xmath session. You can set up your initial working environment for the Xmath session. For example, you can specify a list of directories as a search path.

Xmath looks for and executes startup.ms in the following order:

- 1. The space-separated list of directories specified in the environment variable XMATH STARTUP
- 2. The optional xmath subdirectory under your home directory, \$HOME/xmath/startup.ms
- 3. The current directory, ./startup.ms

The environment variable XMATH_STARTUP can be set to include multiple directories. For example:

```
setenv XMATH_STARTUP "/home/group /home/user"
```

Xmath will run startup.ms in /home/group and then /home/user. Example 3-1 shows a sample startup.ms file.

Example 3-1 Sample startup.ms File

```
# set up aliases
alias sp set path =
# set path to several test directories
sp "/usr/me/tests"
sp "/usr/me/tests/routines"
# set up new partition and go there
new partition projectX
set partition projectX
# output data display format
set format long
```

startup.ms (on Windows Systems)

The environment variable XMATH_STARTUP defines the properties of the Xmath startup icon to execute the startup.ms batch file. This batch file contains MathScript statements that execute every time you start a new Xmath session. You can set up your initial working environment for the Xmath session. For example, you can specify a list of directories as a search path.

The following are sample definitions for %XMATH_STARTUP%.

• (Windows 9x) Set the path to the startup.ms batch file by adding the following line to your AUTOEXEC.BAT file (or to any other startup batch file):

```
set XMATH_STARTUP=%HOME%\user
```

Xmath looks for and executes startup.ms in the following order:

- 1. The space-separated list of directories specified in the environment variable XMATH STARTUP
- 2. The optional xmath subdirectory under your home directory %HOME%\xmath\startup.ms
- 3. The current directory .\startup.ms



Note You must define the %HOME% variable yourself.

You can set the environment variable XMATH_STARTUP to include multiple directories. For example:

```
set XMATH_STARTUP="%HOME%\group %HOME%\user"
```

Xmath runs startup.ms in %HOME%\group and then %HOME%\user. Example 3-2 shows a sample startup.ms file.

Example 3-2 Sample startup.ms File

```
# set up aliases
alias sp set path =
# set path to several test directories
sp "\user\me\tests"
sp "\user\me\tests\routines"
# set up new partition and go there
new partition projectX
set partition projectX
# output data display format
set format long
```

I/O Redirection

If you have a lengthy automated process that does not require interactive input, you can run it in background or batch mode using the tty (non-graphical) version of Xmath.

To create a MathScript file suitable for batch execution, start by using an editor to write a script file containing the instructions as you would enter them from the Xmath command line. Alternatively, you can start with a command diary file. Data generated in the batch script file can be written to an external file using the SAVE command.

If a file runs to completion and unsaved variables exist, Xmath asks the question:

Modified variables that have not been saved exist; quit anyway? (y/n)

This presents a problem because you cannot respond while in batch mode. To bypass the situation, you must save or delete the data at the end of the file. The final entry in a batch file must be QUIT. If QUIT does not end the file, Xmath will remain in terminal mode.

I/O Redirection

To run the completed batch file from the UNIX command line, type:

% xmath -tty < batchfile.ms > batchfile.output

where the MathScript input is contained in batchfile.ms, and the output results are redirected to batchfile.output. The output file contains anything that would normally appear in the Commands window log area, so be sure that echo is set properly.

Recording an Xmath Session (Diaries)

Xmath can automatically record commands and responses using command and session diaries. A command diary records user input only, while a session diary records user input and the Xmath responses.

To create a diary, the environmental variable echo must be on. If it is off, a diary file may be opened but nothing will be recorded in it. To determine the echo setting, type:

show echo

If echo is off, you must type set echo on to activate it.

Recording Inputs (Command Diary)

Command diaries record MathScript input. A command diary is by definition an executable file; it contains all valid instructions issued while the command diary was set. However, when the file is executed, you might not see all the outputs you did when you captured the commands; you must either edit the diary to insert the proper terminators or be sure to use them when you input the commands you are capturing.

To open a command diary, type:

```
set echo on
set commanddiary "mytest.ms"
```

where mytest.ms is the name of the diary file. The file is placed in the current working directory. Refer to the *Manipulate and Show Current Directory* section for details on setting the working directory. To see if a diary file is already open, type:

```
show commanddiary
```

If the specified file does not exist, it will be opened for writing. If a diary file of the same name exists, it will be closed and a new file opened.

```
t = 1:0.1:100
s = sin(t)
g=plot (s)?
```

To close a diary file, use the remove command:

```
remove commanddiary
```

Since a command diary contains only executable MathScript commands, you can replay the contents using execute:

```
execute file = "mytest"
```

Notice the output behavior when the file is replayed. When the calls were typed interactively, the outputs of t and t were written to the log area, but when the file was executed, the outputs were omitted. When a value is assigned to a variable, the function outputs will only be displayed if the question mark terminator (?) is used, as was the case for the graph object t

Recording Inputs and Outputs (Session Diary)

A session diary records inputs and outputs, that appear in the Commands window log area while the diary is open. This can be useful when the contents of a data object need to be recorded in the file. For example:

```
set echo on
set sessiondiary "session1"
test1 = 0.75;
exist(test1)
sin(test1)
remove sessiondiary
oscmd("more session1")
```

Because session diaries include outputs that are not MathScript statements, they cannot be executed as command diaries until they are edited.

Graphics

This chapter begins with an outline of the plotting functions and commands available in Xmath. The remaining sections show how to graphically display your data with the plot() function, and also how to change its appearance interactively with the **Xmath Graphics** window.

Xmath Plotting Functions and Commands

General Purpose Plotting Functions

Xmath provides a choice of three basic plotting functions:

- The plot () function provides an easy to learn syntax for 2D and 3D plotting in an interactive graphics window. For a quick, interactive look at your data, and for 3D plotting, plot () is a good choice.
- The uiPlot() function provides full featured 2D plotting integrated with an extensive programmable GUI facility. If you want more control over the formatting of your 2D graphics, or the ability to integrate plots with your own interactive Xmath PGUI tools, then uiPlot() has the power you need.
- The plot2d() function recognizes most plot() keyword options and provides quick access to advanced formatting features of the uiPlot() function, while avoiding the cost of constructing a programmable GUI tool. Use plot2d() to obtain highly customized 2D graphics without writing a PGUI tool.

plot()

The plot() function and its associated **Xmath Graphics** window provide complete interactive facilities for building, modifying, and viewing 2D and 3D graphics. You can specify graph characteristics as keywords to plot, or you can add or modify them interactively from the **Xmath Graphics** window menus or the **Xmath Palette**.

The output of plot () is a graphics object. Rather than archiving an executable file that recreates a graph, you can save the images as graph objects. A graph object can be displayed in the **Xmath Graphics** window,

altered with keywords, or combined with another plot to create a new image.

plot () keyword options facilitate multiple plots, strip plots, bar plots, polar plots, contour plots, and scatter plots. The animation mode of the **Xmath Graphics** window provides rapid sequential display of graphics objects.

This chapter provides additional detail on the capabilities of plot (). For further information about plot () and associated plotting tools, refer to the *Xmath*, *Plotting* topic of the *MATRIXx Help*.

uiPlot()

The uiPlot() function formats and displays 2D plots (including line, scatter, and polygon) in any uiPlotArea widget of a programmable GUI tool. While plot() is limited to displaying its objects in a single **Xmath Graphics** window, uiPlot() can generate and display plots in multiple windows. However, this power comes at a considerable cost—the construction of programmable GUI tools and widgets.

uiPlot() features include interactive data-viewing, zooming, and curve selection. Animation is achieved through the binding of curves to Xmath variables. Custom callbacks can be programmed in GUI tools, providing application-specific, graphic interaction with the data.

The uiPlot() function syntax provides access to the structure of the underlying graphics database. The database hierarchy lets users specify graphics objects much like how one specifies a file path. Properties can then be set using either uiPlot() keywords, or generic option strings of the underlying graphics system, resulting in a wide range of custom formatting capabilities.

For more information about the programmable GUI, refer to Chapter 9, *Graphical User Interface*. For further details on using the uiPlot() function and associated plotting tools, refer to the *Xmath*, *Plotting* topic of the *MATRIXx Help*.

plot2d()

The plot2d() function is based on uiPlot() and is designed to implement most capabilities of both plot() and uiPlot(), while avoiding the overhead of programmable GUI tools and widgets.

In particular, plot2d() provides multiple graphics windows, interactive data-viewing, animation through the binding of curves to Xmath variables, and the power of the uiPlot function syntax. Some new features have been implemented such as multiple Y-axes, advanced row/column layout options, and automatic data scaling in one coordinate while constraints are specified in the other.

For those familiar with plot () syntax, plot2d() supports most of the 2D-related keywords of plot (). It is possible to convert most scripts by substituting plot() function calls with identical plot2d() calls.

The most obvious differences between plot2d() and plot() are that 3D plotting options and the graphics object are not supported. All uiPlot() functionality is available through the plot2d() function.

For further details on using the plot2d() function and associated plotting tools, refer to the *Xmath*, *Plotting* topic of the *MATRIXx Help*.

Comparative Analysis: plot() versus plot2d()

		Advantage	-
			-

Feature	Advantage			
3D Plotting	plot() supports 3D lines and surfaces, and also 2D and 3D contour plots. The plot2d() function does not support 3D or contour plots.			
Polar Plots	plot() supports polar coordinate plotting. To display polar plots, plot2d() users must write their own conversion script.			
Graph Object	The graphic result of a plot function can be saved to a variable. plot2d() does not support graph objects.			

Table 4-1. plot() Advantages

Feature Advantage **Data Viewing** plot2d() has the capability of displaying (X,Y) data values of curves in a pop-up window interactively activated by the right mouse button (RMB). Callbacks plot2d() callbacks can be attached to curves/sub-areas for click/drag/release with modifiers. The callbacks are implemented using MathScript. Variable By binding a variable to a plotted curve, the plot2d() plots are updated as Binding the variable changes. This is a superior to the plot () method of achieving animated display. Polygons plot2d() has polygon plot capability. plot() does not support 2D polygon plots. Hierarchy By specifying hierarchy paths, selected elements of plot2d() plots can be Selection addressed for setting/changing attributes. Plot Inclusion A plot2d() sub-area can be made to include a plot from some other window. It is useful for displaying a single post-stamp sized element of a large row/column plot. Any changes are updated automatically. Drivers Setting generic Hoops options such as driver options, heuristics, visibility and frame are available in plot2d().

Table 4-2. plot2d() Advantages (these features also available with uiPlot)

Plotting Commands and Special Purpose Functions

Several additional commands and functions are used with the general purpose Xmath plotting functions. Brief descriptions are given here. Some are discussed in more detail later in this chapter. For more information, refer to the *Xmath*, *Plotting* topic of the *MATRIXx Help*.

colorind

The colorind function creates a colorindex matrix used as a fourth argument with the plot function to add color emphasis or a fourth dimension to 3D plots.

ERASE

The ERASE command can be used to erase the contents of the **Xmath Graphics** window (plot function display).

HARDCOPY

The HARDCOPY command is used to create a hardcopy of the contents of the **Xmath Graphics** window (plot function display), or a graphics object (plot function display). It can also be used to create hardcopy of plot2d results.

pdmplot

The pdmplot function invokes a dialog box-driven process resulting in plots selected from a specified pdm. It can be used with either the plot or the uiPlot plotting system.

qplot

qplot is a simple uiPlot based function. Like plot2d, it provides use of uiPlot features with a pre-programmed GUI. However, qplot does not support plot and other high-level keyword capabilities of plot2d.

uiPlotArea

uiPlotArea is a programmable GUI function for creating uiPlotArea widgets.

uiPlotGet

uiPlotGet is a programmable GUI function for getting the current cursor position to be used with callback routines.

Using the plot() Function

The plot () function creates 2D and 3D plots from data; complex components (those containing imaginary elements) are ignored. You can call plot () with any one of the following syntaxes:

```
graphObj = plot(y, {keywords})
graphObj = plot(x,y, {keywords})
graphObj = plot(x,y,z, {keywords})
graphObj = plot(x,y,z,colorindex, {keywords})
graphObj = plot()
graphObj = plot((keywords))
graphObj = plot(graphObj, {keywords})
```

If you need to plot complex data, you can make a real versus imaginary cartesian graph. Given complex data z, call plot (real (z), imag(z)).

In the preceding plot syntaxes, x is a vector or matrix; y is a vector, matrix, or PDM; and z is a vector or matrix. If z is a matrix, a color index matrix colorindex can be supplied to add color as a fourth dimension. Each syntax is discussed in the following sections.

An existing graph object can be reused as an input in several ways; it can be altered with keywords or combined with another plot to create a new image.

An optional graph object can be included as an input for one, two, or three input plots. If the data is compatible, the new data is overlaid on graphObj, and the modified graph is returned as a graph object from plot(). However, a graph object can also be referenced with the keep or copy keywords. The keep keyword is preferable because it is fastest. In either case, you can reference a single graph object. You can not specify keep and the optional graph object input in the same call.

If you input the following data, you can test each syntax in the sections that follow:

```
# define vectors for plotting
v=[0:.25:30]';
vc=v.*cos(v); vs=v.*sin(v);

# define a PDM

ypdm=pdm([vc,vs]);

# define matrices for plotting
x=[vc,vc]; y=[vs,vs]; z=[1.5*v,1.5*v];
vm=vs*vc';
m=v*v';
ms=[vs,-vs];
mc=[vc,-vc];
```

Plot One Input

For a single argument the syntax is plot (y):

- If y is a vector with m elements, then y is plotted versus the vector 1:m.
- If y is an $m \times n$ matrix, then each column of y is plotted versus the vector 1:m. The result is n curves, each with m points.

```
plot(vm)?
```

If y is an m × n × d PDM where m × n is the size of each dependent matrix, and d is the length of the domain (the independent parameter), then m × n curves of d points are drawn, each versus domain (y). Therefore, each line corresponds to a channel of a PDM. Refer to the PDM Channels section of Chapter 5, Data Objects and Operators:

```
plot(pdm([vc,vs]))?
```

Plot Two Inputs

The syntax for two arguments is plot (x, y):

- If x and y are vectors of the same length, then y is plotted against x: plot (vs, vc)?
- If x is an m x 1 or 1 x m vector and y is an m x n matrix, each of the n columns of y is plotted against x on a single graph. Each curve has m points:

```
plot (vs,m(:,1:7:length(vs)))?
```

• If x and y are both $m \times n$ matrices, then n curves are drawn, each consisting of a column of y versus the corresponding column of x:

```
plot (m, vm)?
```

Plot Three Inputs

The syntax for three arguments is plot(x, y, z):

• If x, y, and z are vectors of the same length, then z is plotted versus x and y as a curve in space:

```
plot (vc, vs, v/3)?
```

• If x is an $m \times 1$ or $1 \times m$ vector, and y is $n \times 1$ or $1 \times n$, and z is an $n \times m$ matrix, then z is plotted as a surface versus x and y:

```
plot (vc(1:50), vs(1:50), vm(61:110,61:110), {!grid})?
```

• If x, y, and z are matrices of the same dimensions, then z is plotted versus x and y as a surface in space:

```
plot (mc, ms, z, {!grid})?
```

Color as a Fourth Dimension

If inputs x, y, and z are supplied and z is a matrix, then you can pass a fourth argument to use color to represent an additional dimension over the data surface. In the following example, the fourth argument is a matrix the same size as z generated by the colorind() function (a colorindex matrix). The values specified with the face_color keyword are applied to the data surface at the locations in the colorindex matrix:

```
v=[0:.25:30]';
x=v.*sin(v);
y=x;
z=vs*-vs';
z=z(31:60,31:60);
g1=plot(x(1:30),y(1:30),z,colorind(z),{face_color=9:19})
```

Creating and Displaying a Graph Object

This section discusses common plotting approaches. Keywords mentioned here are discussed in detail later in this chapter.

Graph object output is handled like any other function output, except that it is displayed in the **Xmath Graphics** window rather than to the log area. When no output is assigned, the graph is written to the default object ans.

It is a good practice to use the ? terminator with plot (), regardless of how you call it: interactively, in executable files, or in MathScript entities. This is particularly important when plots are developed in a .ms file. By default, set echo is off when files are executed so Xmath displays only graphs with the ? terminator.

The keep keyword, which is also discussed in the *Adding New Data to Existing Plots (keep, copy)* section, combines an existing graph object and any new information. If the plots are compatible, the new information becomes part of the specified graph. For example:

```
v=[0:.05:5];
plot(v.*sin(v),{title="The first curve."})?
plot(-v.*cos(v),{keep,title="The second curve."})?
```

The second curve is plotted over the first; notice that plot () recognized there was already a title and substituted the newest one. You can still add to the graph, and this time name the output:

```
final=plot({ keep, xlog, xmax=100, title="The Final Graph",
legend=["1st curve","2nd curve"]})?
```

If saving a graph to a variable is an afterthought, you can capture the current image in the **Xmath Graphics** window by selecting **File»Bind to Variable** from the **Xmath Graphics** window menu bar or by calling plot () with no arguments:

```
g2=plot() # name current graph object g2
```

Both File»Bind to Variable and Variable=plot() do the same thing as Variable=plot({keep}).

Once a graph object is assigned to a variable, it can be saved to a file and then loaded and displayed at a later time. Rather than creating an executable file that recreates the graph, you can archive the images themselves.

Using Keywords with plot

Every call to plot () can have a list of keywords that modify the appearance of the plot. Almost everything that can be done using keywords can be done interactively with tools available from the **Xmath Graphics** window menus and the **Xmath Palette**. Keywords, however, are convenient because they provide command-line control of graphics modifications. This implies that plot instructions can be saved to and retrieved from a diary file or built up independently in a MathScript file. Also, a keyword string may be aliased to a shorter string.

 Plot keywords, as shown in Table 4-3, are used like any other keywords. As a reminder, though, the type of information dictates how the keyword is implemented.

Keyword Type	Input Samples		
Boolean	{!legend}, {!axisfix}		
integer	{rows=5}, {line_color=12}		
vector	{scale=[.5,.5],line_color=2:24}		
string	{title="My Beautiful Graph"}		
vector of strings	{legend=["input 1","input2"]}		

Table 4-3. Keyword Types

For Boolean scalars, note that a nonzero value denotes TRUE/on, while 0 denotes FALSE/off. For example:

```
plot({grid,marker})  # grid and marker are on
plot({!grid,!x_lab})  # grid and x lab are off
```

- If you use the hold keyword, the keyword settings remain until you redefine an attribute, until you use !hold, or until you call plot({reset}) (refer to the *Hold Keyword* section).
- You can use the negative operator ! to set a keyword to FALSE or 0. For example, you can use either !grid or grid=0 to turn off all grid marks while grid=1 enables them.

The *Using Keywords with plot* section discusses keywords in functional groups as shown in Table 4-4, using examples to illustrate how they work. Each keyword description gives its default setting.

Table 4-4. Keyword Categories

Category	Section		
Labels and legend	Labels and Legend		
Colors	Colors		
Line and marker specifications for data	Line and Marker Specifications for Data		
Multiple graphs and graph positioning	Multiple Graphs and Graph Positioning		
Adding new data to existing plots (keep, copy)	Adding New Data to Existing Plots (keep, copy)		
Axis and zero lines	Axis and Zero Lines		
Tics and grids	Tics and Grids		
Free text and global text settings	Free Text and Global Text Settings		
Axis limits and logarithmic scaling	Axis Limits and Logarithmic Scaling		
Animate	Animate		
Placement, scaling, and rotation	Placement, Scaling, and Rotation		
Background, edge, and face settings	Background, Edge, and Face Settings		
Lighting source settings	Lighting Source Settings		
Holding graph attributes	Reusing plot Attributes and Hold Keyword		

 Table 4-4.
 Keyword Categories (Continued)

Category	Section
Strip plots	Strip Plots
Bar plots	Bar Plots
Contour plots	Contour Plots
Polar plots	Polar Plots

An alphabetized list of all keywords and the location of each appears in Table 4-5.

Table 4-5. Plot Keywords (Alphabetized Listing)*

Keyword	Section	Keyword	Section	Keyword	Section
animate	Animate	line_width	line_width	x_axis_ fix	axisfix x_axisfix y_axisfix z_axisfix
axis	Labels and Legend	log	log	x_axis_l ine	x_axis_line y_axis_line z_axis_line
axix_fix	axisfix x_axisfix y_axisfix z_axisfix	marker	marker	x_grid	x_grid y_grid z_grid
axis_ linea	axis_line	marker_ color	marker_color	x_inc	x_inc y_inc z_inc
bar	Bar Plots	marker_ size	marker_size	x_lab	x_lab
bg_color	bg_color fg_color	marker_ style	marker_style	x_log	x_log y_log z_log
colormap	<pre>mapDefault=plot({color map})</pre>	move	move	x_max	x_max y_max z_max
column	column	polar	polar	x_min	x_min y_min z_min
columns	columns	position	position	x_tic	x_tic y_tic z_tic
contour	contour contour2d	projection	projection	x_tic_ lab	x_tic_lab y_tic_lab z_tic_lab

Table 4-5. Plot Keywords (Alphabetized Listing)* (Continued)

Keyword	Section	Keyword	Section	Keyword	Section
contour2d	contour contour2d	r_inc	r_inc	x_zero_ line	x_zero_line y_zero_line z_zero_line
contour3d	contour3d	r_max	r_max	y_axis	x_axis y_axis z_axis
contour_ interval	contour_interval	reset	reset	y_axis_f ix	axisfix x_axisfix y_axisfix z_axisfix
сору	copy	rotate	rotate	y_axis_ line	x_axis_line y_axis_line z_axis_line
date	date	row	rows	y_grid	x_grid y_grid z_grid
edge	edge	rows	rows	y_inc	x_inc y_inc z_inc
edge_ color	edge_color	scale	scale	y_lab	y_lab
edge_ style	edge_style	strip	Strip Plots	y_log	x_log y_log z_log
edge_ width	edge_width	text	text	y_max	x_max y_max z_max
face	face	text_angle	text_angle	y_min	x_min y_min z_min
face_ color	face_color	text_color	text_color	y_tic	x_tic y_tic z_tic
face_ style	face_style	text_font	text_font	y_tic_ lab	x_tic_lab y_tic_lab z_tic_lab
fg_color	copy	text_ position	text_position	y_zero_ line	x_zero_line y_zero_line z_zero_line
graph_ number	edge_width	text_style	text_style	z_axis	x_axis y_axis z_axis

Keyword Section Keyword Section Keyword Section grid grid text_size text size z_axis_f axisfix ix x_axisfix y_axisfix z_axisfix hold hold theta_inc theta_inc x_axis_line z_axis_ line y_axis_line z axis line keep keep theta_max theta_min z_grid x_grid theta max y_grid z_grid keepsubpl keepsubplot theta min theta min z inc x_inc y_inc theta_max $z_{\perp}inc$ legend 1egend tic z_1ab tic z_lab light light tic_lab tic_lab z_log $x_log y_log$ z 10g light_color light_ tic maj tic_maj x_max y_max z_max color z_{max} light_ light direction tic_min tic_min z_min x_min y_min direction z min line line time time z tic x tic v tic z tic line line_color title title z_tic_ x_tic_lab color lab v tic lab z_tic_lab line line_style x_zero_line x_axis x_axis y_axis z_zero_ style line z axis y_zero_line z_zero_line * Underscores are always optional. For example, both x_axis and xaxis are acceptable.

Table 4-5. Plot Keywords (Alphabetized Listing)* (Continued)

Labels and Legend

Labels allow you to place a text string in a specific location relative to the plotted data. Labels are therefore bound to the plot and their locations cannot be changed.

The keywords legend, date, and time also place text on the graph, but you can move these small text objects with the mouse. To create "independent" text, use the text keywords, or create free text interactively. Table 4-6 summarizes the labels and legends.

Table 4-6. Label and Legend Keywords

Keywords	Description
title	String for the graph title above the plot. Default is an empty string.
x_lab	String for the x-axis label. Default is an empty string.
y_lab	String for the y-axis label. Default is an empty string.
z_lab	String for the z-axis label. Default is an empty string.
date	Places the date in the upper left corner; format is: dayName_month_date_year . Default is an empty string.
time	Places the time in the upper left corner. Format is hour_minutes_seconds on a 24 hour clock. Default is an empty string.
legend	For multi-line or contour plots, you can specify a vector of strings naming each line or contour, for example, <code>legend =["Time", "Speed"]</code> . The default labels for 2D plots are the line number followed by the corresponding line style (and color, for color monitors). For 3D plots, the default legend corresponds to differing surface styles.

Tic labels (numbers corresponding to major tic marks) are discussed in the *Tics and Grids* section.

The example that follows creates 3D data and then creates the contour graph shown in Figure 4-1. All axis information is negated so that you can clearly see every label (negating axis information is optional). Note the string of vectors used to label the legend. There are four intervals in this contour, and this vector of strings provides new labels for only the first and last; the default label is displayed for intervals where the null string " " is specified.

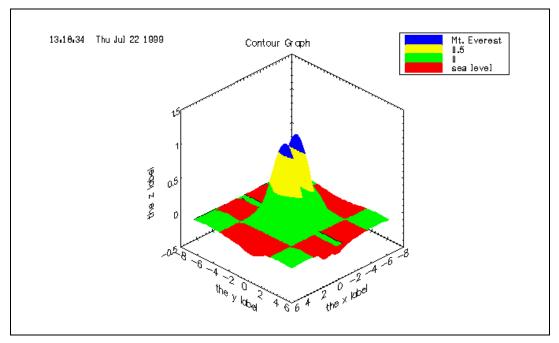


Figure 4-1. Label Locations and Legends

Colors

Many keywords take a color as an argument. You can specify colors by number or name, and a vector of color names or numbers is acceptable. You can see the current colormap on the **Xmath Palette**. On color monitors, up to 64 colors can be allocated.

If a value is specified (an integer between 1 and 64), Xmath indexes into the current colormap.

If a color name is specified, Xmath searches for a match in the following tables in the following order:

- The currently installed Xmath colormap.
 For black and white systems, the current colormap represents black, six shades of gray, and white. On color systems, each row in the colormap is a color. The first column represents red intensity; the second, green intensity; and the third, blue intensity.
- 2. On UNIX systems, the X11 color name database, often stored in /usr/lib/X11/rgb.txt.

This is a very long list.

3. The list of supported Xmath color names, which are listed in Table 4-7.

The first eight colors on this list compose the default sequence for line.

The first eight colors on this list compose the default sequence for line and marker colors. The first color is black or white, depending on the background color, followed by red, green, yellow, blue, magenta, cyan, and black or white.

If you use strings to specify these colors, spacing must be typed as shown, but case is not important. For example:

```
plot(x, {bg_color="CADET BLUE",fg_color=51})
```

4. The list of default (built-in), machine-dependent color names.

As soon as a name match is found in one of the locations above, Xmath looks at the corresponding values, compares them to values in the current colormap, and then implements the closest color available in the current colormap.

To supply your own colormap, construct an $n \times 3$ matrix with values representing red, green, and blue intensity ranging from 0 to 1. Before installing your color map, it is a good idea to save the default color map:

```
mapDefault=plot({colormap})
```

This saves the colormap to the variable mapDefault.

To replace the current colormap with your own mapMyColors, type: plot({colormap=mapMyColors})

Your colormap now appears in the **Xmath Palette** as the current colormap.

For more on colormaps, refer to the *Color List*, *Colormaps*, and *Setting Colors* topics in the *MATRIXx Help*.

 Table 4-7.
 String Color Names for Xmath Supported Colors

No.	Name	No.	Name	No.	Name
1	black	22	chris cyan	43	aliki aqua
2	red	23	periwinkle	44	cyan
3	green	24	prussian blue	45	cerulean
4	yellow	25	cadet blue	46	big blue
5	blue	26	kam blue	47	lapis
6	magenta	27	royal purple	48	blue
7	cyan	28	red violet	49	marine blue
8	white	29	mulberry	50	violet
9	silly putty	30	orchid	51	mark magenta
10	peach	31	maroon	52	purple
11	salmon	32	strawberry	53	fuchsia
12	brick	33	fire engine red	54	berry
13	kin orange	34	orange	55	raspberry ron
14	burnt umber	35	pumpkin	56	red
15	brown	36	golden dawn	57	black
16	coffee	37	yellow	58	gray5
17	mustard	38	lemon yellow	59	gray4
18	neon green	39	light green	60	gray3
19	forest green	40	algae	61	gray2
20	teal	41	grant green	62	gray1
21	ocean green	42	new grass	63	gray0
				64	white

The following keywords dictate color changes for different plot elements:

- bg_color
- edge_color
- face_color
- fg_color
- grid_color
- light_color
- line_color
- marker_color
- text_color

The meanings of these keywords are discussed elsewhere within the keyword functional groups.

Line and Marker Specifications for Data

You can change the color, style, and width for lines (for example, curves) of data as specified in Table 4-8. If you make changes to lines and specify the legend keyword, your changes are reflected in the legend.

Table 4-8. Line Specification Keywords

Keyword	Description
line	Boolean that turns line plotting on or off. Default=1.
line_color	Integer, string, vector of integers, or vector of strings for specifying data line colors (refer to the <i>Colors</i> section). If line_color specifies a vector, the given color sequence is cycled through. On color monitors for plots with multiple curves, Xmath automatically assigns each curve a different color.
line_width	Any float is accepted. The variety of line widths allowed is machine dependent; if you specify a value the machine can not provide, it supplies the closest thing. The default value of 1 is approximately equal to one pixel on your monitor. On a high resolution monitor, the difference between .5 and 1 may be visible. On others, the output might be the same.

Table 4-8. Line Specification Keywords (Continued)

Keyword	Description			
line_style	Integer, vector of integers, string, or vector of strings that specify line styles for each curve on the graph. The line_style mapping is:			
	Integer String			
	0	11 11		
	1	""		
	2	" "		
	3	""		
	4	""		
	5	""		
	6	""		
	7	""		
	_	rle is set to a vector of integers, strings, or names, Xmath cycles pecified sequence of styles.		

The following example generates several line styles and widths; the plot appears in Figure 4-2:

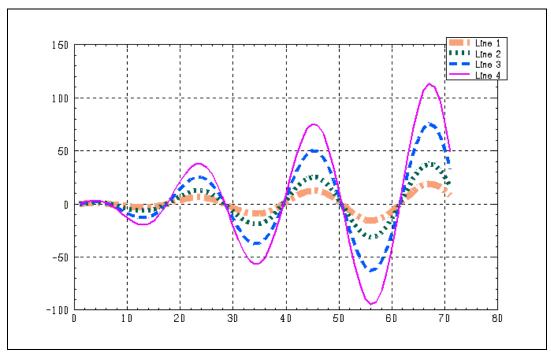


Figure 4-2. Line Styles and Widths

Markers, as described in Table 4-9, are symbols plotted at each data point. You can change a marker's size, style, or color using integers, floats, or strings the same as you do with line styles. To see a plot with only markers, use the keywords {!line,marker}.

Table 4-9. Marker Specification Keywords

Keyword	Description
marker	Boolean that turns on/off plot markers. Default = 0.
marker_color	Integer, vector of integers, string, or vector of strings that specifies marker color (refer to the <i>Colors</i> section). You can specify an integer or string for each curve on a graph. If a vector is specified, the color sequence is cycled through.
marker_size	Any nonzero float is accepted. The range of marker sizes allowed is machine-dependent; if you specify a value the machine cannot provide it will supply the closest thing. The default value is 0.5.

 Table 4-9.
 Marker Specification Keywords (Continued)

Keyword	Description		
marker_style	Integer, vector of integers, string, or vector of strings that specifies marker style for each curve on the graph. The marker style mapping is:		
	Integer	String	Style
	0 1 2 3 4	"*" "X" "+" "0"	no markers asterisks x's crosses circles
	5 6 7 8 9 The default mar	•	filled circles squares filled squares triangles filled triangles vector of marker styles is specified, they

You can use a combination of line styles and markers to expand the number of unique lines you can plot. This is especially valuable for those using black-and-white monitors or for complicated plots that will be printed in black and white.

The final result, shown in Figure 4-3 shows some of the line and marker styles in a variety of widths and sizes. Normally hold and axisfix need to be turned off with !hold and !axisfix, but plot({reset}), which resets everything, is used in this example.

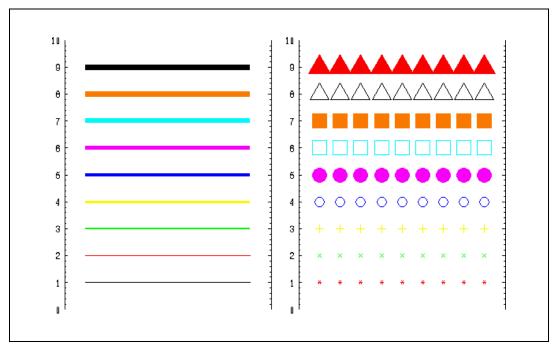


Figure 4-3. Line and Marker Styles with Varying Widths and Sizes

Multiple Graphs and Graph Positioning

The keywords shown in Table 4-10 allow you to place more than one plot in the **Xmath Graphics** window. If you are displaying multiple graphs, you can ensure that they are the same size by dividing the window into rows and/or columns and then positioning the graphs with row and column coordinates or graph number. You cannot rotate or zoom plots with multiple graphs interactively.

Keyword	Description
column	Integer specifying the column position of the graph. Default= 1.
columns	Integer specifying how many columns the plot window is divided into. Default = 1.
row	Integer specifying the row position of the graph. Default=1.

Table 4-10. Graph Specification Keyword

KeywordDescriptionrowsInteger specifying how many rows the plot window will be divided into. Default = 1.graph_numberInteger specifying alternate representation for row and column in a multi-graph plot. For rows=m and columns=n, the "cells" are numbered from 1 to m×n going across the rows and then down the columns. Thus, for rows=2 and columns=2, graph_number=3 is equivalent to row=2, column=1.

 Table 4-10.
 Graph Specification Keyword (Continued)

Notice that the keywords row, rows, column, and columns all default to 1. Therefore, you do not need to specify row=1 or column=1 because Xmath attempts to place graphs in these locations by default. The keywords rows and columns are *initiators*. If they are used in a plot() call, the row/column setting remains in effect for subsequent plots that use the keywords row, column, or graph_number. If a plot is called that does not contain row, column, or graph_number, the default format ({rows=1,columns=1}) is reset.

The following example places six graphs in the window; the final plot appears in Figure 4-4.

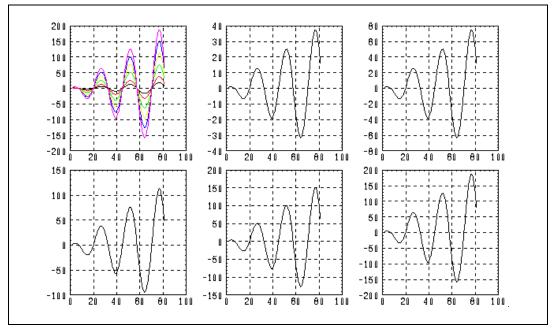


Figure 4-4. Plots Placed with row, column, and graph number Keywords

Adding New Data to Existing Plots (keep, copy)

Xmath has two ways of storing the image in the **Xmath Graphics** window in a variable. The keywords keep and copy described in Table 4-11 both use the contents of the **Xmath Graphics** window, but they may affect previously saved variables differently.

Keep combines the attributes and data from your current plot call with the current contents of the **Xmath Graphics** window and updates the variable. Keep is best used when you are building a plot by overlaying data or adding attributes to an existing plot. Because keep uses whatever is in the **Xmath Graphics** window, Xmath keeps changes you make with interactive tools automatically.

If you create a graph object g1 and later create a graph object g3 that keeps g1, a common incorrect perception is that g1 has the old view and g3, the new. In reality, both variables point to the same graph object. You can test this as follows:

```
v=[1:.25:30]';vs=abs(v.*sin(v));vm=vs*vs';
q1=plot(vs,v)
```

```
g2=plot(vs(1:30),vs(1:30),vm(61:90,61:90))
g3=plot({keep=g1,log})
q1
```

where g1 and g3 are the same.

As long as the data dimensions allow it, Xmath performs any keep you specify. For example, you can combine a 2D and 3D plot. The following example uses the keep keyword to specify a 2D plot and provides the 3D information internally:

```
plot(vs(1:30),vs(1:30),vm(61:90,61:90),{!grid,keep=g3,
    ylab="The Y label",xlab="The X label",
    zlab="The Z Label"})
```

If you want to re-use a graph object but you do not want it to be altered, use the keyword copy instead of keep. Refer to Table 4-11 for these keyword descriptions. For example, g1 and g2 remain different in this case:

```
g2=plot({copy=g1,legend})
g1
```

Copying is computationally expensive, but it means you can save each stage when building a plot.

Table	. / 11	Data	Keywords
Lanie	: 4-11	. Data	Keywords

Keyword	Description
keep	Specifies that the current plot should be added to the specified graph object. If no graph object is specified, the plot is combined with the current contents of the Xmath Graphics window. If the graphs are incompatible, the new plot overwrites the Xmath Graphics window.
keepsubplot	Boolean. Used with keep when adding or replacing data on a subplot. keepsubplot indicates that new data should be laid over the existing data on the subplot. !keepsubplot indicates that the subplot should contain only the new data. Default is 1.
сору	copy can be specified with a graph object argument {copy = GraphObj}; if no graph object is specified, the plot is combined with the current contents of the Xmath Graphics window. copy differs from keep in that copy does not alter the original graph object. In this case, the new data and graph keywords are combined with a copy of the existing graph object. The combined graph object is returned, while the copied graph object remains unchanged.

Figure 4-5 shows an example created by combining graph objects through the sequence of inputs below. By default, if graph objects with different data ranges are combined, Xmath rescales the plot to accommodate all the data. As you create each plot below, notice how the axes change to accommodate the new data with each curve addition.

```
v=[0:.25:20]; vc=v.*cos(v);vs=v.*sin(v);
plot({title="You can add to a graph as you work!"})?
plot(vc,{keep})?
plot(vs,{keep})?
plot(-vc,{keep})?
plot(-vs,{keep})?
g=plot({keep,!grid,legend=[" vc"," vs","-vc","-vs"]})?
```

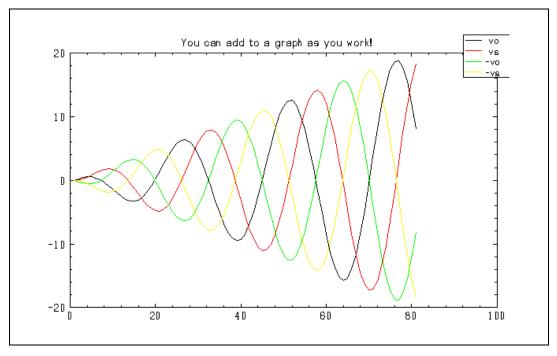


Figure 4-5. Combination of Graph Objects

If you do not want the plots rescaled, you must specify one of the axisfix keywords. Refer to Table 4-12.

Axis and Zero Lines

The keywords described in Table 4-12 control axis and zero-line display.

Table 4-12. Axis and Zero Line Keywords

Keyword	Description
axis	Boolean that turns on or off all axis graphics on the entire graph. This includes grids, zero lines, tic marks, and tic labels. If an attribute is specified, it is applied to all axis graphics.
x_axis y_axis z_axis	Booleans that toggle all axis graphics on the x, y, or z axis. Axis graphics color, style, and width attributes affect all components on the named axis.
axisfix x_axisfix y_axisfix z_axisfix	Booleans that toggles automatic axis scaling when graph objects are combined. Default = 0 (autoscaling on). If axisfix=1, axis limits are those of the kept graph object.
axis_line	Boolean that toggles lines for all axes. Default = 1.
x_axis_line y_axis_line z_axis_line	Booleans that toggle axis line for the x, y, or z axis, respectively. Default=1.
zero_line	Boolean that toggles zero lines on all axes. Default = 0.
x_zero_line y_zero_line z_zero_line	Booleans that toggle zero lines on the x , y , or z axis, respectively. Default = 0 .

The following call produces the zero lines and axes for 2D and 3D plots shown in Figure 4-6. This demonstrates axis and zero lines in 2D and 3D plots.

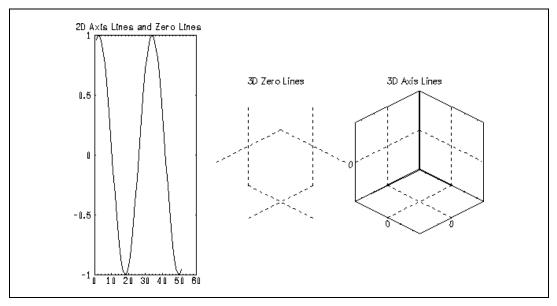


Figure 4-6. Zero Lines and Axes for 2D and 3D Plots

Tics and Grids

Tics and grids appear by default on all plots. You can suppress these features on one or more axes. Table 4-13 describes the keywords grid, tic, and tic_lab, which are especially useful because they control all axes.

Table 4-13. Tic and Grid Keywords

Keyword	Description
tic	Boolean that toggles tic marks on all axes. Default = 1.
tic_maj	Boolean that toggles major tic marks on all axes. Default = 1.
tic_min	Boolean that toggles minor tic marks on all axes. Default = 0.
x_tic y_tic z_tic	Booleans that toggle tic marks on the x, y, or z axis, respectively. Default = 1 .
x_inc y_inc z_inc	Integers specifying the major tic increment for the x, y, or z axis, respectively.
tic_lab	Boolean that toggles tic mark numbering on all axes. Default = 1.

Table 4-13. Tic and Grid Keywords (Continued)

Keyword	Description
x_tic_lab y_tic_lab z_tic_lab	Booleans that toggle tic mark numbering on the x, y, or z axis, respectively. Default = 1.
grid	Boolean that toggles all grids. Default = 1.
grid_color grid_style grid_width	Grid color, style, and width attributes can be changed for the entire graph. Colors are specified as described in the <i>Colors</i> section. Line styles and widths are specified as described in the <i>Line and Marker Specifications for Data</i> section.
x_grid y_grid z_grid	Booleans that toggle the x , y , or z grid, respectively. Default =1.

The following instructions produce the changing tic and grid setting shown in Figure 4-7.

```
v=[[1:.15:15],[15:-.15:1]];
vc=[v.*cos(v)];vs=[v.*sin(v)];
vc5=vc.*.[ 2;2.5;2.75;2.5;2];
vs5=vs.*.[ 1;1.5;2;1.75;1.25];
plot(-vc5,vc5,vs5,{yinc=30,xinc=15,!zgrid})
```

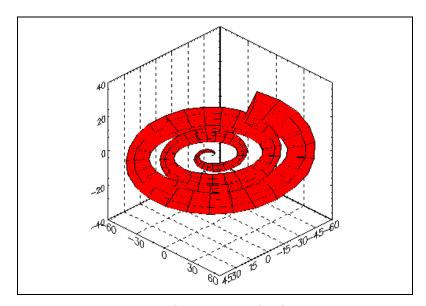


Figure 4-7. Changing Tic and Grid Settings

Free Text and Global Text Settings

The text keyword places a single string onto the plot. You can alter the angle, color, font, position, size, and style of the string with keywords. Refer to Table 4-14).

The text keyword loosely corresponds to the interactive free text feature. If you want to add more than one text string to a plot or show a variety of text styles, you can work on the plot interactively or combine several plots with the keep keyword. Text keywords do not affect text associated with the data, such as labels and titles. You can change these interactively or, in the case of labels, with keywords.

Table 4-14. Free Text and Global Text Keywords

Keyword	Description		
text	String containing the text to be written on the plot.		
text_angle	Vector of three float numbers [x,y,z] specifying the angle of the text's clockwise rotation about the axis.		
text_font	Integer or a string from the following:		
	Integer String		
	1 "simplex" 2 "duplex" 3 "triplex" 4 "complex" 5 "script" 6 "greek" 7 "times" 8 "helvetica" 9 "courier" Fonts 1 through 6 are Hershey fonts, while fonts 7, 8, and 9 are PostScript fonts. The default font (font = 8) is Helvetica. If your platform is not be able to create the font you want in the size you		
	want, it attempts to supply the closest thing.		
text_color	Integer or string indicating the color name. Specifies the color for all text in the graph. Default = "black". Refer to Table 4-7.		

Table 4-14. Free Text and Global Text Keywords (Continued)

Keyword	Description
text_position	Vector of two float numbers $[x,y]$ used to place a line of text anywhere in the Xmath Graphics window. The upper left corner of the text line is placed at the specified position. When first drawn, a plot extends from -1 to $+1$. Note that any float is acceptable, so it is possible to position the text outside the viewport. If you do, it may seem as though the string was not created; you must zoom out to view the text. Default = $[0,0]$.
text_size	Floating-point number specifying the size in points. One point is about 1/72 inches.
text_style	Integer or string indicating the text style: Integer Font 1 "plain" 2 "bold" 3 "italic" 4 "bold italic" Default = 1 (plain).

The following example uses text keywords; it produces the plot shown in Figure 4-8. Notice that text_position and position work on the same principle.

```
v=[0:.5:25]'; vc=v.*cos(v); vs=v.*sin(v); vm=vs*vc';
plot(v,v,vm)
plot({keep, scale=[.9,.9],position=[-.4,0],
    x_inc=5,y_inc=10,
    text="Text is placed with "ntextposition"+...
    ""n and textangle.",
    text_font=3,text_size=14,
    text_angle=[0,0,30],
    text_position=[.1,-.7]})
```

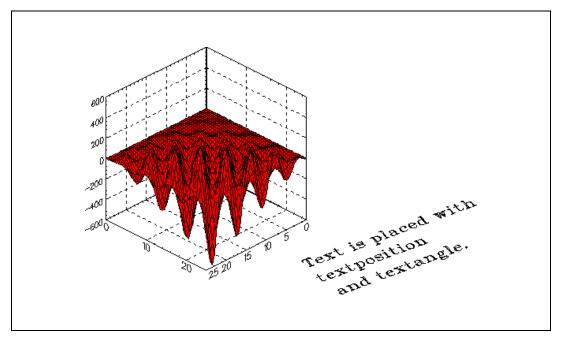


Figure 4-8. Text Changes and Text String Placement

Axis Limits and Logarithmic Scaling

You can change the actual scaling of the data (to log scale, for example). You can also specify the minimum and/or maximum range of data you want to see on any dimension. Refer to Table 4-15 for the pertinent keyword descriptions.

Table 4-15. Axis Limits and Logarithmic Scaling Words

Keyword	Description
log	Turn on/off log scaling for all axes. Default = 0.
x_log y_log z_log	Turn on/off log scaling for the specified axis. Default = 0.
x_min y_min z_min	Integer indicating the minimum for the x, y, or z axis, respectively.
x_max y_max z_max	Integer indicating the maximum for the x, y, or z axis, respectively.
x_inc y_inc z_inc	Integer indicating the increment for the x, y, or z axis, respectively. For logarithmic axes, this value becomes multiplicative. This means that if the integer is greater than 1, it increases by multiples, and if it is less than 1, it decreases by multiples. So if $x_{inc} = 10$, tic values are 1,10,100, and so on. If $x_{inc} = 0.1$, values are 1,0.1,01, etc.

You can make an axis go backward by making the value of xmin greater than xmax as illustrated in the following example:

```
x=exp(.5:0.15:5);
plot(x,{x_log,rows=3,xmax=32})
plot(x,{keep,row=2,y_log,ymax=150})
plot(x,{keep,row=3,xmin=35,xmax=1,title="Reversed Scaling"})
```

The results appear in Figure 4-9.

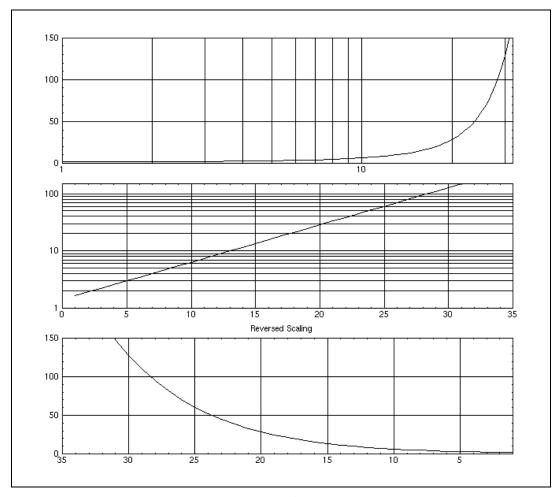


Figure 4-9. Axis Maximums and Minimums

Animate

The animate keyword allows you to plot new data without redrawing other parts of the plot. It is a Boolean used to show changes in data as quickly as possible for an animation effect between successive plots. The default is 0.

The following example plots a series of curves on the same axes. The first plot sets the dimensions of the plot; the second plot holds the dimensions of the first and specifies that only the data will be redrawn each time. The curves are plotted within a loop and then animate is turned off. Alternatively, plot({reset}) can be used to restore the original settings.

```
a=[0:20/75:20];a=a.*cos(a);
b=[10:-10/75:0];b=b.*sin(b); c=[a,b];
plot ({animate,ymin=-85,ymax=85,xmax=150});
for i=[[1:.25:5],[5:-.25:100]];
plot(c*i,{linestyle=1})?
endfor
plot({!animate})
```

Placement, Scaling, and Rotation

The placement, scaling, and rotation keywords operate on a graph as a whole. Refer to Table 4-16 for descriptions. This means scale changes reduce or enlarge the entire graph, including labels, and so forth. The keywords, rotate, projection, and position, also operate on an entire graph. You can use these keywords when plotting a single graph or multiple graphs. Refer to the *Multiple Graphs and Graph Positioning* section.

Table 4-16. Placement, Scaling, and Rotation Keywords

Keyword	Description
scale	Vector of two float numbers [x,y]. Each float indicates the amount of compression (float < 1) or expansion (float > 1) on the relevant x or y Xmath Graphics window coordinate. Default is [1,1].
rotate	Vector of three float numbers [x,y,z] specifying the angle in degrees of the rotation of a 3D plot. Assumes a right-hand coordinate system, based on the Xmath Graphics window axes (not the object coordinates). Rotations are performed counter-clockwise, first about the x-axis, then about the y-axis, then about the z-axis. Because this rotation is based on window coordinates (the current view), it may be simpler to rotate one axis at a time.
projection	String equal to one of the following string values: "stretched" Stretches the graph so that it fills as much of the plotting area as possible. This is the default projection for 2D graphs. "orthographic" Indicates a coscaled setting such that unit distances on all axes are equal. This is the default projection for 3D graphs.

Table 4-16. Placement, Scaling, and Rotation Keywords (Continued)

Keyword	Description
move	Vector of two float numbers [x,y] specifying the distance (in Xmath Graphics window coordinates) to move the object from its current position. [-1,-1] is the lower left corner, [1,1] is the upper right corner, and [0,0] is the center of the window.
position	Vector of two float numbers [x,y] specifying the Xmath Graphics window coordinates of the center of the graph object. Default is [0,0] (the middle of the window). [-1,-1] is the lower left corner, and [1,1] is the upper right corner.

The following example uses scaling, rotation, and projection, and the text_position keyword, which works much the same as position does. This example creates the projection shown in Figure 4-10.

```
x=[-2*pi:0.35:2*pi]';
x=[x;x];y=(x); z=sin(round(x))./x*(sin(y)./y)';
v=[0:.5:20]';vs=v.*sin(v);vm=vs*vs';
plot (x,y,z,{columns=2,scale=[1,.9],rotate=[-20,0,0],
projection="stretched"})?
g=plot (x,y,z,{keep,column=2,projection="orthographic",
text="Stretched and Orthographic Projections",
text_position=[-.35,-.9]})?
```

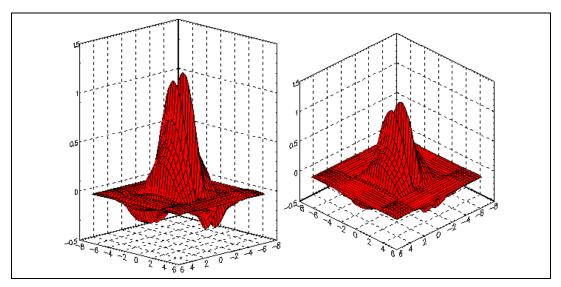


Figure 4-10. Stretched and Orthographic Projections

Background, Edge, and Face Settings

Table 4-17. Background, Edge, and Face Setting Keywords

Keyword	Description		
bg_color fg_color	Specifies the Xmath Graphics window background or foreground color. Accepts an integer or a string. Refer to Table 4-7.		
face	Boolean that turns surface filling on 3D surfaces or bar plots on or off. Default = 1.		
face_style	Changes the style on all faces. Specify an integer corresponding to the desired style from the following list:		
	Integer Face Style		
	0 none (default) 1 solid 2 cross-hatched pattern 3 vertical-line 4 horizontal-line pattern 5 left-slanting diagonal pattern 6 right-slanting diagonal pattern 7 dotted pattern 8 diamond pattern 9 square pattern Note: For black and white monitors, the face styles are only shown if the face color is black or white. If you specify a shade of gray and a face style, you only get gray.		
face_color	Specifies the color of 3D surfaces based on the z data values. Acceptable inputs are an integer, a vector of integers, a string, or a vector of strings. Refer to Table 4-7. If you specify a vector, Xmath cycles through the given sequence.		
edge	Toggles the display of web lines on 3D surfaces or bar plots. Default = 1.		
edge_color	Specifies the color of the web lines on 3D surfaces or bar plots. Acceptable inputs are an integer, a vector of integers, a string, or a vector of strings. Refer to Table 4-7. If you specify a vector, Xmath cycles through the given sequence.		

 Table 4-17.
 Background, Edge, and Face Setting Keywords (Continued)

Keyword		Description
edge_style	equivalent indi	of all web lines. This keyword accepts an integer or a string cating the border line type. solid line). Allowed values are:
	Integer	String
	0	н н
	1	""
	2	""
	3	"
	4	""
edge_width	Sets the width floating point r	of all web lines. This keyword, like line_width, accepts any number.

The following example displays a variety of edge and face specifications.

```
x=logspace(1,180,90);y=logspace(90,270,90);
z=45:134;
a=[-x;x;-x;x];b=[y;-y;-y;y];c=([z;z;z;z]);
plot(a,b,c,{edge_width=2,
    face_style=7,!grid,!axis,bg_color="gold",
    edge_color="black",face_color="cyan"})
```

The graph appears in Figure 4-11.

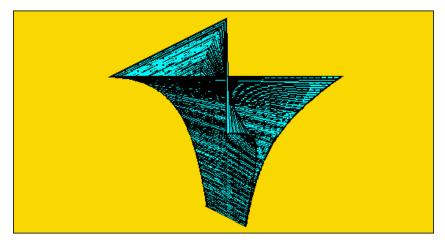


Figure 4-11. Edge and Face Styles

Lighting Source Settings

Table 4-18. Lighting Source Setting Keywords	Table 4-18.	Liahtina	Source	Settina	Kevwords
---	-------------	----------	--------	---------	----------

Keywords	Description
light	Boolean that turns light source on or off. Default=0.
light_color	Integer (color number) or string (color name) specifying light source color. Default = "white".
light_directi on	Vector of three real numbers [x,y,z] indicating the direction in which the light travels. Light source location is assumed to be infinitely far away. The default path vector is [1,–1,3].

Setting light = 1 for the plot shown in Figure 4-11 produces a very different graph as shown in Figure 4-12.

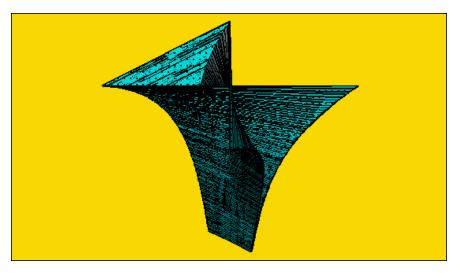


Figure 4-12. Edge and Face Styles with Light Added

Reusing plot Attributes

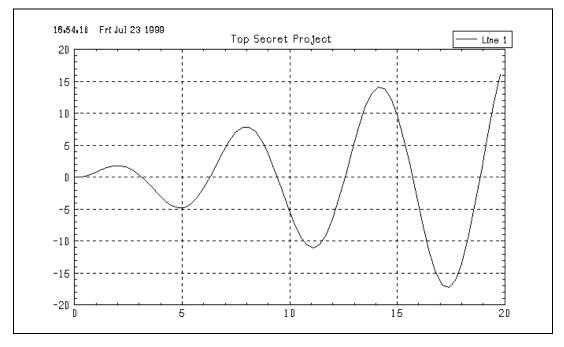
Hold Keyword

Table 4-19. Holding Graph Attributes

Keyword	Description
hold	Boolean. When {hold} is used with other keywords it makes them "permanent", applying them to all future graphs until hold is terminated with plot ({!hold}). Note that {!hold} removes keywords specified by the most recent hold. When you invoke hold in numerous plot calls, a hold stack is formed. You can specify a negative integer as an argument to hold ({hold =-n}) to remove the last n hold invocations from the hold stack. Use plot ({reset}) to clear the entire hold stack. (Default=0)
reset	Resets plot options to their startup values. Use this keyword alone, that is, plot({reset}).

You can use plot attributes, such as line widths, the legend, and titles, with the hold keyword, but you cannot use plot types (strip, bar, contour, and polar) with hold. When you use an attribute with the hold keyword, it replaces the current default. The following example uses the hold stack:

You can see the results of each of these four plots in Figure 4-13 and Figure 4-14.



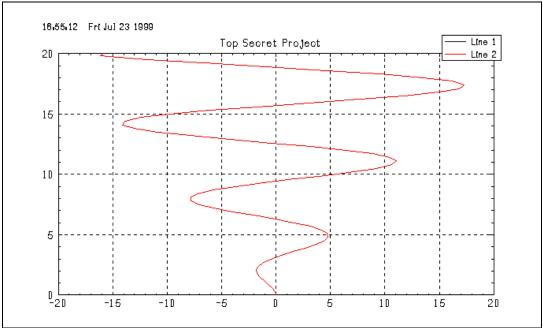
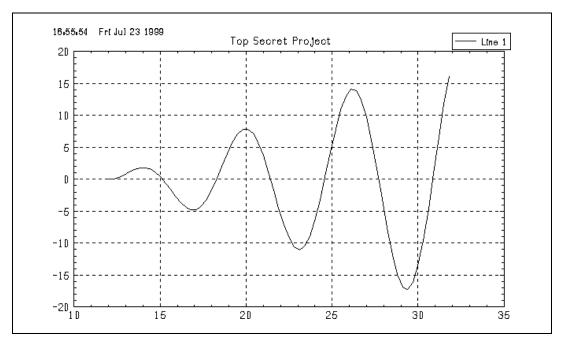


Figure 4-13. Results of First and Second plot Commands Using hold



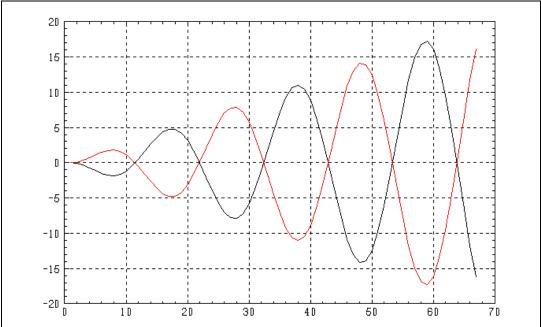


Figure 4-14. Results of the Third and Fourth plot Commands Using !hold

Using an Alias in the Keyword String

Another way to reuse plot attributes is to create an alias. You then can use the alias in the keyword string. An advantage of using an alias is that the defaults are not affected. You can store the aliases you use frequently in your startup.ms file.

You can obtain the results achieved with the hold keyword with an alias:

alias XX time,date,
plot([-vs,vs],{XX})

title="Top Secret Project",scale=[1,.95], legend

This example reproduces the fourth plot command as shown in Figure 4-14.



Note The rows and columns keywords are a special case and cannot be explicitly used with the hold keyword. Because they are initiators, they are automatically held until a plot call is made that does not contain the row or column keyword.

Strip Plots

The strip keyword is an integer indicating the number of data lines to be plotted on each strip plot in a given set.

The default is 1; Xmath plots one strip per channel or column of data for up to 10 strips. After 10, strip adds data to the existing strips.

If a value n is specified, Xmath creates strip plots with n data lines per strip plot. If the number of lines is not evenly divisible by n, the data lines corresponding to the remainder are lost.

Xmath creates strip charts such that the first data line appears on the first strip chart, the second appears on the second strip chart, and so on until each strip in the first cycle has a data line. All the lines in the first cycle have the same line style. Xmath draws the second cycle of lines with a different line style. You can interactively modify line styles, colors, markers, and so forth as discussed in the *Interactive Xmath Graphics Window* section. When you alter a data line, Xmath also changes all lines in that cycle. Note, however, that changes that do not affect data (for example, grid lines) are not passed to other strips.

By default, strip plots are laid out as follows:

• plot (y, {strip=N}) where y is an $(m \times n)$ matrix and n is an integer multiple of N. Strips are arranged as an $((n/N) \times 1)$ matrix of plots. Each strip contains N graphs.

- plot(y, {strip=N}) where y is an (m×n×T) PDM and m is an integer multiple of N. The results are an ((m/N)×n) plot matrix. Think of the PDM as a column vector of blocks. Each subplot contains N graphs.
- plot (y, {strip, columns=m, rows=n}) where y is a matrix with N columns and N is an integer multiple of $m \times n$. This syntax creates an $(m \times n)$ plot matrix that is filled with graphs rowwise. The number of data lines in each subplot is N. This option is very handy because it precludes having to write a nested loop to fill in a matrix of plots.
- plot (y, {strip, columns=m, rows=n}) where y is an $(m_1 \times n_1 \times T)$ PDM and $m_1 \times n_1$ is an integer multiple of $m \times n$. The result is identical to that obtained by plotting makematrix (y) with the same keywords. When used with columns=1, this syntax specifies a column of strip plots instead of a matrix of strip plots.

To demonstrate strip plots, load the following file:

```
load "$XMATH/demos/sys.xmd"
```

This file contains sys, a lightly damped mechanical system that inputs two forces and outputs two positions. It is discrete, sampling at one second. For this example, we use this data to create a system with a sampling rate of one second and named inputs and outputs:

```
sysd=system(sys, {dt=1,inputNames=["Force 1";"Force 2"],
   outputNames=["Position 1";"Position 2"]});
```

Obtain a frequency response of the new system.

```
f = [1:200]/400; gd=freq(sysd, f);
```

Create a continuous version of this system and create a frequency response for it:

```
sysc=makecontinuous(sysd); gc=freq(sysc,f);
```

Plot the continuous and discrete systems.

The results of this example appear in Figure 4-15.

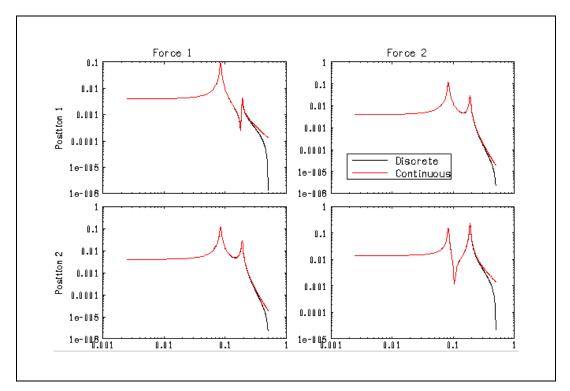


Figure 4-15. Frequency Responses

Bar Plots

The bar keyword is a Boolean used to indicate that the current plot is a bar plot. Each coordinate is plotted as the center of a bar whose height is the y or z coordinate. Default=0.

plot(logspace(1,10,13), {bar,face_style=5,!x_grid})

This plot appears in Figure 4-16.

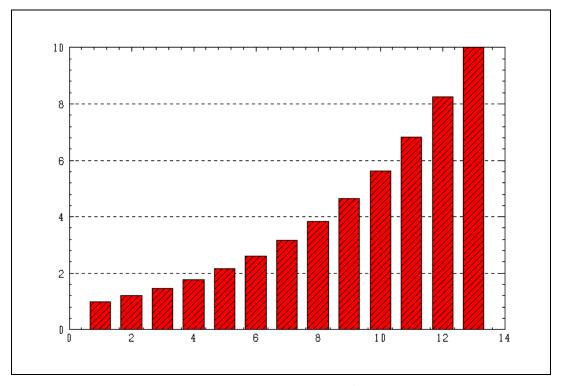


Figure 4-16. Bar Plot

Contour Plots

A contour plot is a 3D plot that shades portions of the plot based on the z data values; the effect is like a topographical map. You can use a legend to show which value ranges correspond to the color or fill pattern shown in the contour plot. If you specify the keyword face_color and supply a vector of colors, those colors will be used to shade the data values.

Keywords	Description
contour contour2d	Booleans used to indicate that the current 2D plot is a contour plot. Requires x, y, and z data. Default = 0.
contour3d	Boolean used to indicate that the current 3D plot is a contour plot. Requires x, y, and z data. Default = 0.
contour_interval	Float value which can be used with contour or contour3d to determine the intervals of

the contour plot. Defaults to the internally calculated tic label values of the **z** data.

Table 4-20. Contour Plots Keywords

The following instructions produce Figure 4-17:

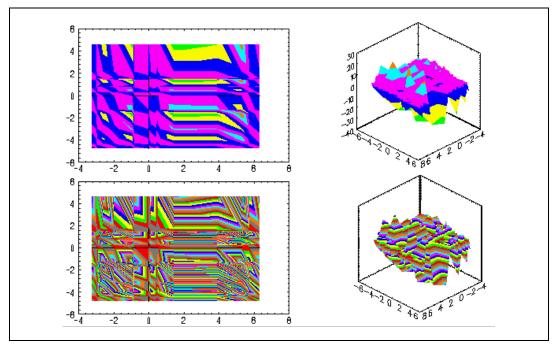


Figure 4-17. 3D Contours with Different Intervals

Polar Plots

The polar plot option draws a 2D plot on a polar grid. Polar plots require a radius (magnitude vector) and an angle vector in degrees (theta):

plot(radius,theta,{polar})

Table 4-21. Polar Plot Keywords

Keywords	Descriptions
polar	Boolean used to make the current 2D plot a polar plot. Default = 0.
r_inc	Integer specifying the polar radius increment value to be marked on the vertical axis of the polar plot.
r_max	Integer specifying the maximum polar radius to be plotted on a polar plot.
theta_inc	Integer specifying the polar angle increment value to be marked around the circumference of the polar plot.
theta_min theta_max	Integer specifying the minimum or maximum polar angle increment to be marked around the circumference of the polar plot.

The following instructions produce Figure 4-18.

```
t=[logspace(1,180,32);logspace(90,270,32);
    logspace(180,360,32);logspace(360,540,32)];
plot (t,t,{polar,!x_grid,r_inc=90,
    theta_inc=10,marker})
```

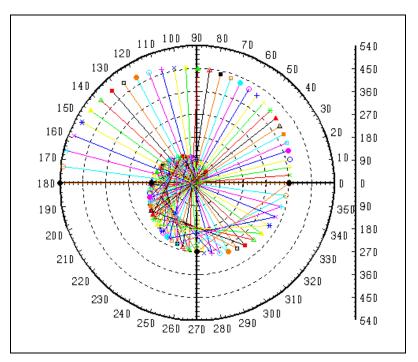


Figure 4-18. Polar Plot

Clearing the Xmath Graphics Window

To clear the **Xmath Graphics** window, type ERASE in the **Xmath Commands** window command area.

Interactive Xmath Graphics Window

The **Xmath Graphics** window displays Xmath plots and other graphics. It is typically opened and updated whenever plot (), or a function that calls plot (), such as bode (), is invoked. It provides extensive interactive facilities for building, modifying, and viewing 2D and 3D graphics. You can specify graph characteristics, such as labels, placement, and size, as keywords to plot (), or you can add or modify them interactively from the **Xmath Graphics** window menus or the **Xmath Palette**.

Graphs are composed of objects such as lines, labels, markers, and axes. Object attributes can be pre-specified as keywords when the plot command is issued from the Commands window command area. Keyword usage is discussed in the *Using Keywords with plot* section of this chapter. You also can manipulate the attributes of an object interactively from the **Xmath Graphics** window menus or toolbar or from the **Xmath Palette**.

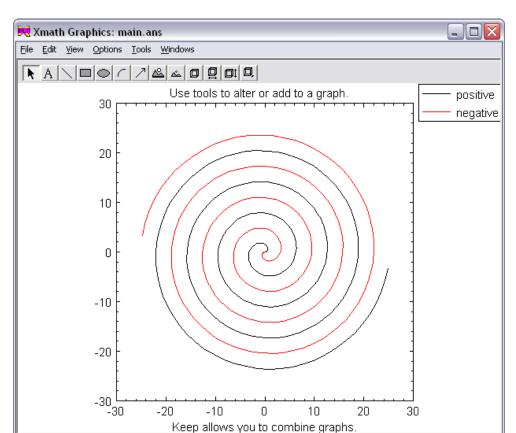


Figure 4-19 shows the Xmath graphics environment.

Figure 4-19. Xmath Graphics Environment

In the example shown in Figure 4-19, the graph originated with a plot () function call in the **Xmath Commands** window command area:

```
v=[0:.1:25]';vc=v.*cos(v);vs=v.*sin(v);
plot(vc,vs)?
plot(-vc,-vs,{keep,!grid,
    legend=["positive","negative"],
    xlab="Keep allows you to combine graphs.",
    title="Use tools to alter or add to a graph."})
```

Notice that two plots were combined using the keep keyword. Graphical additions (the arrows, for example) were created with tools from the toolbar. New objects (for example, the timestamp and datestamp) were added from the Options menu in the **Xmath Graphics** window. The mouse was used to select and position objects (for example, the legend, timestamp, and the datestamp).

Working Interactively

The most common approach is to start with a graph and then use interactive tools to alter it to your satisfaction.

- To make interactive changes, first click an object to select it.
 Xmath selects the closest object to the mouse-click. When you select text, round handles appear on the corners of the text box. When you select a line or curve, it is highlighted and has a thicker appearance.
 - When you make a selection, the appropriate attributes are enabled for both the **Xmath Palette** and the **Xmath Graphics** window menus. For example, when the background is selected, the **Xmath Palette** shows that only the fill patterns are available (line and marker styles are disabled, and the **Fills** button is pushed). If a label is selected, the Font and Point menus become available in the **Xmath Graphics** window; in the **Xmath Palette**, the **Text** button is pushed. You can then change the font and point size from the **Xmath Graphics** window and select a new color from the **Xmath Palette**.
- Place the cursor over an object and drag to move objects.

You can also use pull-down menus to modify and move selected objects, make global changes (zooming, rotating, and so forth), or add objects (through the Options menu). Click an object to select it. When you pull down the menus, only the items appropriate for the object selected are displayed.

Toolbar

The toolbar appears in the **Xmath Graphics** window by default. This feature provides quick mouse access to simple graphical drawing tools and the zoom and rotate tools. To toggle the toolbar off and on, **(UNIX)** select **Options»Icon Bar**. Figure 4-20 shows the toolbar.



Note Notice that not all tools are enabled for all plot types. In general, zooming and rotation are disabled for all multiple graph plots, such as strip plots.

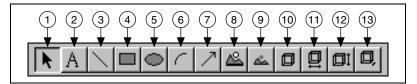


Figure 4-20. The Xmath Graphics Toolbar

This toolbar contains the following tools:

- Selection Arrow
- 2. Text Tool
- 3. Line Tool
- 4. Rectangle Tool
- 5. Ellipse Tool
- 6. Arc Tool
- 7. Arrow Tool
- 8. Zoom In
- 9. Zoom Out
- 10. Rotate All Axes
- 11. Rotate About X-Axix
- 12. Rotate About Y-Axis
- 13. Rotate About Z-Axis

The following sections describe these tools.



Selection Arrow

You use the selection arrow to reset the cursor to selection mode after you use a drawing or text tool.



Text Tool

To use the text tool, click on the **Text Tool** toolbar button. You receive an I-beam cursor. Move to the graph area and click. An empty text box appears; you may start typing. The text box expands as you type. To create a paragraph (continuous lines of text) press <Enter> and keep typing. To start a new string, click in a different place. To turn off the text tool, click the selection arrow or another tool.

To edit existing text, click the **Text Tool** toolbar button, and then click in the text; the text box reappears. Note that the changes you make are not displayed until you click the selection arrow or another tool.

To format text, select it, and then choose a font style and point size from the Font and Size menus on the **Xmath Palette**; you can also enable checkboxes for bold and italic font. To change text color, select the text, and then select a color from the **Xmath Palette**.



Drawing Tools

The line tool, rectangle tool, ellipse tool, arc tool, and arrow tool are primitive drawing tools that allow you to draw in the **Xmath Graphics** window. When you use drawing tools, they remain active until you choose the selection arrow or another tool. To use a tool, click on the desired toolbar button; a crosshairs cursor appears. Click and drag until the desired shape is formed. Release the mouse button to accept changes.



Note You cannot resize or reshape the polygons you create because these are primitive tools.



Zoom In/Zoom Out

To zoom in on a graph, click the toolbar button with the larger image on the left. Position the mouse over your plot; then click and drag to create a box around all or a portion of the graph; the area captured in your box is enlarged to fill the **Xmath Graphics** window. Every time you zoom in, the previous view is saved on a stack.

You can use the **Zoom Out** toolbar button (the toolbar button with the smaller image) to undo a series of enlargements. If you zoom out when you are at the default view, the graph is reduced by approximately 10%.

The zoom feature is disabled for multiple graph plots.



Rotation Tools

Rotation is only allowed with 3D plots and other contour plots. The first rotation tool allows rotation on all axes. The other tools are constrained to rotate only in the directions indicated by the arrows. Select a tool, and then move the cursor to the plot area. Click and slowly drag the cursor in the direction allowed. The data disappears and you see the plot axes turning in response to your mouse movement; when the axes are in the position you wish to view the plot, release the mouse button, and the data is redrawn. To return to the original graph, select **View»Reset**.

Consider the following example:

```
x = [0:10];
y = [0:10];
z = [0:10];
graph = plot(x,y,z, {marker=1, x_lab="X", y_lab="Y",
Z-lab="Z"})
```

The default plot appears in Figure 4-21. This 3D vector is projected in such a way that it is not particularly useful.

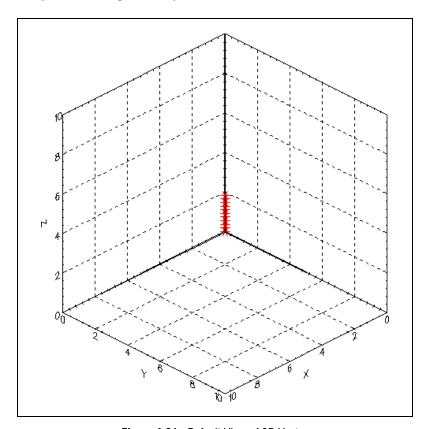


Figure 4-21. Default View of 3D Vector

Using the rotation toolbar buttons, you can rotate this plot in almost an infinite number of ways. Figure 4-22 shows one rotated view, which gives more information than the default plot.

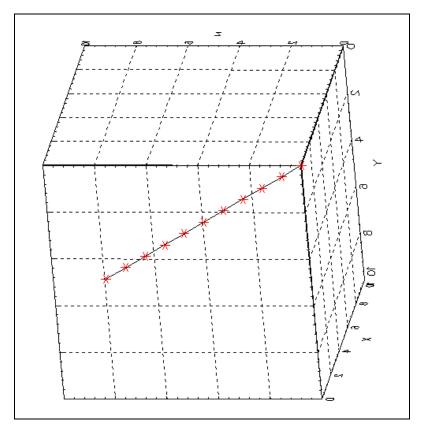


Figure 4-22. Rotated View of 3D Vector

Xmath Palette

Xmath provides another window from which you can work interactively.

Complete the following steps to bring up the **Xmath Palette**:

Click Windows»Palette in the Xmath Graphics window.
 The Xmath Palette comes on view. Figure 4-23 shows this window.

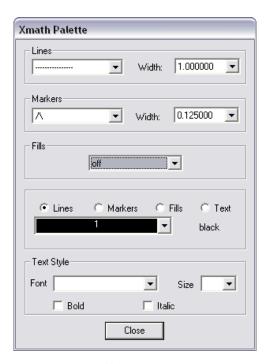


Figure 4-23. The Xmath Palette

Complete the following steps to use the **Xmath Palette**:

- Select an object in the Xmath Graphics window.
 The object type appears at the top of the Xmath Palette in the title bar.
 The radio button for the active option—Lines, Markers, Fills, or Text—is pushed. All items that are available for the selected item are active, whereas others are inactive in the window.
- 2. Click the radio button for the option that you wish to change: Lines, Markers, Fills, or Text.

- 3. Make the desired changes for this option.
 - You can control the color of all attributes. You can turn lines, markers, and fills off or choose the type of each. For lines and markers, you can also choose the width. For text, you have a choice of fonts, sizes, plain, bold, italic, or bold italic style. The text choices mimic the options available through the Font and Point menus in the **Xmath Graphics** window in UNIX.
- 4. Modify as many attributes for as many objects as you want, and then click **Close** to close the window.

Data Objects and Operators

This chapter provides a conceptual overview and detailed descriptions of Xmath data objects and operators.

Data Hierarchy

Xmath data hierarchy, as shown in Figure 5-1, is divided into numeric and nonnumeric branches.

The matrix, for example, is general. It consists of matrices of various shapes. The square matrix is a specific kind of matrix that requires an equal number of rows and columns, but otherwise *inherits* the characteristics of the matrix. A scalar is a special kind of square matrix with dimensions of 1×1 . A scalar is also defined as a special kind of vector, because it is a vector with a length of 1.

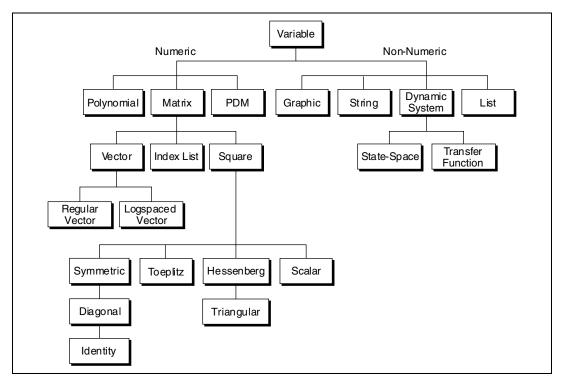


Figure 5-1. Object Relationships

Xmath provides an object-based structure, which enables the following benefits:

- Simplified data management—As variables in Xmath can represent complex groupings of data, you do not have to track numerous variables. For example, with a state-space system using system(A,B,C,D), all the data (including input names, output names, and so on) is stored in a single variable. The matrices can be deleted.
- Optimized performance—Many Xmath data objects were designed
 to take advantage of optimized algorithms. This is especially true of
 the specialized matrices. The eigenvalues of a symmetric matrix, for
 example, can be found more quickly with a symmetric eigensolver
 rather than a general eigensolver. Xmath recognizes the special
 properties of a matrix and uses the appropriate, optimized algorithm.
- **Natural syntax**—Because Xmath recognizes the special properties of each type of data object, operations are intuitive. For example, it is more natural to multiply two polynomials by typing p1*p2 than it is to call convolve(p1, p2).

Data Object Descriptions

This chapter describes Xmath data objects in the following order:

- Matrix
- Polynomial
- Parameter-dependent matrix (PDM)
- Dynamic system
- String
- List

Some of the categories are subdivided. For example, dynamic systems include state-space systems and transfer functions, and matrices include the following:

- Vector
 - Regular vector
 - Logspaced vector
- Square
 - Symmetric, Diagonal, Identity, Toeplitz
 - Hessenberg, Triangular
 - Scalar
- Indexlist



Note To reproduce the examples, cut and paste the monospace text.

Matrix

A matrix is an object organizing m rows and n columns $(m \times n)$ of real or complex numbers (elements). A complex number contains both a real and an imaginary term. A matrix is complex if at least one element is complex. To qualify as a real matrix, all elements must be real.

Matrices are specified with the following syntax elements:

- A matrix specification is enclosed in square brackets.
- Matrix column elements must be separated by commas.
- A semicolon separates rows.

For example, x=[jay, 4; 3,-1]. In a formatted matrix, a line feed replaces the semicolon:

```
x=[jay, 4 # Line Feed
3, -1] # Return
```

The matrix specification ends with a right bracket.

Specific types of matrices are also created with functions such as zeros(), random(), diagonal(), and so on. These functions require row and column dimensions as inputs:

```
set seed = 0
x=random(3,4)

x (a rectangular matrix) =

0.211325    0.756044    0.000221135    0.330327
0.665381    0.628392    0.849745    0.685731
0.878216    0.068374    0.560849    0.662357
```

The functions <code>check()</code> and <code>is()</code> can be used to determine if a variable is a matrix. For brief explanations of <code>check()</code> and <code>is()</code>, refer to the <code>Object Query Functions</code> section of Chapter 6, <code>MathScript Programming</code>. Sample syntaxes are: <code>check(x, {matrix})</code> or <code>is(x, {matrix})</code>.

Use size to find the row and column dimensions of a matrix:

```
size(x)
ans (a row vector) = 3 4
To find the total number of elements, use length():
length(x)
```

12

ans (a scalar) =

Many classes stem from the matrix class, and it is the primary component of several more specialized objects.

Matrix Concatenation

Concatenation (combining several matrices into a new matrix) is performed using square bracket operators []. Right concatenation is indicated with commas [,]; bottom concatenation is indicated by semicolons [;].

For example,

- [A, B] concatenates B to the right of A (where B must have the same number of rows as A).
- [A; B] concatenates B to the bottom of A (where B must have the same number of columns as A).

```
x=random(3,2)*12
```

```
x (a rectangular matrix) =
 8.71621
            2.38217
 6.53109
            2.7849
 2.77468
            2.59756
x=[x, ones(3,4); ones(2,2), zeros(2,4)]
x (a rectangular matrix) =
 8.71621
            2.38217
                      1
                           1
                                1
                                     1
 6.53109
            2.7849
                      1
                           1
                                1
                                     1
 2.77468
          2.59756
                     1
                          1
                                1
                                     1
                      0
                           0
                                0
                                     0
 1
            1
 1
            1
                      0
                           0
                                0
                                     0
```

Matrix Operators

The operators in Table 5-1 have special meanings for matrices:

```
scalar operator matrix
```

usually means applying the operator elementwise.

```
mat1=[1,1,1,1; 2,2,2,2; 3,3,3,3];
mat2=mat1 * mat1'
```

```
mat2 (a square matrix) =
    4    8    12
    8    16    24
    12    24    36
3 * mat1
ans (a rectangular matrix) =
```

```
3 3 3 3
6 6 6 6
9 9 9 9
```

 Table 5-1. Matrix Operations

Operator	Effect
+	Addition (or unary plus). Matrices must have the same dimensions.
-	Subtraction (or unary minus). Matrices must have the same dimensions.
*	Matrix multiplication. The number of columns in the first matrix must equal the number of rows in the second matrix.
/	Matrix right division. A/B solves the equation $X \times B = A$. The number of columns in A must equal the number of rows in B .
\	Matrix left division. $B\setminus A$ solves the equation $B\times X=A$. The number of columns in B must equal the number of rows in A .
1	Transpose (unary suffix).
* '	Complex conjugate transpose (unary suffix).
.*	Elementwise matrix multiplication. Matrices must have the same dimensions.
./	Elementwise division (left divided by right). Matrices must have the same dimensions.
.\	Elementwise division (right divided by left). Matrices must have the same dimensions.
^ or **	Raise a square matrix to a scalar power.
.^ or .**	Raise elements to a power. Another matrix of the same size can contain the powers.
.*.	Kronecker product.
./.	Kronecker right division.
.\.	Kronecker left division.
&	Elementwise logical and.
	Elementwise logical or.
!	Elementwise logical not.
<	Elementwise less than.
>	Elementwise greater than.
<=	Elementwise less than or equal.
>=	Elementwise greater than or equal.

Table 5-1. Matrix Operations (Continued)

Operator	Effect
==	Elementwise equal.
<>	Elementwise not equal.
=	Assignment.

Matrix Indexing

Indexing (extracting a specific subset of matrix elements) is performed using the parentheses operators (). Indices can consist of any one of the following:

• Two integers specifying the desired row and column.

A(i,j) extracts from A the element located in row i, at column j. This can be demonstrated using the matrix mat2 created earlier.

mat2

mat2 (a square matrix) =

4 8 12 8 16 24 12 24 36

mat2(2,3)

ans (a scalar) = 24

• Two vectors of integers specifying a range of rows and columns. A (vector1, vector2) extracts a portion of A with rows corresponding to vector 1 and columns corresponding to vector 2.

mat2(1:2,2:3)

ans (a square matrix) =

8 12 16 24

 An index list that specifies all desired element locations in terms of row and column indices. An index list can be created with the find() or indexlist() functions. For more on the index list object, refer to the *Index Lists* section.

ijList=find(mat2>15)
ijList (an index list) =
2 2

2 3 3 2 3 3

36

• Notice that find() returns the row and column coordinates for elements in mat2 that are greater than 15: (2,2), (2,3), (3,2), and (3,3). You can use indexing to display the values in these index list locations:

```
mat2(ijList)
ans (a column vector) =

16
24
24
```

Indexing with the Colon Operator (:)

The colon operator (:) is a wildcard for all elements, thus A(i, :) is the *i*th row of A and A(:, j) is the *j*th column of A.

You can use a wildcard and a decreasing vector to reverse the columns of a matrix.

```
mat2(:,[3:-1:1])
ans (a square matrix) =

12     8     4
24     16     8
36     24     12
```

Here wildcards are used to extract rows, which are reassembled into a new matrix:

Vector

The vector class is a subclass (or specialization) of the matrix class. A vector object is a matrix that has a row or column dimension equal to 1. Vectors can be *oriented* as either rows or columns.

• Use ^ to raise elements to a power (for matrices, use .^). [1:4]^[1:4]

```
ans (a row vector) = 1 4 27 256
```

• Vectors can be indexed with a single index variable. Thus v(i) is the *i*th element of the vector v. A single vector of integers can also be used as an index.

```
a=[2,4,6,8,10]
a (a row vector) = 2 4 6 8 10
a([1,3,5])
ans (a row vector) = 2 6 10
```

- The colon (:) wildcard expands vectors in column form.

 aVector(:) is always defined as a column, regardless of whether the vector is a row or column.
- The length() function is the most natural method of determining the length of vector. length(aVector) is defined as max(size(aVector)).
- To see if a variable is a vector, invoke is (var, {vector}) or check(var, {vector}).

To determine whether the vector is a row or column, use is (var, {row}) or is (var, {column}) (or use check). The {row} and {column} keywords imply {vector}. For brief explanations of check and is, refer to the *Object Query Functions* section of Chapter 6, *MathScript Programming*.

Regular Vector

A regular vector is evenly spaced, with each element a fixed increment from the previous value. If a regular vector is created with the colon operator, Xmath stores it as three values (start:increment:stop). You can treat it as a vector, but it is displayed in a special manner.

• A regular vector can only be a row vector. Transposing it expands it to full size, turns it into a simple vector.

```
x=0:0.33:1

x (a regularly spaced vector) = 0 : 0.33 : 1

x'
```

```
ans (a column vector) =

0
0.33
0.66
0.99
```

• Putting a regular vector between square braces [] will expand it.

```
[x]
ans (a row vector) = 0 0.33 0.66 0.99
```

A regular vector is internally expanded for most operations, except indexing.

Although a regular vector is stored in compact form (as start, stop, and increment values), it has the same dimensions as if it were created in expanded form. You can view the sizes of all the variables in your current partition with the who command. Use the size function to view the size of a single variable:

```
size(x)
ans (a row vector) = 1
```

Logspaced Vector

A logspaced vector is just like a regular vector except that its points are evenly spaced on a log scale. It can only be created with the logspace() function. logspace() inputs are the initial value, the final value, and the number of points desired in the vector. All the display considerations for a regular vector apply to logspaced vectors.

```
x1=logspace(0.1,10,4)
x1 (a log-spaced vector) = 0.1 : 10 (4 points)
[x1]
ans (a row vector) = 0.1 0.464159 2.15443 10
```

Square Matrix

The square matrix class is a subclass of the matrix class. A square matrix object has equal row and column dimensions.

All of the functions that are defined for matrices are also defined for square matrices. However, there are several square matrix functions that are not valid for rectangular matrices. The most important of these are shown in Table 5-2.

Table 5-2. Functions That Are Only Valid for Square Matrices

Function	Result
^ or **	raise matrix to a power $(A^3=A\times A\times A)$
.^ or .**	raise each element to a power
cholesky()	Cholesky decomposition
cosm()	matrix cosine (use cos elementwise)
det()	determinant
eig()	eigenvalues
expm()	matrix exponential (use exp elementwise)
hessenberg()	Hessenberg decomposition
inv()	inverse
logm()	matrix logarithm (use log elementwise)
lu()	L-U decomposition
orth()	orthogonal decomposition
polynomial()	characteristic polynomial
polyvalm()	evaluates polynomial function of a matrix
dz()	generalized eigenvalues
rref()	reduced-row echelon form
schur()	Schur form
sinm()	square matrix sine (use sin elementwise)
sqrtm()	matrix square root (use sqrt elementwise)
trace()	find the sum of the diagonal elements of a matrix

Symmetric

The symmetric matrix class is a subclass of the square matrix class. A symmetric matrix object is equal to its transpose.

For most applications, symmetric matrices act just like square matrices. Certain algorithms take advantage of their special structure to achieve improved results. For example, the eigenvalues of a symmetric matrix can

be found more quickly than the eigenvalues of a general matrix. Also, the answers are constrained to be purely real.

```
a=[1:4];b=[a;a;a;a]
b (a square matrix) =
  1
       2
             3
                   4
  1
       2
             3
  1
       2
             3
                   4
  1
       2
             3
is(b,{symmetric})
ans (a scalar) =
c=tril(b,1) + tril(b,1)'
c (a square matrix) =
  2
       3
             1
                  1
  3
       4
             5
                  2
  1
       5
             6
                  7
       2
  1
             7
is(c,{symmetric})
ans (a scalar) =
                     1
```

Diagonal()

The diagonal matrix class is a subclass of the symmetric matrix class and the triangular matrix class as discussed in the *Triangular* section. A diagonal matrix object has zero in all positions except along the main diagonal.

The diagonal () function can be used to extract a diagonal from a matrix. Extract the diagonal from the matrix c defined above:

```
d=diagonal(c)
d (a column vector) =

2
4
6
8
```

If a vector is used as an input, a matrix is created that has the vector on the main diagonal.

Identity

The identity matrix class is a subclass of the diagonal matrix class. An identity matrix object has ones on the main diagonal and zero for all other elements. The function eye() creates an identity matrix from row and column dimensions:

eye(3,3) ans (a square matrix) = 1 0 0 0 1 0 0 0 1

For most applications, identity matrices act like square matrices. Certain algorithms, such as multiplication and inversion, take advantage of their special structure.

Toeplitz

The Toeplitz matrix class is a specialization of the square matrix class with constant entries along the diagonals. A Toeplitz matrix can be described by its first row and first column (if it is symmetric, it can be described by a single vector). The matrix left and right division operations have been overloaded for solving matrix equations of the form $T \times X = A$ and $X \times T = A$ (where T is a Toeplitz matrix):

```
t=toeplitz([3,2,1],[1,2,3])
t (a toeplitz matrix) =

3     2     1
2     3     2
3     2     3
```

Hessenberg()

The Hessenberg matrix class is a subclass of the square matrix class. A Hessenberg matrix has zeros in all elements below the first subdiagonal or above the first superdiagonal. The hessenberg () function puts a matrix A in Hessenberg form H, defined such that $A = T \times H \times T *$ where T is a unitary transformation matrix of the same size and type as A.

```
hessenberg([1,2,3;1,2,3;1,2,3])
```

ans (a square matrix) =

```
1 -3.53553 0.707107
-1.41421 5 -1
0 -3.14018e-16 3.14018e-16
```

Triangular

The triangular matrix class is a specialization of the Hessenberg matrix class. A triangular matrix object has zeros in all elements above the main diagonal (upper triangular) or below the main diagonal (lower triangular).

```
set seed 0
a=round(rand(4,4)*4)
a (a square matrix) =
  1
       3
             0
                   1
  3
        3
                   3
  4
        0
             2
                   3
  3
        1
             2
                   1
12345678 112345678 212345678
aTriu=triu(a)
                      # an upper triangular
aTriu (a square matrix) =
  1
       3
             0
                   1
  0
        3
             3
                   3
             2
  0
        0
                   3
        0
                   1
aTril=tril(a)
                      # a lower triangular
aTril (a square matrix) =
  1
        0
             0
                   0
  3
        3
             0
                   0
  4
        0
             2
                   0
  3
        1
             2
                   1
```

Scalar

The scalar class is a subclass of the square matrix class. A scalar object is a matrix with a single row and a single column.

Any function or operator defined for a matrix is also defined for a scalar. However, scalars have many special properties when used in combination with other classes of objects, as shown in the samples that follow.

• **scalar x matrix**—Each element of the matrix is multiplied by the scalar. The same holds true for vectors and PDMs. Division works the same way.

```
5*[1:5]

ans (a row vector) = 5 10 15 20 25

ans/5

ans (a row vector) = 1 2 3 4 5
```

• scalar x polynomial—If the polynomial is in factored form, the gain of the polynomial is multiplied by the scalar. Refer to the *Polynomial()* section for mor information. If the polynomial is in coefficient form, each coefficient is multiplied by the scalar. Division works the same way.

Using a scalar with a polynomial in roots form:

```
4*polynomial(1:4)

ans (a polynomial) =

4(x - 1)(x - 2)(x - 3)(x - 4)
```

Using a scalar with a polynomial in coefficients form:

makepoly(1:4)

```
ans (a polynomial) =

3  2
x + 2x + 3x + 4

ans/0.5

ans (a polynomial) =

3  2
2x + 4x + 6x + 8
```

• **scalar x system**—Multiplies the gain of the system by the scalar. Refer to the *Dynamic System* section for more information about dynamic system objects. For transfer functions, the numerator polynomial is

multiplied by the scalar. For state-space systems, the C and D matrices are multiplied by the scalar. Division works the same way.

```
system([2,2;2,2],[3;3],[4,4],1);
2*ans
ans (a state space system) =
  A
  2
       2
  2
       2
  В
  3
  3
  С
  8
       8
  D
  2
  X0
  0
  0
  System is continuous
system(makepoly(2:5), makepoly(0:3))
ans (a transfer function) =
    3
         2
  2x + 3x + 4x + 5
      2
    x + 2x + 3
  initial integrator outputs
  0
  Input Names
  -----
  Input 1
```

```
Output Names
  _____
 Output 1
 System is continuous
ans/2
ans (a transfer function) =
  3
         2
 x + 1.5x + 2x + 2.5
      2
     x + 2x + 3
 initial integrator outputs
  0
  Input Names
  -----
  Input 1
 Output Names
 Output 1
```

System is continuous

matrix+scalar—The scalar is added to each element of the matrix. This operation is commutative. The same holds true for vectors and PDMs. Subtraction works the same way.

• **polynomial+scalar**—Converts the polynomial to coefficient form and adds the scalar to the scalar (order 0) term of the polynomial. This operation is commutative. Subtraction works the same way.

```
p=polynomial(3:5)
```

```
p (a polynomial) =
   (x - 3)(x - 4)(x - 5)
2+p
ans (a polynomial) =
   3   2
   x - 12x + 47x - 58
```

 matrix(vector,vector)=scalar—Copies the scalar to each element of the specified partition of the matrix. The same holds true for vectors and PDMs.

```
o=ones(4,5);
o([2:3],[2:4])=32
o (a rectangular matrix) =
  1
        1
               1
                            1
                      1
  1
       32
              32
                     32
                            1
  1
       32
              32
                     32
                            1
  1
        1
               1
                      1
                            1
```

Polynomial()

Polynomials take the form $x^3 + 9x^2 - 4x + 7$ or x(x-2)(x+6). The first notation is in coefficients form; its coefficients (1, 9, -4 and 7) are plainly shown. The second polynomial is in roots form, its roots being 0, 2, and -6. Polynomial objects consist of a vector of coefficients or roots and a single independent variable (a text string, usually a single character).

Polynomials can be defined in terms of their roots or coefficients. The polynomial() function creates a polynomial object where roots are the elements of a vector or eigenvalues of a square matrix you supply. You can specify a text string for the polynomial variable. makepoly() converts a simple vector into a polynomial.

Create a polynomial from its roots with polynomial (). The polynomial is displayed in roots form:

```
p1=polynomial([1*jay, -1*jay, 1,
2*jay, -2*jay, 2,
3*jay, -3*jay, 3], "j")
```

Create a polynomial from a vector with makepoly (); the polynomial will be displayed in coefficients form:

Polynomial Operators

The following operators are valid for polynomials:

polynomial addition
 polynomial subtraction
 polynomial multiplication
 creates a transfer function

Operations can only be performed between polynomials that have the same independent variable or between polynomials and scalars.

System is continuous

The functions in Table 5-3 can handle parts of polynomials. For more information on inputs and outputs, refer to the *MATRIXx Help*.

Table 5-3. Polynomial Handling Functions

Function	Purpose
roots()	extracts the roots of a polynomial
makematrix()	extracts the coefficients of a polynomial
domain()	extracts the independent variable from a polynomial or PDM

Function

Purpose

evaluates a polynomial at each element of a given matrix

polyvalm()

evaluates a polynomial over an entire square matrix

Table 5-3. Polynomial Handling Functions (Continued)

Parameter-Dependent Matrix (PDM)

A parameter-dependent matrix (PDM) is a flexible extension of the matrix data type. It consists of a vector of same-size matrices with a vector attached to it. The attached vector (or parameter) is referred to as the *domain* as shown in Figure 5-2. A PDM also has optional string names for its rows and columns Figure 5-3.

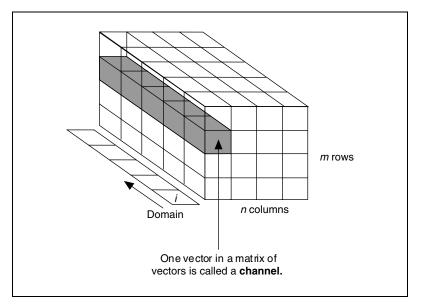


Figure 5-2. Structure of a PDM

PDM data is stored as a series of matrices indexed by a single domain vector. Computations involving the PDM are performed on each matrix separately. Data can also be handled as a series of vectors, called *channels*, having a common domain vector (time or frequency, for example). In this format, the computations are performed on each vector of the data separately.

Used either way, PDMs provide a convenient method for storing data as a function of a parameter and are particularly useful in the analysis of multiple input and/or output dynamic systems, where they can be used to store time or frequency responses.

For example, when the frequency response of a system with n inputs and m outputs is calculated, a PDM is created. Each of the n columns represents an input, each of m rows represents an output, and the dependent matrix at element i of the domain corresponds to the frequency response from each output to each input. Plotting time and frequency responses stored as PDMs are particularly convenient when the {strip} keyword is used, in which case a matrix plot is produced where the rows and columns correspond with inputs and outputs, respectively (for information on strip plots, refer to the $Strip\ Plots$ section of Chapter 4, Graphics. For an explanation of time response, refer $Time\ Response$ section.

PDM Organization

Consider the object radar as an example of PDM organization (+). Exactly how radar is created is outlined in *Creating PDMs* section.

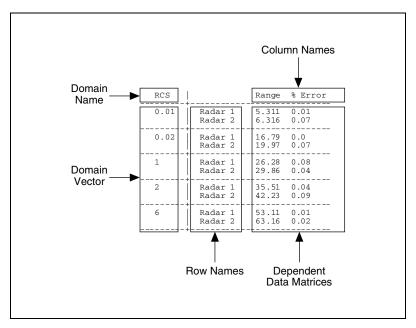


Figure 5-3. Parts of the PDM radar

Every PDM consists of five main parts:

- **Dependent Data Matrix**—Every PDM contains one or more matrices; radar has five 2×2 matrices in the dependent data area. The matrices must be the same size. There is no limit to the size or number of matrices in this area.
- **Domain Vector** The PDM allows you to group an independent vector of parameter values and a stack of associated matrices. The vector of independent parameter values is called the *domain* of the PDM. The domain usually represents a physical parameter, for example, time, frequency, temperature, pressure, or altitude. If no domain vector is specified, the PDM domain defaults to increasing positive integers starting from one.
- **Domain Name**—A label for the domain vector. In radar, the domain string is "RCS". If no name is specified, the default string is "domain".
- Row Names—Each dependent matrix row may have an optional string name. In radar, the names are "Radar 1" and "Radar 2". Each matrix has the same row names associated with it. If no names are specified, the row names are labeled "Row 1", "Row 2", ... "Row N".
- Column Names—Each dependent matrix column may have an optional string name. In radar, the names are "Range" and "% Error". If no column names are specified, the columns are labeled "Col 1", "Col 2", ..."Col N".

Creating PDMs

PDMs are created from a single matrix object using the function $pdm(\)$. Additional optional arguments to $pdm(\)$ specify the domain, domain label, and row and column labels to be associated with the matrices in the final PDM.

For the PDM radar, the dependent data is formed from a columnwise concatenation of the vectors maxrange and perr:

The final dependent data matrix [maxrange, perr] used as an argument to pdm() has two columns and 10 rows.

The domain vector used in radar, rcs, has five elements.

```
rcs = [0.01, 0.02, 1, 2, 6];
```

Use the pdm() function to construct the PDM radar from the matrix [maxrange, perr] and the domain vector RCS:

```
radar = pdm([maxrange,perr],rcs,{domainName="RCS",
    rowNames = ["Radar 1","Radar 2"],
    columnNames = ["Range","% Error"]})
```

radar (a pdm) =

RCS			Range	% Error
0.01	Radar	1	5.311	0.01
	Radar	2	6.313	0.07
0.02	Radar	1	16.79	0
	Radar	2	19.97	0.07
1	Radar	1	26.28	0.08
	Radar	2	29.86	0.04
2	Radar	1	35.51	0.04
	Radar	2	42.23	0.09
	Radar	1	53.11 63.16	0.01

You have just recreated the PDM shown in Figure 5-3.

The dependent matrix is the only required argument to a PDM. Any additional arguments can modify the structure of the PDM. For example, using pdm () with no optional arguments results in a PDM with each dependent matrix having one row.

Default PDM Behavior

If you do not use the rows or columns keywords and do not specify a domain vector, each row of the input matrix becomes one of the output dependent data matrices. For example:

ans (a pdm) =

domain | Col 1 Col 2 Col 3

1 | 0.849745 0.685731 0.878216

2 | 0.068374 0.560849 0.662357

3 | 0.726351 0.198514 0.544257

4 | 0.232075 0.231224 0.216463

This default behavior also applies if any or all of the rows or columns keywords, or domain vector, are specified in a way that matches the default case. For example, Xmath generates the same PDM output. The rows and columns keywords are ignored in this case):

```
pdm(r43, {rows=1, columns=3})
```

ans (a pdm) =

•	Col 1		
•	0.849745		
2	0.068374	0.560849	0.662357
3	0.726351	0.198514	0.544257
4	0.232075	0.231224	0.216463

pdm(r43,1:4)

ans (a pdm) =

	Col 1		
	0.849745		
	•'	0.560849	
3	0.726351	0.198514	0.544257
4	0.232075	0.231224	0.216463

If you specify arguments that deviate from the default, other PDMs are obtained:

In the previous example, the number of rows of the input matrix (4) is not a multiple of the length of the domain vector (3). However, the number of columns of the input matrix (3) is a multiple. In this case, each column, instead of each row, of the input matrix becomes one of the output Dependent Data Matrices.

When no domain vector is specified, the default vector is [1:1:#rows].

pdm([maxrange,perr])

ans (a pdm) =

domain	Col 1	Col 2
1	5.311	0.01
2	6.313	0.07
3	16.79	0
4	19.97	0.07
5	26.28	0.08
6	29.86	0.04
7	35.51	0.04
8	42.23	0.09
9	53.11	0.01
10	63.16	0.02

To change the dimensions of the dependent matrices, use the rows and columns keywords. For example:

```
1 | Row 1 5.311 0.01
     Row 2
            6.313 0.07
   2 | Row 1 16.79
     Row 2 19.97
                 0.07
   3 | Row 1 26.28
                  0.08
     Row 2 29.86
                 0.04
-----
   4 | Row 1 35.51
     Row 2 42.23
                 0.09
                 0.01
   5 | Row 1 53.11
     Row 2 63.16
```

ans (a pdm) =

Alternatively, the row and column size is implied in the number of strings entered in keywords columnnames and rownames:

domain			Range	
1	Radar Radar	1 2	5.311 6.313	0.01 0.07
2	Radar Radar	1 2	16.79 19.97	0 0.07
3	Radar	1 2	26.28 29.86	0.08
4	Radar Radar	1 2	35.51 42.23	0.09
	Radar Radar	1 2	53.11 63.16	0.01 0.02
	-			

The dependent matrix size can also be influenced by the domain vector. In the following example, the columns of the PDM matrices are the same as the input matrix. The number of rows of each PDM matrix is equal to the total number of rows in the input matrix divided by the number of elements in the domain vector. The domain rcs has five elements, and the input matrix has 10 rows. Therefore, each PDM matrix has 10/5 (=2) rows.

pdm([maxrange,perr],rcs)

ans (a pdm) =

domain	 	Col 1	Col 2
0.01		5.311	0.01
0.02	Row 1 Row 2		0
	Row 1	26.28	0.08
2	Row 1 Row 2		0.04
6	Row 1 Row 2	53.11	0.01 0.02

The PDM row and column dimensions specified by rows, rowNames, columns, and columnNames must agree with the PDM dimensions specified by the domain vector, or an error message is returned:

```
pdm(r43, {rows=1, columns=3})
```

Dimensions of PDM do not match specified rows and columns and length of domain vector

PDM Channels

In some circumstances, a PDM is a collection of vectors instead of a collection of matrices. For PDMs, these vectors are called *channels* of the PDM. A channel is a vector consisting of the same element from each dependent matrix. For example, radar has four channels,

```
(1,1): 5.311, 16.79, 26.28, 35.51, 53.11
(2,1): 6.313, 19.97, 29.86, 42.23, 63.16
(1,2): 0.01, 0, 0.08, 0.04, 0.01
(2,2): 0.07, 0.07, 0.04, 0.09, 0.02
```

and all channels have the common independent variable defined by rcs. Figure 5-2 illustrates this idea.

Certain MathScript functions, such as fff(), have the option of operating on the dependent matrices or the channels of a PDM. By default, all functions operate on the dependent matrices.

```
Y = fft(radar)
```

If the FFT of each channel is needed, the channels keyword must be included.

```
Y = fft(radar, {channels})
```

Refer to the *Using Functions with PDMs* section for more details on using functions with PDMs.

Indexing to Extract Portions of a PDM

PDM Dimensions

Use the size() function to see the dimensions of the new PDM: size(radar)

```
ans (a row vector) = 2 2 5
```

The above result indicates that each dependent matrix has two rows and two columns, and that the length of the PDM (the length of the domain or the number of dependent matrices) is five.

Dependent Matrices

PDM indexing allows you to extract parts of a PDM. The output of any PDM indexing operation is always another PDM. If you want to index to extract a single piece of data—as opposed to a dependent matrix or a channel of a PDM) it may be simpler to use makematrix() before indexing. Refer to the *Converting PDMs to Matrices* section.

To extract a single dependent matrix, use a single index corresponding to the domain value of interest. For example, you might want to extract only the data pertaining to objects with RCS value of 1:

```
radar(3)
```

To see the third through fifth elements of the PDM, you can index into radar using the standard colon notation. Refer to the *Indexing with the Colon Operator* (:) section:

You can also examine one or more channels of the data in a PDM and see changes over the length of the PDM (as the RCS parameter changes). When indexing with both row and column specifications, you extract the (i,j) channel over the entire domain. The following example extracts the element that resides in the second row and first column of each dependent matrix.

radar(2,1)
ans (a pdm) =

radar(3:5)

RCS	•		Range
	+ Radar		6.313
0.02	Radar	2	19.97
1	Radar	2	29.86
2	Radar	2	42.23
6	Radar	2	63.16

The standard colon notation can be used to access more than one channel:

radar(1:2,1)

ans (a pdm) =

RCS	 +	Range
0.01	Radar 1 Radar 2	5.311 6.313
0.02	Radar 1 Radar 2	16.79 19.97
1	Radar 1 Radar 2	26.28 29.86
2	Radar 1 Radar 2	35.51 42.23
6	Radar 1 Radar 2 +	53.11 63.16

To extract a single value in PDM form, you can use a temporary value:

Individual PDM elements can be extracted and modified using three scalar indices to specify the row, column, and domain positions, respectively. The returned object is always a scalar. Thus, for the radar example:

```
radar(1,1,1)
ans (a scalar) = 5.311
radar(2,2,5)
ans (a scalar) = 0.02
radar(2,1,3) = radar(1,1,5)
```

radar	(a pdm)	=		
RCS			Range	% Error
+				
0.01	Radar	1	5.311	0.01
	Radar	2	6.313	0.07
+				
0.02	Radar	1	16.79	0
	Radar	2	19.97	0.07
+				
1	Radar	1	26.28	0.08
	Radar	2	53.11	0.04
+				
2	Radar	1	35.51	0.04
1	Radar	2	42.23	0.09
+				
6	Radar	1	53.11	0.01
ĺ	Radar	2	63.16	0.02
+				

Domain and Name Information

The domain can be extracted using domain().

```
rsvector = domain(radar)
rsvector (a row vector) = 0.01  0.02  1  2  6
```

The PDM names can be extracted with the names () function. In order to get all three labels, specify three outputs:

```
[rowN,colN,domN]=names(radar)
rowN (a row vector of strings) = Radar 1 Radar 2
colN (a row vector of strings) = Range % Error
domN (a string) = RCS
```

Example 5-1 Indexing into a PDM

This example illustrates PDM indexing by plotting a PDM and different combinations of data that can be extracted from it. Notice that plot() will reuse the row and column labels from your PDM, if possible.

```
 \begin{aligned} & \texttt{x=logspace}(1,100,3); \texttt{F=}([1.02:.02:2.5]); \\ & \texttt{s1c=system}(\texttt{makep}([\sin(\texttt{x})]), \texttt{makep}(-\texttt{x}^*2)); \\ & \texttt{s2c=system}(\texttt{makep}([\cos(\texttt{x})]), \texttt{makep}(\texttt{x}^*2)); \\ & \texttt{s3c=system}(\texttt{makep}([\cot(\texttt{x})]), \texttt{makep}(\texttt{x})); \end{aligned}
```

If strip is specified alone, each submatrix is plotted in a separate subgraph, as shown in Figure 5-4. Try plotting portions of the PDM with the different strip settings shown below.

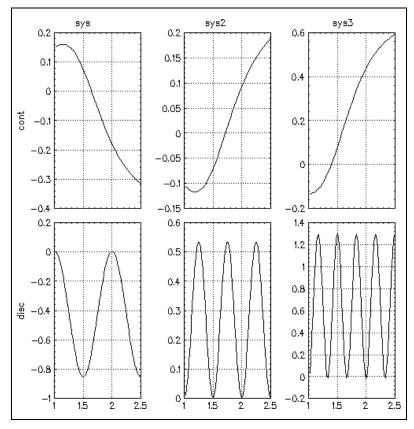


Figure 5-4. PDM Plotted with strip

If the number of strips is specified, the inputs will be plotted accordingly.

```
plot(p,{strip=3})
```

Extract all discrete rows, then plot one plot per subgraph:

```
plot(p(2,:), {strip=1})
```

Plot all rows of the 2nd column with default strip settings.

```
plot(p(:,2),{strip})
```

Modifying PDMs

Substitution

Using PDM indexing, outlined in the *Indexing to Extract Portions of a PDM* section, assignments can be made to replace parts of a PDM. For example, to replace the third dependent matrix of radar with an identity matrix, type:

```
ind = eye(2,2); radar_copy = radar; radar_copy(3) = ind
radar_copy (a pdm) =
```

RCS		Range	% Error
0.01	Radar 1 Radar 2	5.311 6.313	0.01 0.07
0.02	Radar 1 Radar 2	16.79 19.97	0 0.07
1	Radar 1 Radar 2	1	0 1
2 	Radar 1	35.51 42.23	0.04
-	Radar 1 Radar 2	53.11 63.16	0.02

```
ind = [10,20,30,40,50];
radar_copy(1,1) = ind
```

radar_copy (a pdm) =

RCS		_	% Error
0.01	Radar 1	10	0.01
	Radar 2	6.313	0.07
0.02	Radar 1	20	0
	Radar 2	19.97	0.07
1	Radar 1	30	0
	Radar 2	0	1
2	Radar 1	40	0.04
	Radar 2	42.23	0.09
6	Radar 1	50	0.01
	Radar 2	63.16	0.02

Concatenation

Compatible PDMs can be concatenated in the same manner as matrices. A comma results in right concatenation, and a semicolon results in bottom concatenation.

```
new_radar =[radar,radar(1:2,1)^2]
```

new_radar (a pdm) =

RCS	 +	_	% Error	_
0.01	Radar 1 Radar 2	5.311 6.313	0.01 0.07	28.2067
0.02	Radar 1 Radar 2	16.79 19.97	0 0.07	398.801
1	Radar 1 Radar 2	26.28 29.86	0.08 0.04	690.638
2	-		0.04	1260.96

	Radar 2			1783.37
	Radar 1			2820.67
	Radar 2	63.16	0.02	3989.19

Converting PDMs to Matrices

The makeMatrix() function converts a PDM into a matrix by discarding the independent parameter (domain) and right concatenating the dependent matrices columnwise. If a PDM is an argument to makematrix(), a matrix containing all dependent matrix data is returned:

radar_mx = makematrix(radar)

```
radar_mx (a rectangular matrix) =
       5.311
                 0.01
                          16.79
                                           26.28
                                                     0.08
                                                                       0.04
                                                             35.51
       6.313
                 0.07
                          19.97
                                    0.07
                                           29.86
                                                     0.04
                                                             42.23
                                                                       0.09
```

All Radar 1 values are right-concatenated to form the first row, and all Radar 2 values appear in the second row.

To create a matrix formatted in the same manner as the dependent matrix elements in radar, transpose the PDM—this transposes each dependent matrix separately for each domain element—then transpose the result as shown below. Compare this result to radar and radar_mx.

```
radar_mxTrans = makematrix(radar')'
```

radar_mxTrans (a rectangular matrix) =

```
5.311
           0.01
 6.313
           0.07
16.79
19.97
           0.07
26.28
           0.08
29.86
           0.04
35.51
           0.04
42.23
           0.09
53.11
           0.01
63.16
           0.02
```

When the channels keyword is used, rows of each dependent matrix are right-concatenated to form rows in the resulting matrix:¹

```
radar_mxChan = makematrix(radar, {channels})
```

radar_mxCl	nan (a r	ectangular	matrix) =	
5.311	0.01	6.313	0.07	
16.79	0	19.97	0.07	
26.28	0.08	29.86	0.04	
35.51	0.04	42.23	0.09	
53.11	0.01	63.16	0.02	

Sections of a PDM can also be used as an input to makematrix(). This makes it easy to extract a desired value. For example, to see the range for Radar 2 at 0.01, type:

```
temp=makematrix(radar(1))
temp (a square matrix) =
    5.311     0.01
    6.313     0.07
temp(2,1)
ans (a scalar) = 6.313
```

The SAVE command also has the ability to create matrices from PDMs. When SAVE is called with the matrixx keyword, all saved PDMs are stored as two matrices. The domain is given the name pdmName_t and the dependent matrix data is given the name pdmName_u, where pdmName is the name of the original PDM. This handling is designed to map to simulation data.

Using PDMs with Operators

Operators defined for matrices are also defined for PDMs. For example, the square of each element in the first dependent matrix of radar can be calculated by:

¹ This feature can be used to convert time and frequency responses to a format similar to that used in MATRIXx.

```
| Radar 2 33.9703 0.06803
```

Notice the output is also a PDM.

Operations between two PDMs are defined such that the operation is performed elementwise on each pair of corresponding matrices. These operations are restricted to PDMs with identical dimensions.

For example, the average value of Row 1 and Row 2 is calculated by:

```
(radar(1,1) + radar(2,1))/2
```

RCS	•			
0.01		Radar	1	5.812
0.02	1	Radar	1	18.38
1	İ	Radar	1	28.07
2	İ	Radar	1	38.87
6	İ	Radar	1	58.135

Operators can also be used between matrix objects, including vectors and scalars as well as matrices, and PDMs. In this case, the operation is performed between the matrix object and each dependent matrix in the PDM. The result of the operation is a PDM with the same domain as the PDM operand.

For example, the identity matrix is added to each dependent matrix using the expression:

```
radar + eye(2,2)
ans (a pdm) =
```

RCS	 +	-	% Error
0.01	Radar 1 Radar 2	6.311 6.313	0.01 1.07
0.02	Radar 1	17.79 19.97	0 1.07
1	Radar 1 Radar 2	27.28 29.86	0.08 1.04
2	Radar 1 Radar 2	36.51	0.04

A scalar value can also be used in operators with a PDM. The operation will be applied to each matrix element and the scalar.

Chapter 5

Using Functions with PDMs

When a PDM is used as an input to a function, the function is applied to each dependent matrix as shown in Figure 5-5. If the channels keyword is available and is used, the function will be applied to each channel.

$$\begin{bmatrix} ypdm_1 \\ ypdm_1 \\ ypdm_2 \\ \downarrow \\ ypdm_n \end{bmatrix} = \begin{bmatrix} [f(xpdm_1)] \\ [f(xpdm_2)] \\ \downarrow \\ [f(xpdm_n)] \end{bmatrix}$$

Figure 5-5. Functions of PDMs

For example, if xpdm is a step response of a system with n inputs, m outputs over p time points, then y = max(xpdm) is a $(1 \times 1) \times p$ PDM whose k^{th} element contains the maximum element of the k^{th} matrix in xpdm (the maximum output for every time point). The result of any function that accepts the channels keyword is always a matrix the size of the dependent matrices in the PDM. Refer to Figure 5-6.

Where max(xpdm, {channels}) is an n x m matrix where (i,j) element is the maximum of the vector of the (i,j) elements of all the dependent matrices.

PDMs use optimized internal looping to speed up the total computation time. Therefore, using a single PDM as a function input is much more efficient than looping through a set of separate matrices with MathScript commands.

Next you will use the intrinsic function $\max(\)$ to illustrate the flexibility of PDMs. $\max(\)$ finds the maximum over a specified subset of the PDM data.

$$\begin{aligned} \mathbf{y} = f(\mathbf{x} \mathbf{p} \mathbf{d} \mathbf{m}, & \{\mathbf{c} \mathbf{h} \mathbf{a} \mathbf{n} \mathbf{e} \mathbf{l} \mathbf{s} \}) \\ & \left[f(v_{11}(d_1 : d_p)) \dots f(v_{n1}(d_1 : d_p)) \right] = \left[\begin{pmatrix} (v_{11}) & \dots & (v_{n1}) \\ \vdots & & \vdots \\ (v_{1m}) & \dots & (v_{nn}) \end{pmatrix} d_1 \\ & \downarrow \\ f(v_{1m}(d_1 : d_p)) \dots f(v_{nm}(d_1 : d_p)) \right] = \left[\begin{pmatrix} (v_{11}) & \dots & (v_{nn}) \\ \vdots & & \vdots \\ (v_{1m}) & \dots & (v_{nn}) \end{pmatrix} d_p \\ & \vdots & & \vdots \\ & (v_{1m}) & \dots & (v_{nn}) \end{pmatrix} d_p \end{aligned}$$

Figure 5-6. Functions of a PDM Over Channels

To find the maximum range for both Radar 1 and Radar 2 over all RCS values, apply the function to all rows of the first column of dependent matrices. Type:

```
maxrad = max(radar(:,1))
maxrad (a pdm) =

RCS |
----+----
0.01 | 6.313
0.02 | 19.97
1 | 29.86
2 | 42.23
6 | 63.16
```

max() treats the PDM as a series of matrices, returning a PDM with the same domain as radar. It loops over all the domain points (values of RCS), finds the largest value each dependent vector contains (in this case, the Range value), and returns that scalar value as the dependent matrix corresponding to the same domain point in the output PDM.

You might want to know the maximum ranges for Radar 1 and Radar 2 separately. In this case, the PDM is treated as a matrix of vectors, each corresponding to a channel of the PDM. To use max() in this manner, invoke the channels keyword:

```
maxvals = max(radar(1:2,1), {channels})
maxvals (a column vector) =
   53.11
   63.16
```

The range for Radar 1 corresponds to the (1,1) channel, and the range for Radar 2 corresponds to the (2,1) channel. The (1,1) element of the output matrix, 53.11, is the maximum value for the range of Radar 1 over all the RCS values. The second element is the maximum value for Radar 2.

Dynamic System

The dynamic system class represents systems of time-dependent equations for modeling input/output relationships. In general, there are many different kinds of dynamic systems, with many different representations.

Xmath supports linear, time-invariant systems. These can be continuous (systems of differential equations) or discrete (systems of difference equations). Two specific representations are provided: state-space systems and transfer functions. Both are created with the <code>system()</code> function and are discussed later. Sampling times (0 for continuous systems and nonzero for discrete) are automatically stored within a dynamic system object.

The dynamic system class is closely tied to the PDM class. Simulations or dynamic systems are defined using a PDM to represent inputs, and return a PDM representing the outputs. The * (product) operator has also been overloaded (defined) such that system*input_pdm performs a simulation over the data in input_pdm.

State-Space Systems

A state-space dynamic system stores the *A*, *B*, *C*, and *D* matrices associated with the following equation:

for continuous systems for discrete systems
$$\frac{dx}{dt} = Ax + Bu \qquad x_{k+1} = Ax_k + Bu_k$$

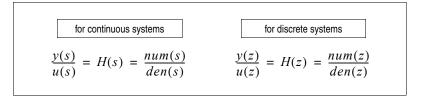
$$y = Cx + Du \qquad y_k = Cx_k + Du_k$$

x is the state vector (with initial conditions X_0), u is the input vector, and y is the output vector. All matrices are stored, even if they are null.

- State-space systems can be single-input/single-output (SISO) or multiple-input/multiple-output (MIMO).
- Names can be attached to each of the inputs and outputs and states of a state-space system. This capability is particularly useful with MIMO systems.

Transfer Functions

A transfer function is described as:



The notations H(s) and H(z) are common for transfer functions. s represents the Laplace transform variable, and z represents the z-transform variable. A transfer function represents a dynamic system in terms of numerator and denominator polynomials.

- A transfer function is *proper* if the order of the numerator is less than or equal to the order of the denominator.
- It may sometimes be convenient to use an *improper* or *noncausal* transfer function (to represent an ideal differentiator, for example). Xmath allows you to define an improper transfer function, but restricts the types of analyses you can perform. You can find the frequency response of an improper transfer function, but not the time response.

An improper transfer function cannot be connected with state-space systems or converted to state space form.

- Currently, only SISO transfer functions are supported.
- Names can be attached to the inputs and outputs of a system in transfer-function form.
- To perform a time-domain simulation (*Sys* × *u*), multiply a system by a PDM whose columns contain the input vector(s) for the simulation(s). Refer to the *Time Response* section.

Creating Systems

Dynamic systems can be created with the system() function. If four compatibly sized matrices are given as inputs, a state-space system is formed.

```
a=[1,2;3,4]; b=[.1,-.1,1; 2,-.2,2]; c=[3,3]; d=[.4,-.4,4];
ssSys=system(a,b,c,d, {inputNames=["red","white","blue"],
  outputNames=["Flag"], stateNames=["Alaska", "Nebraska"], dt=.01})
ssSys (a state space system) =
 Α
  1
       2
  3
       4
 В
  0.1
         -0.1
  2
         -0.2
                  2
 С
  3
       3
 D
  0.4
         -0.4
 \mathbf{x}_0
  0
State Names
Alaska
          Nebraska
```

```
Input Names
-----
red
white
blue
Output Names
```

Flag

System is discrete, sampling at 0.01 seconds.

A handy shortcut for creating state-space systems with an all-zero D matrix is to use a NULL-matrix specifier ([]) for the D matrix. This automatically sets the D matrix to a zero matrix, with row size equal to the row size of C and column size equal to the column size of B.

If dt was not given a value, ssSys would have been continuous. dt defaults to 0.

The size of a system object is defined by the number of outputs, inputs, and (in the case of a state-space system) the number of states it has. You can use the size() function to find these dimensions.

```
[out,in,states]=size(ssSys)?
out (a scalar) = 1
in (a scalar) = 3
states (a scalar) = 2
```

If a pair of polynomials is given, a transfer function results:

```
n=makepoly(polynomial([1,-1;2,-2],"s"));
d=polynomial([-2,1;1,-2],"s");
tfSys=system(n,d,{inputNames="In", outputnames="Out"})
```

tfSys (a transfer function) =

```
s(s + 1)
-----
(s + 1)(s + 3)
initial integrator outputs
0
```

O Input Names
-----In
Output Names
-----Out

System is continuous

The various parts of a transfer function or a state-space system can be extracted with the abcd(), numden(), period(), and names() functions. Refer to the *MATRIXx Help* for more information.

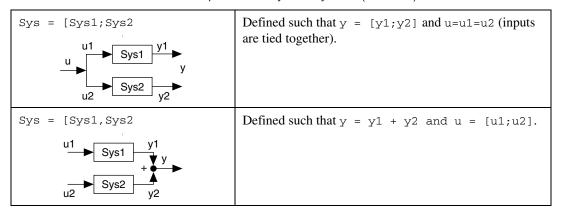
Using Operators with Dynamic Systems

Operators have also been defined to perform connections between dynamic systems. Suppose you have dynamic systems Sys1 and Sys2, where outputs are y1 and y2 and inputs are u1 and u2, respectively. The statements in Table 5-4 would then be true.

Table 5-4. Operations on Dynamic Systems

Sys = Sys1 + Sys2	Defined such that $y = y1 + y2$.		
Sys1 y1 y y y y y y y y y y y y y y y y y	The inputs are tied together such that u=u1=u2.		
Sys = Sys1 - Sys2	Defined such that $y = y1 - y2$.		
Sys1 y1 y y y y y y y y y y y y y y y y y	In the unary case, $Sys = -Sys2$ is defined such that $y = -y2$ ($Sys1=system([],[],[],[])$).		
Sys = Sys2 * Sys1	The cascade connection of Sys1 followed by Sys2.		
u1 y1 u2 y2 u Sys1 Sys2 y	The output of Sys is y2 and the input is u1.		

Table 5-4. Operations on Dynamic Systems (Continued)



Creating Subsystems by Indexing into Dynamic **Systems**

You can index into a dynamic system to create a subsystem comprising a subset of the original inputs and outputs, as shown in Table 5-5.

Table 5-5. Indexing Into a Dynamic System

Sys = Sys1(i,j)	Defined to be a system such that y=y1(i) and u=u1(j).i and j	
	can both be vectors as well, in	
	which case multiple inputs and	
	outputs will be extracted.	

If you are familiar with input/output notation, you may feel that the previous definition (outputs first, inputs second) of indexing seems reversed. It was designed with the traditional definition of a transfer function in mind, where outputs are specified first: $y(s) = Sys(s) \times u(s)$. This definition also led to Xmath's definition of $Sys \times aPDM$ to perform simulation, since in that case $y(t) = Sys \times u(t)$. For a MIMO system with m outputs and n inputs, y is an $m \times 1$ vector and u is $n \times 1$; thus, it makes sense for Sys to be $m \times n$. You can see this if you index into sssys from the Creating Systems section:

Sys2=ssSys(1,3)

2

4

Sys2 (a state space system) =

Α 1 3

```
в
1
2
С
3
    3
D
X0
0
State Names
-----
Alaska
        Nebraska
Input Names
-----
blue
Output Names
Flag
System is discrete, sampling at 0.01 seconds.
```

The output is a SISO dynamic system containing the third column of the B and D matrices.

Functions for Manipulating Dynamic System Objects

Table 5-6 summarizes functions commonly used to manipulate systems. To see a full description of each function, refer to the *MATRIXx Help*.

Table 5-6. Functions Commonly Used to Manipulate Systems

Function	Description
abcd()	Extracts the component A, B, C, and D matrices from a state-space system object. In addition, it returns the initial conditions on the states if a fifth output argument is requested.
	abcd() can be called on systems in either state-space or transfer-function form. If the system is a transfer function, the conversion to state-space is done internally to return A, B, C, and D, although the format of the variable itself remains unchanged. The transfer function must be proper.
discretize()	Converts a continuous system to discrete form.
makecontinuous()	Converts a discrete system to continuous form.
numden()	Returns the numerator and denominator polynomials comprising a SISO system in transfer function form. If the system is in state-space form, an internal conversion is performed to find the transfer function equivalent, but the format of the system variable itself remains unchanged. State-space systems used as inputs to numden () must be SISO. Note that common roots in the numerator and denominator polynomials are not canceled.
period()	period() extracts the sample period (in seconds) of a system. If the system is continuous, period() returns zero.
names()	Extracts matrices of strings representing the input, output, and (if the system is in state-space form) state names of a system. It works much the same as described for PDMs in the <i>Domain and Name Information</i> .
check()	Can be used to return a Boolean indication of whether a system is in transfer-function or state-space form, discrete, continuous, or stable. In addition, check can be used with the convert keyword to change the representation of a system between SISO state-space and transfer-function forms.

Time Response

The behavior of a dynamic system as a function of time in response to external stimuli is referred to as the *time response* of that dynamic system. Xmath can simulate the response of a dynamic system to various inputs to obtain the system's time response. This is accomplished with the * operator between dynamic systems and parameter-dependent matrices (PDMs) and with one or more of the functions in Table 5-7.

Function

Description

impulse()

Computes the impulse response of a system.

initial()

Computes the unforced response of a system to a given initial condition.

step()

Computes the step response of a system.

defTimeRange()

Computes a default time vector for simulations.

Table 5-7. Time Response Functions

Borrowing from the convenient frequency response notation for a system where y(s) = H(s)*u(s), Xmath defines the operation system*ppm as a time domain simulation. Thus, for any dynamic system system*ppm (continuous or discrete) and for a PDM u representing the external stimulus as a function of time, the operation y=Sys*u creates a PDM y that contains the outputs of the system as a function of time.

For a dynamic system with n_y outputs and n_u inputs, the input vector is defined to be $n_u \times 1$ and the output vector is $n_y \times 1$. Thus, the input PDM u should be $n_y \times 1 \times N_{samp}$, where N_{samp} is the number of time points in u.

- The input PDM must have a regular domain.
- If the system is discrete, the domain intervals must be equal to the sampling period of that system.
- If the system is continuous, it is discretized using the exponential (zero-order hold) method, with the sampling interval set equal to the input domain interval spacing. For accurate results, make sure this sampling interval is small enough that discretization effects are negligible.

If you desire to run several simulations with different inputs, you can define a PDM where columns contain the input vectors for the different simulations. Then u will be $n_y \times q \times N_{samp}$, where q is the number of different simulations to be run. The resulting y will be $n_y \times q \times N_{samp}$, with each column of the PDM corresponding to a different simulation.

Refer to the *Strip Plots* section of Chapter 4, *Graphics*, for a explanation of how PDMs are plotted.

Strings

A string object is a sequence of characters enclosed by double quotes. To be recognized as a string, an object must be created with double quotes or be the output of the string() function, which converts numbers to strings.

• You can concatenate strings with the plus (+) operator.

```
c="California";s="Sacramento";
str=""nThe capital of "+c+ " is "+s+"."
str (a string) =
The capital of California is Sacramento.
```

 You can concatenate strings and then use them on the Xmath command line.

```
alias mypath "C:/myhomedir/myexamples/"
display mypath + "engine"
execute file = mypath + "engine"
```

• You can group multiple strings into string matrices (also called *tables*) using the same punctuation as matrices.

```
r=" rest"; i=" ice"; c=" compression"; e="
elevation";
rice=[r,i,c,e];ouch=[82,73,67,69];
sport=[char(ouch)',rice']
```

sport (a rectangular matrix of strings) =

```
R rest
I ice
C compression
E elevation
```

• For strings, size() returns the number of rows and columns of the whole string matrix.

```
size(sport)
ans (a row vector) = 4 2
To find the total number of elements (characters) in a string, use length().
length(sport)
ans (a scalar) = 35
```

Converting Strings and Numbers

Numbers can be converted to strings using the string() function, and strings to numbers using makematrix().

```
aStr=string(32)
aStr (a string) = 32  # result is a string
aNum=makematrix(aStr)
aNum (a scalar) = 32  # result is a scalar
```

The displayed result looks the same; only the object type has changed.

The $\mathtt{ascii}(\)$ function returns the ASCII representation of a single character. The $\mathtt{char}(\)$ function returns the character representation of a single character.

```
ascii("A")
ans (a scalar) = 65
char(65)
ans (a string) = A
```

Special Characters in Strings

Sometimes you may want to format your string output. You can insert a newline with the sequence "n or char(10). To insert a tab, use the sequence "t or char(9). To cause double quotes to appear in a string, use a pair of double quotes ("") or char(34).

```
str=""n2 feet, 3 inches can be shortened to " + "2'3""."; display str
```

```
2 feet, 3 inches can be shortened to 2'3".
```

You can use the DISPLAY command to display a string, variable, or the result of an expression; only the string is displayed (the message ans (a string) = is omitted.)

A string must be enclosed in quotation marks. For example:

```
"What's next?"
```

For more examples refer to the *DISPLAY* topic of the *MATRIXx Help*.

Manipulating Substrings

You cannot use conventional to index into a string, but you can index into a matrix of strings. Refer to the *Indexing with the Colon Operator* (:) section for more information.

Create a matrix of strings:

```
mat=[65:69;97:101]; m=char(mat(1:2,:))
```

m (a rectangular matrix of strings) =

```
A B C D E a b c d e
```

Index into a matrix of strings:

```
bball="The N"+m(1,2)+m(1,1)+...
" is where the action is."
```

```
bball (a string) = The NBA is where the action is.
```

You can use the index() function to find the starting location of a substring within a string.

```
i=index(bball, "ac")
i (a scalar) = 22
```

As mentioned earlier, length () returns the total number of characters in a string. The function stringex () extracts a substring from a string, and the function delsubstr() deletes all instances of a substring. Look up these functions in the *MATRIXx Help*, and notice how you can use them to alter a string, as shown in the following example:

```
bball2=stringex(bball, i, length(bball))
```

```
bball2 (a string) = action is.
```

bball3=delsubstr(bball, bball2)

bball3 (a string) = The NBA is where the

bball4=bball3+"money is."

bball4 (a string) = The NBA is where the money is.

Lists

Lists are created with the <code>list()</code> function. A list object can be thought of as a collection or set of other objects. Each element in the list can be of any arbitrary class, including another list. This makes nested lists possible. A list is one-dimensional, in that it can only be addressed with a single index. The following is an example list:

```
title="Gasoline Prices"; t=1:12; d=1:100;
fg=makepoly([1,2,-.9],"t"); p="p=polyval(fg/t)/d;";
L=list(title,t,d,fg,p)
L (a list with 5 elements) =

1:
    Gasoline Prices

2:
    1 : 1 : 12
    3:
    1 : 1 : 100

4:
    2
    t + 2t - 0.9
5:
    p=polyval(fg/t)/d;
```

A single index can be used to access entire objects from the list.

```
p (a column vector) =
    2.1
    7.1
```

p=polyval(L(4),L(2))'

14.1

34.1

47.1 62.1

79.1

98.1

119.1

142.1 167.1

The plus (+) operator can be used to concatenate two lists.

Index Lists

An index list contains a list of indices or pointers into a vector, matrix, or PDM. An index list looks like a matrix, but matrices cannot be used as lists. The function find() outputs an index list, and you can create your own with indexlist().

An index list has either one, two, or three columns. If it has one column, it can be used to index into a vector. If it has two columns, it can be used to index into a matrix; the first column contains row pointers, and the second column pointers. If it has three columns, it can be used to index into a PDM; the first column is used for domain pointers, the second for row pointers, and the third for column pointers.

```
set seed 0
m=hessenberg(random(4,4))
m (a square matrix) =
   0.211325
                -0.563151
                              0.529676
                                            0.288135
  -1.31969
                 1.47381
                                            0.0170223
                              0.313928
                -0.599434
                              0.164669
                                            0.00777988
   0
                 0
                              0.173159
                                           -0.217164
```

Find the row and column location of each element smaller than 0, and assign the value 3 to it:

```
lis=find(m<0)
lis (an index list) =
  1
        2
  2
        1
  3
        2
  4
        4
m(lis)=3
m (a square matrix) =
  0.211325
                            0.529676
                                         0.288135
                            0.313928
  3
               1.47381
                                         0.0170223
  0
               3
                            0.164669
                                         0.00777988
  0
                0
                            0.173159
                                         3
```

The following example shows the use of a three-column indexlist with a PDM. For a complete discussion of PDMs, refer to the

Parameter-Dependent Matrix (PDM) section. Using the previous matrix, create a PDM with two dependent matrices:

mpdm=pdm(m,[1,2])

mpdm (a pdm) =

domain		 Col 1	Col 2	Col 3	Col 4
1				0.529676 0.313928	
	Row Row	0	3 0		0.00777988 3

The goal is to find all elements of mpdm in row 2 of a dependent matrix that are greater than 0 and less than .5 and set them to 0.1. To do this, first find the location of all elements of mpdm that meet the criteria:

```
mlis=find((mpdm > 0) & (mpdm < .5))
mlis (an index list) =
  1
       1
             4
  1
       2
             3
  1
       2
             4
  2
       1
             3
  2
             4
       1
  2
       2
             3
```

The first column shows the domain, the second the row, and the third the column. Extract the portions of the index list that index elements in row 2 of the dependent matrices.

```
row2=find(mlis(:,2)==2)
row2 (an index list) =
3
4
7
```

Create an indexlist that locates only the elements in row 2 of a dependent matrix that meet the criteria used to create mlis.

```
rlis=indexlist(mlis(row2,:))
```

rlis (an index list) =

1 2 3 1 2 4 2 2 3

Set all elements of mpdm that are greater than 0, less than .5, and in the second row to 0.1:

mpdm(rlis) = 0.1

mpdm (a pdm) =

domain		Col 1	Col 2	Col 3	Col 4
	Row 1	3			0.288135 0.1
2	Row 1 Row 2	0	3 0		0.00777988

MathScript Programming

This chapter describes how you can combine MathScript expressions, statements, commands, and functions to create MathScript programs.

Xmath handles custom MathScript functions (MSFs) and MathScript commands (MSCs) you write in the same manner as it does the pre-defined commands and functions that ship with Xmath (refer to the *Using Predefined Functions and Commands* section of Chapter 3, *MathScript Basics*). MSCs and MSFs can call other MSCs and MSFs, or call themselves recursively.

Overview

This section explains how to create a MathScript function (MSF) and a MathScript command (MSC), giving you a brief overview of the scripting process along the way. In subsequent sections, scripting will be explained in detail, and we will use these samples as a point of reference.

Creating a Sample MSF

User-defined MSFs behave exactly like predefined functions; they take input arguments, perform the statements in the body of the function using these arguments, and return one or more outputs. Input arguments are not modified.

The sample MSF halfwave (Example 6-1) converts all values less than zero to the value of zero. Go to your Xmath working directory and use a text editor to create a file named halfwave.msf, as shown.

Example 6-1 halfwave.msf

```
#{
Function halfwave() has 1 required input argument
}#
Function out1 = halfwave(in1) # function declaration
line
   out1 = in1
```

```
out1(find(in1 < 0)) = 0
endFunction</pre>
```

The file begins with an optional block comment (text enclosed in #{ }#). If supplied, the comment serves as help on this function if you supply a help file (refer to the *Creating Online Help for User-Defined MSFs and MSCs* section). The function declaration is required. This declaration defines the function name, the number and type of input arguments, and the number of output arguments.

To use halfwave, call the function just like any intrinsic MathScript function.

```
y = [1,0,-1,0,1,0,-1,0];
z = halfwave(y)
z (a row vector) = 1  0  0  0  1  0  0  0
```

Creating a Sample MSC

While MSFs return one or more new objects as outputs and cannot modify input arguments (pass by value). MSCs do not return any values, but they can modify input arguments (pass by reference).

As an example of a typical MSC, consider the command graphit (shown in Example 6-2), which takes a single input and plots it on a log-log scale; a legend is supplied if the input is a matrix. Inputs other than a vector or matrix invoke an error message. Go to your Xmath working directory and use a text editor to create the file shown in Example 6-2.

Example 6-2 graphit.msc

```
#{
GRAPHIT plots a numerical input.
}#

Command graphit indata  # command declaration
if !is(indata, {scalar}) & !is(indata, {string})
  if is(indata, {matrix,!vector}) == 1
    plot (indata, {legend})?
  else
    plot (indata, {xlog,ylog,xmax=length(indata),
        ymin=min(indata), ymax=max(indata)})?
  endif
```

¹ This text will be displayed in the Local Help window when you type help halfwave in the Command window command area.

```
else
  error("Input is not worth plotting!","C")
endif
endCommand
```

The first line of the file after the optional block comment (#{ }#) section is the command declaration. The command declaration is required. It defines the command name, and the number and type of input arguments. Notice that the arguments are not in parentheses as they are in functions.

To test this command, call it as follows:

```
a=[1:.01:3];[,c]=size(a);
k = a(1,100:125);
m = k .*. sin(a);
v=[a*5, a*2, a*4, a];
graphit c
graphit m
graphit v
```

In these examples, the argument to graphit is a single variable that requires no parsing; in cases where the argument is a simple token—a single variable or constant, you can separate the command name from the first argument with white space only, and it works. If the first argument is more complex, such as an expression, you *must* also place a comma after the command name. A comma separating the command name from the first argument always works. The following example illustrates this point.

Create the following MSC in your working directory:

```
Command add3nums arg1, arg2, arg3
arg1+arg2+arg3?
endCommand
```

The following usages of this command all work:

```
add3nums 1,2,3
add3nums a,b,d
add3nums a,b-c,d
add3nums a,b,d-c
```

The following produces an error message:

```
add3nums a-c,b,d
```

If you place a comma after the command name, however, the command works:

```
add3nums, a-c,b,d
```

General Rules for MathScript Programs

There are two types of names in MathScript programming: the MathScript name and the filename.

- MathScript names follow the same rules as variable names (refer to the *Rules for Names* section of Chapter 3, *MathScript Basics*).
- MSF and MSC filenames must be lowercase, and they must match the MathScript name.
- All filenames must be unique. For example, creating both name.msf and name.msc is ambiguous. The filename for Xmath to call is undefined.

MathScript File Formats

The file formats are shown in Figure 6-1 and Figure 6-2.

```
#{
    Optional Block Comment
    that may be used for Help
}#

Function [out1,...outn]=fun_name(in1,...inN, {keywds})

# MathScript instructions that operate on the
# arguments.
    Optional Return
...
endFunction
```

Figure 6-1. MSF File Format

#{ Optional Block Comment that may be used for Help }# Command command_Name in1,...inN, {keywds} # MathScript instructions that operate on the # arguments. Optional Return ... endCommand

Figure 6-2. MSC File Format

Comment Header

The optional comment at the top of the file may serve as the online help entry for your MSF or MSC. To display your help for your MSF or MSC in the Local Help window type:

help script_name



Note Refer to the *Creating Online Help for User-Defined MSFs and MSCs* section for additional information about creating online help for your MSF or MSC.

Declaration



Note Refer to the *Creating Online Help for User-Defined MSFs and MSCs* section for additional information about creating online help for your MSF or MSC.

The first line of code following the comment help block is the declaration, which defines the number of input and output arguments. Required arguments are placed before the braces, while keywords are defined inside the braces.

- Files must end with the appropriate end statement (endCommand or endFunction) followed by a carriage return (blank line).
- There can only be one user-defined command or function in an MSF or MSC file (refer to Example 6-3 and Example 6-4 for extended examples of MSCs and MSFs). MathScript Objects (MSO) allow for more than one function or command to be declared in a file. An

optional return statement can be used to exit before the endFunction or endCommand statement.

Void Function Declaration

Although the discussion and examples show both input and output arguments, you can define a void function that has no outputs. The syntax of this function declaration is as follows:

```
function [ ] = void_func_name(in1,...inN, {keywds})
```

MathScript Programming

This section gives an overview of MathScript programming. Some of the functions mentioned here are also discussed in the *Programming* section.

For a detailed description of any function or command provided by MATRIXx, refer to the *MATRIXx Help*.

Assigning Default Values

Optional arguments and keywords typically have default values that will be used if the argument is not specified. The DEFAULT command assigns a default value to the specified argument. In the following function syntax, kwd1 is given a default value of 5.0, and kwd2 is assigned "Earth" by default.

```
function [out1,out2,out3]=funName(in1,in2,{kwd1,kwd2})
  DEFAULT kwd1 = 5.0
  DEFAULT kwd2 = "Earth"
```

Output Keywords

For MathScript programs, output keywords provide a feature whereby desired output can be selected directly by name rather than positionally. For example, consider an MSF defined with this prototype:

```
[01,02,03] = function myfun(i1)
```

To access only the third output of an MSF, use one of the following methods:

• Skip the first two outputs like this:

```
[,,thirdout] = myfun(a)
```

• Use output keywords like this:

```
[thirdout = o3] = myfun(a)
```

For a general discussion of keywords, refer to the *Keywords* section of Chapter 3, *MathScript Basics*

Calling Void Functions

When you call a void function, you must use the following syntax:

```
[ ] = void func name(...)
```

Refer to the *Void Function Declaration* section.

Variable Scoping

All variables created within MathScript functions and commands are local unless you use an explicit partition name (partitionName.variableName). Remember, you cannot change partitions within a program.

For MSFs, input arguments are passed by value. This means that functions cannot alter the values of their arguments. Output arguments requested by the caller are copied back to the scope of the caller.

For MSCs, arguments are passed by reference and can alter the values of their arguments, rename them, or delete them altogether if the argument is a variable name.



Note If you get an error message from Xmath indicating that your file is incomplete, your file may be missing an ending carriage return.

Creating Online Help for User-Defined MSFs and MSCs

You can provide online help for your MSF or MSC in one of the following ways:

- Provide a help file in the same directory as your MSF or MSC.
- Allow Xmath to use the block comment at the top of your MSF or MSC if you do not provide a help file.

When you try to bring up help for your MSF or MSC by typing the following command

help script_name

Xmath follows these steps:

- 1. Xmath searches for the help topic name in the standard Xmath Help project file (help.hpf).
 - If Xmath finds your help topic, it displays it in the MATRIXx Help window
- 2. If Xmath does not find an Xmath help topic, it looks in the local help project file (local.hpf).
 - If Xmath finds your help topic, it displays it in the Local Help window.



Note On UNIX systems, local.hpf is in your home directory. On Windows systems, local.hpf also exists in your home directory if the home directory is defined; otherwise, you can find local.hpf in %XMATHTMPDIR%.

- 3. If Xmath does not find the help topic in the local help project file, it looks in the same directory as your MathScript file for a help file with the name <code>script_name.html,script_name.htm</code>, or <code>script_name.txt</code>.
 - If Xmath finds your help file, it displays it in the Local Help window and appends the topic name to the local.hpf file.
- 4. If Xmath does not find a help file, it goes to the MathScript itself, extracts the text in the comment section at the top, and creates a text file (script name.txt) that contains the extracted information.

On UNIX systems, Xmath stores the <code>script_name.txt</code> file in your home directory. On Windows systems, Xmath stores the <code>script_name.txt</code> file in your home directory if the home directory is defined; otherwise, Xmath stores the file in <code>%XMATHTMPDIR%</code>.

Xmath displays the help topic in the Local Help window and appends the topic name to the local.hpf file.

Using User-Defined MSFs and MSCs

Your MSF or MSC can be called in the same way as Xmath functions and commands. However, Xmath must know where to look for them.

Search Paths

When you call a MathScript program, Xmath looks for it in the search path using the following criteria:

- The current working directory (.) is put in the search path when Xmath starts up.
- The search path is searched only upon the first call to the MSF or MSC.

 You can use DEFINE and UNDEFINE to select or deselect an MSF or MSC.

For example, if halfwave.msf is not found in the search path, you receive the following message:

```
File halfwave not found
```

If this occurs, add the new directory to the search path with the command set path "directory" where directory can be any valid directory path string. Assuming halfwave.msf is in the subdirectory myScripts, you add its path as follows:

```
set path "myScripts"
show path
1) .
```

myScripts

Manipulating Search Paths

If the file graphit.msc is in the directory test, you can add this entry to the Xmath search path as follows:

```
set path "test"
show path

1) .
2) myScripts
```

3) test

To remove an entry from the Xmath search path, use the REMOVE command and the path number.

```
remove path 2
show path
1) .
2) test
```

To handle paths through a file selection box, use **Settings»Path**. In the **Path Editor** dialog box, click **Add Path** to select a directory to add to the path.

DEFINE

By default, Xmath looks for built-in functions and commands (refer to the *Using Predefined Functions and Commands* section of Chapter 3, *MathScript Basics*) before searching user paths. The DEFINE command explicitly associates an MSF or MSC with a MathScript name. It is useful for accessing functions that are not in the search path. For example, the Xmath function hilbert () is stored in the following location:

whatis hilbert

```
hilbert is an ISI function (path/hilbert.xf)
```

where path is the path to your Xmath installation. Suppose we have an MSF called hilbert.msf located in a subdirectory called funs, and we would rather use it for Hilbert computations. To make and verify the change, type:

```
define hilbert, {directory = "funs"}
whatis hilbert
```

```
hilbert is a Mathscript function (funs/hilbert.xf)
```

All calls to the hilbert() function will now use the function located in funs instead of the predefined function. To retrieve the predefined function, release your local version of hilbert(), and then verify with the whatis() function:

```
undefine hilbert
whatis hilbert
```

```
hilbert is an ISI function (path/hilbert.xf)
```

For more information on DEFINE and UNDEFINE, see the *MATRIXx Help*.

MathScript Program Compilation and Execution (.xf, .xc)

When a program is defined or called for the first time, Xmath compiles the program and stores the resulting binary code in an .xf or .xc file, depending on the file type. Refer to Figure 6-3.

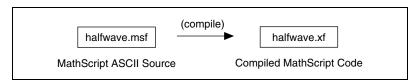


Figure 6-3. Compile Process for an MSF

When halfwave is called again, the Xmath interpreter checks the last modified dates of halfwave.xf and halfwave.msf. If halfwave.msf is more recent, the ASCII .msf file is recompiled, overwriting the existing .xf file. After compilation, the new halfwave.xf binary file is executed.

You can use the following command to turn off file usage time stamp checking:

```
SET AUTOCOMPILE OFF
```

If you know that you will not be modifying a source file, this can improve the speed of a task such as calling an MSF in a loop.

If a new version of Xmath is installed, old local .msf and .msc files are automatically recompiled.

Examples

Example 6-3 provides a sample user-defined MSF called pdm2mx. This MSF changes a PDM to a matrix of the same dimensions as the input matrix. This is to reverse any PDM formatting so that you can compare the dependent dependent matrices of a PDM with the source matrix for the PDM.

Example 6-3 pdm2mx.msf

```
#{-----
Destructs a PDM to a matrix of the same dimensions as the input
matrix. Idea is to reverse any PDM formatting so that you can compare
a PDM's dependent matrices with, for example, the original matrix the
PDM was created from.
Syntax:
         Function [mat,same]=pdm2mx(m,p)
                A matrix to compare to the elements of a PDM.
Inputs:
                A PDM with elements you wish to organize in a
          р
                matrix of the same dimensions as m.
Outputs:
         mat A matrix of elements of p formatted according to m.
          same If mat and m are the same, same=1. If not, same=0.
Function [mat,same]=pdm2mx(m,p)
[mr,mc]=size(m); [pr,pc,pl]=size(p);
if is(m, {matrix}) & is(p, {pdm}) & mr*mc==pr*pc*pl
```

```
if mr==pr & mc==pc
    mat=makem(p')';
else
    mat=makem(pdm(makem(p')',{rows=mr, columns=mc}));
endif
    if any(mat-m) <> 0; same=0; else same=1; endif
else
    error("Matrix and PDM must have same number of elements.","C")
endif
endFunction

    A call to pdm2mx might be:
b=rand(6,3)? bp=pdm(b,{rows=3,columns=6})
[,same]=pdm2mx(b,bp)
```

The command plotspectrum in Example 6-4 takes PDM input and plots the original wave and its magnitude spectrum in the Graphics window. plotspectrum uses check to see if the input is a PDM. If the input is a PDM, the length of the PDM channels is returned from length() to the variable len.

Example 6-4 plotspectrum.msc

```
#{plotspectrum first uses check() to see if the input is a PDM. If the input
is a PDM, the length of the PDM channels is returned from length() to the
variable len. The domain of the PDM is a vector stored as in am.}#

command plotspectrum input

stat = check(input, {pdm,abort});len = length(input);
dm = domain(input);

#compute the fft of the input, and the frequency range

qPDM=fft(input,{channels});
res = (len-1)/(len*(dm(len)-dm(1)));
dmF=(0:res:(len-1)*res);
output = pdm(abs(makematrix(qPDM)), dmF);

#{set up the frequency axis label. The x label on the spectral graph is
generated using + to append strings together. The final string is stored in
xLab.}#
```

The Graphics window will display the time and spectrum plots.

Programming

This section describes MathScript functions, commands, and constructs used for programming.

Iterative and Conditional Looping Statements

Loops provide the ability to repeat a command or sequence of commands, either for a fixed number of iterations or until some criterion is met. You can also exit a loop with the EXIT statement as described in the *MATRIXx Help*.

For

The For command executes a statement or a set of statements for a specified number of iterations. If a statement contains a variable on which the loop_variable operates, the order of execution is as follows:

- If the variable is a column vector, the order is top to bottom of the column vector.
- If the variable is a matrix, the order is by columns, moving from left to right.
- If the variable is a row vector, the order is from left to right.

The For loop syntax is as follows:

```
For loop_variable = vector
    statements
endFor
```

A line break acts as a terminator in this construct. A comma, a semicolon, or the DO keyword can be used. For example, the following formats are correct:

```
For x=1:n, statements; endFor
For x=1:n; statements; endFor
For x=1:n DO statements; endFor
```

While

A While loop iterates as long as a conditional expression is TRUE. The While loop can be structured as follows:

```
While conditionalExpression
statements
endWhile
WHILE conditionalExpression, statements; ENDWHILE
WHILE conditionalExpression; statements; ENDWHILE
WHILE conditionalExpression DO statements; ENDWHILE
```

lf

If executes a statement or set of statements when a particular condition is met; if the condition is not met, any else or elseIf statements are executed.

The syntax for an if statement is:

```
If condition
statements
elseIf condition
statements
else
statements
endIf
```

A line break acts as a terminator in the above construct, or a comma, a semicolon or the THEN keyword can be used. For example, the following variations are correct:

```
IF condition, statements ELSE, statements ENDIF
IF condition; statements ELSE, statements ENDIF
IF condition THEN statements ELSE, statements ENDIF
```

For example:

```
if input < cost
   display "Please deposit: "+ string(cost-input)+ " cents"
elseif input > cost
   display "Your change is: "+ string(input-cost)+ " cents"
else
   display "Thank You."
```

Or, for example:

```
IF in1 | in2 < 1 THEN x=0; ELSE x=1; ENDIF
```

Goto and Labels

A goto and corresponding label can be defined in a MathScript function (MSF), MathScript command (MSC), or MathScript object (MSO) file (not in a .tt file); goto cannot be used interactively. The goto command causes a jump to a specific label in the program. A label is a name enclosed in angle brackets; labels must be unique within a script.

For example, an MSF, MSC, or MSO file might have the following:

```
If input > cost & change < input-cost
    GOTO exact # jump to <exact>
endIf

#{
definition of label exact
}#
<exact>
display "Please use exact change only."
```

Object Query Functions

These functions are useful for testing the validity of input arguments of MathScript entities. To see the full set of available keywords for each function, refer to the *MATRIXx Help*.

exist()

exist() checks to see if an object is defined with the given name. exist() returns TRUE(1) if the object is defined, and FALSE(0) otherwise.

```
a = 1; exist(a)
ans (a scalar) = 1
delete a
exist(a)
ans (a scalar) = 0
```

check()

check() performs multiple checks on a variable and prints out error messages (by default); check() is similar to is, but has additional features including error reporting, two-input comparisons, and conversions between different object types. Both functions are useful in programming and often used interchangeably.

check() only operates on variable names (you can use is if your input is an expression); check() can also compare certain properties of two inputs, such as sameClass or sameRate. See the *check* topic in the *MATRIXx Help* for a listing associated keywords.

• By default, check() automatically reports an error when the keyword list does not match the input object. If you type:

```
a = [1,2,3,4];
t = check(a,{symmetric})
```

t (a scalar) = 0 is displayed in the log area, and the following message appears in the error log window:

Specified argument to check must be symmetric.

To turn off reporting, specify !report in the keyword list; the status
of check() is still displayed in the log area, but the message is
suppressed.

The abort keyword highlights a specific argument and returns an error message; the statement does not execute until the appropriate correction is made.

check() can accept two inputs, and compare them:

```
a = [1:4]; b = [3:5];
check(a,b,{samelength, !report})
```

- ans (a scalar) = 0
- check() can be used to make the following conversions:
 - single channel PDM \leftrightarrow vector
 - polynomial ↔ vector
 - row \leftrightarrow column

When the convert keyword is used, the input is a variable; if all keyword requirements are met, the input variable is converted to the appropriate keyword format.

<code>check()</code> converts p from a PDM to a vector. Refer to the *check* topic of the $MATRIXx\ Help$ for a complete description of <code>check()</code> and its keywords.

is()

is () accepts a variable name or an expression as an input, and then determines if the input variable is of the type specified in the keyword argument. is () returns 1 if TRUE and 0 if FALSE.

```
tmatrix = [1,3;0,1];
is(eig(tmatrix), {identity})
ans (a scalar) = 0
is(tmatrix, {triangular})
ans (a scalar) = 1
```

is () can be used to report errors as follows, notice that the error () function can only be used in a MathScript program:

```
if !(is (a,{symmetric})); error("Argument must be
symmetric.")? endif
```

Many keywords can be used with is (); refer to the is topic and the check topic in the MATRIXx Help for details about these keywords.

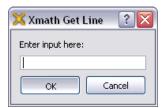
User Interface Functions

Xmath provides the simple graphical user interface functions getline(), getchoice(), pause(), error(), and beep(). For more sophisticated tools, refer to Chapter 9, *Graphical User Interface*.

qetline()

```
getline() pops up a dialog box with a prompt asking for input.
response = getline("Enter input here:")
```

The dialog box appears.

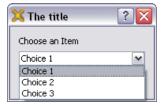


You will not be able to enter text in the Command window until the dialog box is closed. If the string returned from getline () must be converted into a number, use the makematrix () function. It is overloaded to handle strings.

```
response (a string) =
                        2.333
response = makematrix(response)
response (a scalar) =
                        2.333
```

getchoice()

getchoice() pops up a dialog with choices defined by an input string matrix. By default the dialog will have radio buttons, which allow only one choice. If the multiple keyword is used, the dialog will have check boxes, which allow more than one selection. If the keyword defaultChoice is specified, certain choice(s) are pre-selected when the dialog appears.



The output variable returns the user choice(s) as a scalar or vector.

pause()

This command displays a dialog with a button that must be pressed before Xmath will continue. pause() is commonly used in .ms files to view a graph in the Graphics window.

If a string is added to the pause () command, that string will appear in the Xmath Pause dialog.

```
plot(1:10)
pause "press Continue to see the next plot"
plot(random(1,10))
```



You can disable pause () with the following command:

set pause off

error()

error () can only be used inside MathScript entities. You supply a severity code of W, C, S, or F to signify the type of error: warning, confirmation, strong warning, or fatal. The operating system and the error severity determine where the error is displayed:

- For all operating systems, F aborts execution; the instruction remains in the command area with the error highlighted, and the error message is displayed in the message area.
- On Windows operating systems, all error messages remain in the Xmath Commands window; W, C, and S settings display your message in the log area.
- On UNIX, C and S settings display a dialog with the error message you specified. W writes your message to the message area.

Refer to the MATRIXx Help for additional details.

```
if is(Input2, {!matrix})==1
    error("Not a matrix!", "F", Input2)
endif
```

If the error criterion is met, the string **Not a matrix!** is written to the commands window message area.

beep()

beep () causes an audible beep; on UNIX, it also displays a dialog box. beep "this is a test"



Indexing Functions

This section is a brief overview of indexing functions that are useful in programs. For detailed descriptions of these functions, refer to the *MATRIXx Help*.

index()

index () finds the starting location of a substring within a string. If the substring is not found -1 is returned.

```
s="What is the meaning of this?";
i=index(s,"this")
i (a scalar) = 24
```

find()

find() returns an index list of the elements in the matrix that meet the specified condition. An index list is a matrix containing the row and column locations (the indices) of all elements that meet the condition.

```
a = [20,4,-14;30,-65,0;48,582,29]
a (a square matrix) =

20     4    -14
30     -65     0
48     582     29
elements = find(abs(a)>25)
elements (an index list) =

2     1
```

Using the Xmath Debugger

The Xmath Debugger can be controlled interactively from the **Xmath Debugger** window, shown in Figure 6-4, or from the command area. This section describes both interfaces.

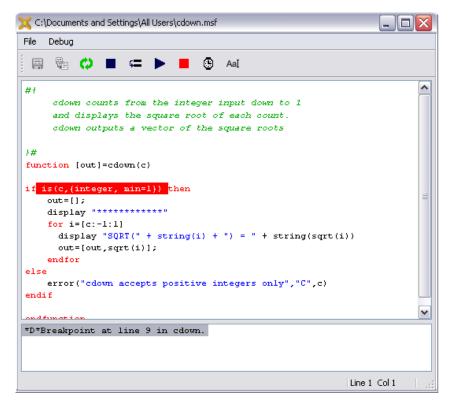


Figure 6-4. Xmath Debugger Window in Debug Mode

Debug mode starts under any of the following circumstances:

- A call is made to a program that is set up for debugging.
- A program contains a syntax error. A syntax error is an error in punctuation, for example, a missing brace: plot(a, {xlab="A missing brace").
- A program contains a runtime error. A runtime error occurs when an instruction is impossible to process. The following statement would cause a runtime error because the objects are incompatible: x=5 + "hello".

Debug

You can use the debug command to define and set break for a program. In the command window command area, type:

debug program_name

If you activate debug for a program, the debugger opens automatically on the first executable line in the script whenever you call the entity. While in debug mode you can step through your file and evaluate any expression or run any command. In addition, the NEXT and SET BREAK commands can be used to debug nested functions.

Debug Mode

In addition to the above cases (where you are intentionally debugging a specific MSF or MSC), a programming error also invokes the **Xmath Debugger** window in debug mode (refer to the *SET DEBUGONERROR* section).

Stepping Through a Script

- In the command area debugger you can step forward, using the next command, or continue execution with the go command.
- You can set and remove break points from the Xmath Debugger window or the command area (refer to the Setting, Showing, and Removing Breakpoints section).
- You can set and remove watch points from the Xmath Debugger window or the command area (refer to the Setting and Removing Watchpoints section).

Exiting Debug Mode



- To stop debugging from the Xmath Debugger window, click End Debug, shown at left.
- To stop debugging from the command area, type abort.

To close the window, select **File**»Close.





When the **Xmath Debugger** window is not in debug mode, it is acts as an editor. To fix your script, first click the **Allow Edit** button, shown at left. Then, click into the Debugger window and make your change. If you modify the script through the **Xmath Debugger** window, the **Save** and **Revert** buttons become active, and you can no longer step through. Before saving, make sure that the script file is not open in any other editor.

SET DEBUGONERROR

The environmental setting debugonerror determines the mode in which the debugger will appear.

- The default setting is On. If an error is detected in a program, Xmath opens the debugger and redirects focus to the **Xmath Debugger** window (refer to the *Debug Mode* section).
- If debugonerror is set to On, and you have activated debugging for a program with debug program_name, the debugger opens in debug mode whenever the entity is called.
- If debugonerror is set to Off, and you have activated debugging for a program with debug program_name, the debugger opens whenever the entity is called, but focus stays in the Commands window.

Setting, Showing, and Removing Breakpoints

A breakpoint causes the debugger to stop execution at a specific line number in the source, provided that set debugonerror on is in effect (the default).

- If you issue the command DEBUG NAME a break is automatically set on the first executable line of the script, causing the debugger to open whenever that script is called.
- You can set a breakpoint interactively in the Xmath Debugger window, or from the Commands window command area.



Note In order to set a breakpoint interactively, the file in which you wish to set or remove breakpoints must currently be open in the Xmath debugger in debug mode.



To set a breakpoint in the **Xmath Debugger** window, position the cursor in the line where you want to break execution, then click the **Set Break** button, shown at left. Note that when you position the cursor in this window, the line number is shown in the lower-right corner of this window.

or

Go to the command area and type:

SET break lineNumber

• To see a list of the breakpoints you have set, go to the Xmath command area and type:

SHOW break

A list of breakpoints will appear in the format fileName:Line_Number. You will see breakpoint line numbers for

fileName:Line_Number. You will see breakpoint line numbers for all entities that have debugging enabled.

 Breakpoints can be removed from the command area with the REMOVE command. Again, you must be viewing this script in debug mode. Go to the command area and type:

REMOVE break lineNumber

As mentioned earlier, all scripts that have been called or explicitly defined automatically have a breakpoint set on the first executable line. Type SHOW debug to see the files you are debugging.

• To run a file without stopping at its breakpoints, go to the command area and type:

DEBUG program name off

Note, however, if the script contains an error, the debugger will open regardless.

Setting and Removing Watchpoints

A watchpoint causes the debugger to stop execution whenever a watched variable is modified.

You can set a watchpoint interactively in the **Xmath Debugger** window or from the command area. The script containing the variable you want to watch must currently be shown in the debug window in debug mode:

- To set a watchpoint interactively, go to the Xmath Debugger window, highlight the variable you want to watch, and click the Set Watch button (shown at left).
- To set a watchpoint with the set command, go to the commands window command area and type:

set watch varName

Now you can use the **Xmath Commands** window to display the values of variables that are local to the current MSF or MSC.



To see a list of the variables you are watching, go to the **Xmath Commands** window (while in debug mode) and type:

show watch

A listing appears in the format functionName: varName.

Watchpoints can be removed by using the remove command. The entity containing the watchpoints you want to remove must currently be shown in the debug window in debug mode. Go to the Command window command area and type:

remove watch varName

If you want a function to run without stopping at the watchpoints but you do not want to remove them, type

debug program_name off

in the command area.

For more information about using the **Xmath Debugger** window, enter help xmath debugger in the Xmath command area.

Advanced Topics

This section includes the following topics:

- Variable arguments
- Executing a function at a specific directory
- Partition and variable directory functions
- MathScript command output and error capture
- Programming for platform independence

Variable Arguments

When you use the colon (:) index operator in a MathScript entity declaration, the program handles a variable number of inputs, outputs, or keywords. The function <code>argn()</code> returns the number of program arguments, whereas <code>argv()</code> extracts the value and name of the argument.

argn()

argn() returns the number of inputs (the default), keywords, or outputs for a MathScript entity (refer to Example 6-5). To get the number of keywords, specify the keyword, keywords; to get the number of outputs, specify the keyword, outputs.

Example 6-5 argn()

```
function [args]=howmany(:)
   args=argn()
endfunction
```

Example 6-5 counts the number of inputs. For example, howmany (1,1,1,1) returns 4.

argv()

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argv() allows you to index into the inputs, keywords, or outputs for a program. argv() can return the value and/or name of the argument; for argv() to return the name of the argument, however, it must be a keyword. To return the name of an output, the calling statement must use output keywords (refer to the *Output Keywords* section).

Using argn and argv

Example 6-6 uses the argn () to determine the number of inputs and loop over them accordingly. argv () gets the value of each argument, and then the length is determined for the output.

Example 6-6 argv() combined with argn()

```
function out=howlong(:)
n=argn();
for i=1:n
   in=argv(i)
   out(i)=length(in);
endfor
endfunction
x=howlong(rand(2,3),1:7,pdm(ones(4,5),{rows=2}))?
x (a column vector) =
   6
   7
```

Example 6-7 accepts any number of scalars; it displays a message when the keyword reply is specified but not otherwise.

Example 6-7 msg.msf

```
function [out] = msg(:, {reply})
ni=argn()
nk=argn({keywords});
[v,n] = argv(ni);
ni=ni-nk;
if n=="reply"
  key=1;
else
  key=0;
endif
for i=1:ni
  if is(argv(i), {!scalar})
     error("Scalars Only!", "C");
  else
     out(i) = argv(i);
  endif
  if key==0 & i==ni
    out;
  endif
  if key==1 & ni==1
    display "Thanks for the scalar!";
  elseif key==1 & i==ni
   display "Thanks for the " + string(ni) + " scalars!" ;
  endif
endfor
endfunction
msg(1,1000,pi,{reply})
Thanks for the 3 scalars!
ans (a column vector) =
     1
  1000
     3.14159
msg(5,5,9)
```

ans (a column vector) =
5
5
9

Example 6-8 provides the function varargs (), which has a variable number of outputs, inputs, and keywords. In the following call:

```
[out1=fop1, out2=fop2]=varargs(1,2,3,{k=9})
```

Notice that we define two outputs (fop1, fop2), three inputs, and one keyword (k).

Within the function, argn() is used to determine the number of arguments, and argv() is used to determine the name of the arguments. Notice the use of the [value, name] = $argv(i, {keywords})$ syntax for inputs and keywords and the name= $argv(i, {outputs})$ syntax for outputs. Notice also that the function itself does not assign a value to the outputs.

The output of the previous call appears in Example 6-9. The names of the keyword and the outputs appear in the output stream; the names of other input arguments are NULL.

Example 6-8 varargs.msf Using argn and argv

```
function [:] = varargs(:,{:})
for i=1:argn({keywords})
[v,n] = argv(i, \{keywords\})?
                     # display value and name of
end
                            # keyword inputs
display "-----"n"
for i=1:argn({!keywords})
[v,n] = argv(i, \{!keywords\})?
                      # display value and name
end
                            # of non-keyword inputs
display "-----"n"
for i=1:argn()
[v,n] = argv(i)?
                             # display value and name
end
                             # of all inputs
display "-----"n"
for i=1:argn({outputs})
n = argv(i, {outputs})?
                             # display name of all outputs
end
endfunction
```

Example 6-9 Output of varargs.msf

```
v (a scalar) =
n (a string) =
            k
v (a scalar) = 1
n is null
v (a scalar) =
            2
n is null
v (a scalar) =
n is null
_____
v (a scalar) = 1
n is null
v (a scalar) =
n is null
v (a scalar) =
            3
n is null
v (a scalar) =
n (a string) =
_____
n (a string) = fop1
n (a string) = fop2
```

To assign values to the outputs fop1 and fop2, the function needs an assignment statement(s), which must be a text string. For example, the following loop assigns the outputs with the values 1 and 2, respectively:

Executing a Function at a Specific Directory

The function assignment syntax used in calling an LNX in background mode allows a directory to locate the function to be specified with a keyword. For example:

```
[out] = (define myfunc, {directory="mydir"})(1,2,3)
```

where Xmath calls the MSF or LNX function myfunc () in the directory mydir, leaving an existing definition of myfunc () unchanged.

Partition and Variable Directory Functions

The function <code>directory()</code> allows directory listings of Xmath partitions and variables to be captured as vectors of string names. The <code>directory()</code> function requires one input, a string containing a wildcard as used in the command <code>WHO</code>, and produces one output, a vector of names of partitions and variables as produced by the command <code>WHO</code> using the specified wildcard. The names are always full names, and the partition name is always prefixed. The syntax is shown in the following example:

```
out = directory("main.*")
```

where the variable out will contain a vector of strings of the variable names found in main (for example, main.a, main.b, and so on.).

MathScript Command Output and Error Capture

The following syntax allows the textual output and error messages of a MathScript command to be captured in MathScript variables as string values:

```
[outputs = format, errors] === statement
or
[outputs, errors] === statement
```

where outputs and errors are MathScript variable names and statement can be any valid MathScript statement. The format keyword formats the output in a command-dependent way; refer to the following examples for details.

If the outputs variable is specified, the textual (nongraphical) outputs of statement, if any, are inserted into the outputs variable instead of displaying in the Xmath log area of the Commands window. If the outputs variable is omitted, the output of statement is displayed normally.

If the errors variable is specified, Xmath will suppress normal processing (error location highlighting, bringing up the Debugger window, and stopping command execution) of any errors generated by statement. Instead, the error messages are converted to text and inserted into the errors variables. If errors is omitted, Xmath performs normal error processing of errors generated by statement.

This error capture feature allows a program to perform error handling of commands that may fail as shown in the following *Examples* section.

Examples

In the following example of error handling, if the variable name contained in the string varname is a legal Xmath variable name, err would be a null; otherwise, err would contain an error string. For example:

```
varname = getline("Please enter an Xmath variable
name:");
[,err]===execute varname + "=1;"
```

In the following example of error handling, any error calling myfunc is converted into an error message and inserted into err as a text string:

```
[,err] === myfunc(123)
```

In a similar example, the variable out captures the output of the Windows dir command in a string:

```
[out] === oscmd("dir")
```

In the following example, out contains a formatted version of the captured output:

```
[out=format] === statement
```

Currently, the who and SHOW PARTITIONS commands support this formatting. The directory() function described in the *Partition and Variable Directory Functions* section uses both these commands. For example,

```
DIRECTORY("main.*")
```

actually executes this statement:

```
[out=format] === who main.*
```

The captured output is a vector of strings containing the names of the variables in the partition main.

When [out=format] is used with other statements that do not support formatting, the captured output will be a vector of strings, each of which contains a line of output. By default, the length of the row vector out is the number of strings (and therefore the number of lines in the captured output). You can transpose out to see the output strings as they are normally displayed in the Xmath log area.

```
[out=format] === rand(2,2)
size(out)
out'?
```



Note This syntax cannot be nested.

Programming for Platform Independence

While MathScript is portable across UNIX and Windows platforms, calls to the operating system are platform-dependent. For example:

```
oscmd("ls *.xmd") # UNIX
oscmd("dir *.xmd") # Windows
```

With the MathScript function platform(), you can program a command so that it can be run on either platform. For example:

```
if platform() == "UNIX"
    oscmd("ls *.xmd") # UNIX
else
    oscmd("dir *.xmd") # Windows
endif
```

Another problem area with cross-platform programming is the directory path name syntax difference. The <code>get({path})</code> function is useful in reconciling these differences. The <code>COPYFILE</code> command, for example, makes use of the <code>get({path})</code> function to provide a platform-independent way of copying files. For more information, refer to the <code>MATRIXx Help</code>.

MathScript Objects

This chapter outlines the procedure for writing and using your own MathScript object (MSO). Before writing an MSO you should have a good understanding of object-oriented concepts and Xmath objects in particular. Chapter 5, *Data Objects and Operators*, introduces each intrinsic Xmath object and the operators that are overloaded for that object. You should also be proficient in the MathScript language. Refer to Chapter 3, *MathScript Basics* and Chapter 6, *MathScript Programming*.

As described in Chapter 5, *Data Objects and Operators* you can easily augment these intrinsic objects by designing your own custom objects using MathScript.

MSO Overview

The MathScript object feature enables you to create custom high-level objects for use in the Xmath environment. Object development in Xmath fundamentally involves determining what data defines the instance of an object, writing the initializer function and creating the various commands, functions, and operators which can manipulate object instances. The complete definition of an object and its behavior is encapsulated within an MSO file. The structure and contents of an MSO file are described in greater depth in subsequent sections.

Careful thought should be used when developing objects, especially those which will be shared among a number of people. The object author should design, test, and document objects *before* allowing others to use them. Once an MSO is in use, any changes to the definition of the class variables will create inconsistencies between current and future instances that may be difficult to identify.

Object Instantiation

Once an object is defined by creating an MSO file, object instances can be created from the Xmath command line or within any script using the following syntax:

instance = myobject(parameters);

This statement executes the initializer function of the object by using the supplied input parameter(s). The output of this expression is an object instance. An object instance is recognized as an Xmath variable; this implies that it can be operated on by Xmath commands such as SAVE, LOAD, and DELETE, copied with the assignment operation, passed as a parameter to a function or command, and returned as a function output.

The object instance is a container that stores the persistent *class variables* that characterize a particular instance. The syntax for accessing a class variable is the same as the syntax for addressing a variable in another partition. For example, if an object named myobject contains a class variable named sigma, then that variable can be accessed with the following statement:

instance.sigma

MSO File Format

MSO file format structure adheres to the rules in the *General Rules for MathScript Programs* section and the *MathScript File Formats* section of Chapter 6, *MathScript Programming*, with one exception. The MSO file format accommodates multiple constructs in a single file. This enables you to use a single file to define the object, overload or create pertinent functions and commands, and overload operators to support the new object. Example 7-1 illustrates the structure of an MSO file.

Example 7-1 Sample MSO File Format

```
Command memCmd <type>input {kwds}
    ... MathScript statements
endCommand
```

• If *MATRIXx Help* is desired, supply a help file or begin the file with commented text that will serve as the help text.



Note You provide online help for MSOs the same way as for MSFs and MSCs; refer to the *Using User-Defined MSFs and MSCs* section of Chapter 6, *MathScript Programming* for more details.

- The body of the file consists of programming constructs. The first construct in the file must be the *initializer function* for the object. The initializer function contains the MathScript statements which are executed by Xmath whenever a new instance of this object is created. The initializer function is explained in greater detail in the *Initializer Function* section.
- Optional constructs to define or overload MathScript functions and commands that act on your object can follow the initializer function in any order, as discussed in detail in the *Member Functions* section.
- Optional constructs to overload operators can also appear anywhere after the initializer function, as discussed in detail in the *Operator Overloading* section.

Using MSOs in Xmath

The process for defining an MSO is identical to that for other MathScript entities (refer to the *Using User-Defined MSFs and MSCs* section of Chapter 6, *MathScript Programming*). Just include the MSO files you need in your Xmath path. Alternatively, you can define them explicitly with the DEFINE command:

```
define mymso, {directory="/myHome/myobjects/my_mso"}
```

Xmath dynamically loads an MSO definition into memory only when it is necessary.

Initializer Function

The initializer function is a special function that is executed to create a new instance of an object. It is the only required component in an MSO, and it must be the first construct in the MSO file following the optional help text. The syntax for an initializer is the same as MathScript functions, except

that the initializer is declared between the statements Object and endObject. All other rules in the *General Rules for MathScript Programs* section and the *MathScript File Formats* section of Chapter 6, *MathScript Programming*.

The following is a simple initializer function is shown below.

```
Object[y]=mymso(a1,{b1})
    ... MathScript code
endObject
```

Class Variables

An object instance is characterized by persistent variables that are stored within the object instance, similar to the way variables are stored within a partition. The initializer is responsible for creating an instance and storing the class variables within the instance. After object instances have been created, any other constructs defined in the MSO file can access the class variables.

There are three types of class variables: required, optional, and computed. Examine the following code fragment:

- Required variables, such as a1 in the previous example, must be specified by the user when the object instance is created.
- Optional variables, like b1, are optional input arguments to the initializer.
- Computed variables, such as y1, are calculated by the initializer, typically as a function of the input arguments.

Any number of required, optional, or computed class variables may be defined for an object. The DEFAULT command is sometimes useful to give optional and computed variables a default value.

When the initializer completes execution, a class variable that exists within the function scope will be stored within the object instance. The MathScript statements within the initializer can modify or delete any class variable. As a result, required, optional, or computed arguments may or may not exist within an object instance, depending on statements in the initializer.

Variables created in the body of the initializer that are not class variables are considered temporary and are automatically deleted when the initializer

completes execution. If you want a variable to be persistent, specify it as a computed variable.

When an object initializer is called, the result of that statement is always a single instance of the new object. The defined outputs, such as y1 in the above initializer function, are used to create a computed class variable (as opposed to the output of an ordinary function).

The following is a sample initializer function for the new object mysys. Notice that this object does not have any computed variables. They are not required.

```
Object mysys(a,b,c,d, {dt})
    ... MathScript code
endObject
```

You would create an instance of mysys as follows:

```
inst= mysys(1,2,3,4);
```

After the input variables are created within the object and given their appropriate values, the initializer is called in the scope of the inst object. The initializer checks the arguments for correctness, sets any optional arguments that require a default value, and then calculates the output arguments based on the inputs. When the initializer is complete, all local variables are deleted from the object.

Nested Objects

Any class variable can be an instance of another object. As a result, you can create quite complex nested object hierarchies. If a required or optional class variable is an object, the user must create an instance of the nested object and supply it as an input to the initializer. If a computed class variable is an object, the initializer itself will create the instance of the nested object.

For example, consider the following nested object embedded within two other objects.

```
Object nested(z)
    ... MathScript code
endObject

Object supplied(<nested> x)
    ... MathScript code
endObject
```

```
Object [x] = computed(y)
    x=nested(y)
    delete y
endObject
```

To create an instance of the object supplied, the user would type the following:

```
a = nested(1);
b = supplied(a);
```

However, to create an instance of the object computed, the user only types the following:

```
c = computed(1);
```

Type Declaration

Type declarations are qualifiers that can optionally precede each input argument for functions, commands, and operators defined in an MSO. They create a restriction that an argument must be an instance of a particular type of object.

The syntax of a type declaration is to specify the name of an MSO within a set of angle brackets immediately before any input argument.

In the initializer function shown in the previous example, the type declaration <alien> specifies that any instance of an object of type alien will be accepted as the second argument.

Arguments that do not have a type declaration indicate that any object will be accepted when this function, command, or operator is called.

The Xmath interpreter uses type declarations for two purposes:

- Ensure that parameters passed to user-defined functions and commands are the correct type. If a mismatch is encountered, Xmath will automatically generate an error message.
- Facilitate function, command, and operator overloading by limiting the
 use of certain constructs to a specific combination of input arguments.
 The use of type declarations to achieve overloading is described in
 detail in a later section.

Operator Overloading

The ability to customize the behavior of operators in Xmath to manipulate MSOs is called operator overloading. Operator definitions containing MathScript statements that should be executed to achieve the desired behavior are placed within an MSO file. The syntax of an operator definition is similar to that of a function definition, with the exception that the operator behavior is declared between the Operator and endOperator statements. For example, to define the plus (+) operator to add two apple objects together, you would insert the following construct in apple.mso.

```
Operator y = + ( <apple>left, <apple>right)
    ... MathScript code
endOperator
```

Multiple operator definitions may be required for the same operator to completely define all possible object combinations. For example, if you have an apple.mso and an orange.mso, you would need the following three operator definitions in addition to the one above to describe all possible combinations of adding apples and oranges.

```
Operator y = + ( <apple>left, <orange>right )
    ... MathScript code
endOperator

Operator y = + ( <orange>left, <apple>right )
    ... MathScript code
endOperator

Operator y = + ( <orange>left, <orange>right )
    ... MathScript code
endOperator
```

Operator definitions can be inserted in any of the MSO files that are declared as arguments. So the two operators that combine apples and oranges can appear in either the <code>apple.mso</code> or the <code>orange.mso</code>. However, because Xmath searches MSO files from the left argument to the right argument, it is more efficient to put the operator definition in the MSO file corresponding to the first argument.

Type declarations, like <apple>, tell the Xmath interpreter which operator definition to choose from when performing operations that deal with objects. For unary and binary operator definitions, at least one of the

arguments must have a type declaration for the MSO in which the operator definition resides.

Type declarations are not required on all arguments. If a type declaration is not specified, Xmath will accept any variable for that argument. For example, the following operator will add an apple object to any type of object including intrinsic Xmath objects such as matrices, strings, etc.

```
Operator y = + ( <apple>left, right )
    ... MathScript code
endOperator
```

The MathScript code within such an operator should check unqualified arguments and restrict inputs to the object types that the MathScript code can properly handle; an error should be returned if the conditions are not met.

Operators that can be overloaded are listed in Table 5-1.

Unary operators act on a single variable and their operator definitions will have only one input argument. Binary operators act on two variables and their definitions will have two input arguments. The – operator is both a unary and binary operator and Xmath will automatically select the correct definition from an MSO file based on the number of declared arguments.

```
Operator y = - ( <apple> arg)
    ... MathScript code
endOperator

Operator y = - ( <apple>left, <apple>right )
    ... MathScript code
endOperator
```

The comma and semicolon operators are special operators that can accept two or more operands. For example, the following operator definitions describe two combinations of different types of objects manipulated by the comma operator.

```
Operator y = , ( <obj1>one, <obj2>two )
    ... MathScript code
endOperator

Operator y = , ( <obj1>one, <obj2>two, <obj3>three )
    ... MathScript code
endOperator
```

The comma operator definitions above would correspond to the following two types of expressions, assuming a, b, and c are of the appropriate type:

```
case1 = [a,b];
case1 = [a,b,c];
```

The comma and semicolon operators can also be used in compound expressions. In the following example, a and b would first be resolved using the appropriate comma operator to produce an intermediate result, then, c and d would be resolved with the appropriate comma operator to produce a second intermediate result. Finally, the two intermediate results would be resolved with the appropriate semicolon operator.

```
result = [a, b; c, d];
```

When the comma or semicolon operators act on an operand of heterogeneous types, a separate operator definition is required for each specific combination of operands, as was illustrated in the previous examples. However, the variable argument construct (:) can be used when all operands are of the same type (refer to the *Variable Arguments* section of Chapter 6, *MathScript Programming*). The variable argument construct also has the advantage that a single operator definition can generically handle any number of operands. The following definition of the comma operator illustrates the variable argument syntax:

```
Operator y = , ( <special>: )
    n = argn();
    for i = 1:n
        x = argv(i);
        y = ...
    endfor
endOperator
```

The colon argument (:) instructs Xmath that any number of operands will be accepted by this definition, all of which must be of type special. The argn() function, which requires no inputs, will return the number of operands. The argv(i) function accepts an integer between 1 and the number of operands and will return a copy of the requested operand. Consequently, the variable argument operator definitions can be generically programmed with loops to handle any number of homogeneous operands.

The insertion and extraction index operators are also special operators. The insertion index operator enables indexing into an object instance on the left side of the equal sign in an expression. In the following example, inst is

an instance of an MSO called myObj, and the following expression attempts to insert 10 into the second element of the inst object.

```
inst = myObj(a);
inst(2) = 10;
```

The extraction index operator enables indexing into an object instance on the right side of the equal sign in an expression. For example, the following expression attempts to extract the value from the fifth element of the inst object.

```
ans = inst(5);
```

The definition of the insertion and extraction index operators would have the following structure and would reside in the myobj.mso file.

The argument i would contain the element indices 2 and 5 from the previous examples at runtime. The argument y would contain the value to be inserted or the result to be extracted to or from the object. The MathScript code within the index operator should check and restrict the input arguments (i and y) to only object types with values that the MathScript code can properly handle; an error should be returned if the conditions are not met.

The word Object in the above declarations is a reserved token which instructs Xmath that this is a special operator that will execute directly within the scope of the object instance. In other words, the MathScript code within these operators can directly access the class variables within the instance. For example, consider a situation where the variable \times is a class variable of myObj. The MathScript code within a binary plus (+) operator would have to reference \times with the statement left. \times or right. \times , but the index operator can reference \times directly with the statement \times . Take care that the declared arguments of the operator (y and i) do not overwrite the class variables of the object.

The index operators can accept any number of operands, as long as an operator definition with the appropriate number of arguments resides in the MSO file of the object. To also handle two-dimensional indexing for the myObj example object, the following two operators, each with two index arguments, i and j, would be required.

```
Operator Object(i,j) = y
... Mathscript code
endOperator

Operator y = Object(i,j)
... Mathscript code
endOperator
```

The index operators also support the variable argument construct to handle any number of operands generically. The following extraction index operator illustrates the variable argument syntax for the index operator.

```
Operator y = Object(:)
    n = argn();
    for i = 1:n
        x = argv(i);
        y = ...
    end
endOperator
```

Member Functions

Your MSO should include any functions or commands that use your object.

 Member functions and commands behave like MSFs and MSCs with the exceptions that they cannot be debugged individually unless they are uniquely named.

Once your MSO is defined, MSO member entities can be called from the Xmath command area, or other MathScript files.

You can overload existing commands and functions to operate on your object. For example, the following function overloads the function max() to accommodate the MSO type group.

```
function [out]=max(<group>a)
  out=max(a.data)
endfunction
```

When a function or command is overloaded, its behavior is limited to the cases specified in the function header. For example, the overloaded version of max will only be enabled if the input is a group object.

 The file need not contain all the code for each new function or command. Using LNXs for complex numerical operations will speed up execution considerably. You can identify member functions with the whatis command. For example:

```
whatis other
```

```
other is a member function (./other.mso)
```

Member function and command definitions do not include help text;
 their help text should be included with the help text for the MSO.

Sample MSO

The MSO shown in Example 7-2 defines an object named group. This MSO will accept any single row matrix. This MSO overloads the min() and max() functions to support this object. It also overloads binary and unary minus (-), *, +, and binary and unary equality. You can find this example in \$XMATH/examples/mso/group.mso.

Example 7-2 group.mso

```
#{-----
```

The group object is an unordered collection of unique whole numbers which can be manipulated by operators that adhere to conventional set theory. We are using the name "group" for this object so it does not conflict with the "set" command in Xmath.

A new group is defined using the group initializer. For example:

```
s1 = group([1,2,3,4]);

s2 = group([3,4,5,6]);
```

Binary group operators are defined as follows:

Unary group operators are defined as follows:

```
endif
  data = sort(data); // check for duplicate elements
  [,n] = size(data);
  for i = 1:n-1
    if data(i) == data(i+1)
      error("Non-unique element", "F", data);
    endif
  endfor
endObject
#-----
# Overload of max
#-----
function [out] = max(< group> a)
 out=max(a.data)
endfunction
#-----
# Overload of min
#-----
function [out] = min(< group> a)
 out=min(a.data)
endfunction
#-----
# Unary Minus
#-----
Operator y = - (\langle group \rangle a)
 y = group(-a.data);
endOperator
#-----
# Difference
#-----
operator y = -(<group> a, <group> b)
  [,cols]=size(a.data)
 y = null;
 temp = null;
  for i = 1:cols
   loc = find(a.data(i) == b.data )
   if( loc == null )
    temp = [temp,a.data(i)];
   endif
  endfor
```

```
if (temp <> null)
    y = group(temp);
  endif
endoperator
#-----
# Intersection
#-----
operator y = * (<group> a, <group> b)
  [,cols]=size(a.data)
  y = null;
  temp = null;
  for i = 1:cols
   loc = find(a.data(i) == b.data )
   if( loc <> null )
     temp = [temp,a.data(i)];
   endif
  endfor
  if (temp <> null)
    y = group(temp);
  endif
endoperator
#-----
# Union
#-----
operator y = + (<group> a, <group> b)
  c = b - a;
  y = group( [a.data,c.data] );
endoperator
#-----
# Equality
#-----
operator y = == (<group> a, <group> b)
  y = 0
  [,acols]=size(a.data)
  [,bcols]=size(b.data)
  if( acols <> bcols )
   return
  endif
  res = a.data==b.data
  if( check(res, {nonzero, !report}) )
   y = 1
  endif
```

endoperator

Limitations

- Member entities and operators cannot have their own online help.
- You cannot explicitly define or debug a member function, command, or operator, only the object initializer. Consequently, if you alter the definition of a member entity, you must UNDEFINE it before the new definition can be used.
- A MathScript object cannot be passed into an LNX, but the class variables from a given instance can be passed into an LNX as other variables are.
- You cannot assign or access a variable using an expression that
 contains more than one dot. This implies that if an object instance
 contains another MSO as a class variable, you cannot directly access
 the class variables of the nested object. For example, the following
 syntax is not allowed:

```
x = obj1.obj2.var;
```

This limitation can be circumvented if you use a temporary variable:

```
temp = obj1.obj2;
x = temp.var
```

External Program Interface

This chapter describes the three Xmath interfaces for user programs written in C, C++, or FORTRAN:

- The User-Callable Interface (UCI) mechanism allows a user program to call Xmath as a server.
- The LNX (LiNked eXecutable) mechanism allows a subroutine in a user program to be callable by Xmath as if it were a regular MathScript function.
- Any C or C++ program can call the functions XmathSave() and XmathLoad() to save and load Xmath data files.

Overview

A user program using the LNX or UCI mechanism is termed an LNX or UCI program, or simply an LNX or UCI. Table 8-1 summarizes the differences between an LNX and a UCI.

Table 8-1. LNX and UCI Comparison

Feature	Comparison
Purpose	A UCI starts Xmath; an LNX is started by Xmath.
Data Structure	Both use the same data structure, the externType.
Functions	<pre>UCI: Must use XmathStart() and XmathStop(); must not use XmathMain().</pre>
	LNX: Must use XmathMain(); must not use XmathStart() or XmathStop().
Build	Both must include a C header file called xmathlib.h and link with a library called libXmath.a (for UNIX) and xmath.lib (for Windows).
Running	UCI: Start Xmath with -call (a switch that triggers the UCI), the program that is calling Xmath, and any other desired startup options.
	LNX: An LNX can be called just like any other MathScript function.

Xmath also provides two functions, XmathSave() and XmathLoad(), which allow an external program to save and load Xmath data.

The Xmath directory \$XMATH/src contains code examples for the LNX and UCI utilities, as well as a sample makefile. \$XMATH/include has include files for LNX and UCI scripts.

LNX

The LNX utility allows you to invoke C, C++, or FORTRAN subroutines from within Xmath. After an LNX is built, it can be used in the same manner as any MathScript function. Furthermore, an LNX can be invoked in background mode so that it can run in parallel with Xmath.

Sample LNX Program

An LNX written in C program has the layout shown in Figure 8-1. Each LNX program contains one LNX function. The LNX function performs a specified calculation and has the following format:

```
void LNXfunc(nlhs, lhs, nrhs, rhs)
int nlhs, nrhs;
externType **lhs, **rhs;
{
    ...
}
```

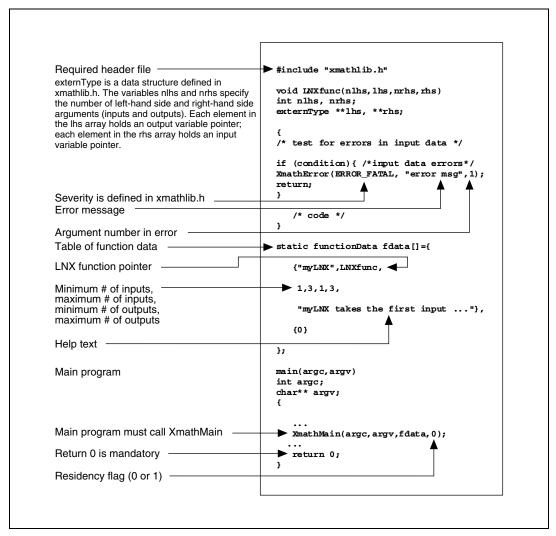
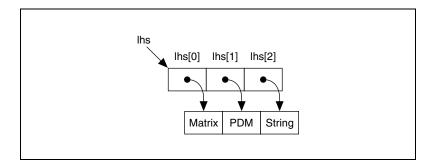


Figure 8-1. Typical C Language LNX Program Format

The input arguments reside in an array of externType pointers to which the variable rhs (right-hand side) points. The integer nrhs (number of right-hand side arguments) defines how many externType pointers are in the array.

An LNX function writes its outputs to 1hs, which is an array of nlhs pointers allocated by Xmath. For example, if nlhs=3 (indicating that your

LNX was called with three outputs), you might allocate a matrix for the first input, a PDM for the second, and a string for the third:



UCI Programs

The User Callable Interface (UCI) lets an external C program invoke Xmath as a child process, send and receive data to and from Xmath as shown in Figure 8-2, and execute MathScript statements. A UCI has the layout shown in Figure 8-3.

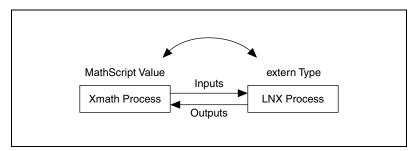


Figure 8-2. Calling Xmath from an External Program (UCI)

```
Required header file
                                    #include "xmathlib.h"
                                    main(argc,argv)
Main program
                                    int argc;
char** argv;
                                         XmathStart(""); /* Starts Xmath */
                                         /* Calls to XmathGet, XmathPut, XmathExecute, etc....*/
XmathStop(""); /* Stops Xmath */
                                         return 0:
```

Figure 8-3. Typical C Language UCI Program Format

Compatibility

If an existing LNX or UCI compiled for an older version of MATRIXx is intended to be run in a new version of MATRIXx, we recommend that you rebuild the LNX or UCI using the new version of MATRIXx to maintain currency with the new compiler, DLLs, and OS supported by the new version of MATRIXx.

Sometimes the IPC protocol in the Xmath LNX or UCI library changes due to bug fixes and enhancements. An existing LNX or UCI must be rebuilt using the new version of the MATRIXx LNX or UCI library (libXmath.a/xmath.lib). If you attempt to run a previous version of an LNX or UCI, Xmath displays the following message:

Process failed to load (incompatible ipc version).

externType Data Types

The file \$XMATH/include/xmathlib.h contains the data structures for externType data types and related function declarations. This file must be included in all LNX and UCI programs and programs that call XmathSave() (refer to the *XmathSave()* section) and XmathLoad() (refer to the *XmathLoad()* section).

An externType is an external version of an Xmath data value such as matrix, string, and PDM. These are detailed in the following subsections.

If you allocate memory for the externType data type with an Allocate*() function, you need to remember to deallocate the memory with the corresponding Delete*() function, especially before re-using the variable. The function tables in this section provide the names of these functions for each data type.

Matrix Data Type

The externType et_matrix corresponds to a MathScript scalar matrix value.

```
typedef struct {
   externType et;
   int rows, columns, isReal;
   double *real, *imag;
} et_matrix;
```

The Boolean member isReal indicates whether the matrix is complex (isReal = 0) or real (isReal = 1).

Table 8-2 lists the functions provided in the LNX functions used to allocate a new matrix, convert arrays to the matrix structure, and delete existing matrices.

Table 8-2. et matrix Functions

Function	Description and Prototype
AllocateMatrix()	Allocates a matrix:
	<pre>et_matrix* AllocateMatrix(int rows,int columns,int isReal);</pre>
WrapMatrix()	Converts single or double arrays into a real or complex matrix.
	<pre>et_matrix* WrapMatrix(int rows,int columns double* real,double* imag);</pre>
	Both input arrays must be previously allocated and of type double. If the matrix is real, use the NULL pointer 0 as the imag argument.
	This function does not copy the input data; therefore, do not delete the original arrays after calling WrapMatrix().
DeleteMatrix()	Deallocates storage associated with the et_matrix input argument.
	<pre>void DeleteMatrix, (et_matrix* the_matrix)</pre>

String Data Type

The externType et_string corresponds to the MathScript string value.

```
typedef struct {
  externType et;
  int len, rows, columns;
  char *buf;
  char **array;
} et string;
```

- array is an array of char* with dimensions defined by rows and columns.
- buf points to the string in the first row, first column of array. The
 integer len defines the length of this string. len does not have any
 significance for any of the other strings in array.

For a summary of the et_string type functions, refer to Table 8-3.

Table 8-3. et_string Type Functions

Function	Description and Prototype
AllocateStringMatrix()	Creates an et_string structure that can hold strings up to length len.
	<pre>et_string* AllocateStringMatrix(int rows,int columns,int len))</pre>
	The length of the string does not include the termination character.
WrapString()	Converts a previously defined string to the et_string data type:
	et_string* WrapString(char *buffer);
WrapStringMatrix()	Converts a previously allocated array of strings to a string matrix object (LNX string data type).
	et_string* WrapStringMatrix(int rows,int columns,char** buffer))
	Wrapping functions WrapStringMatrix() and WrapString() do not perform any copying of strings; therefore, do not delete the original input strings after calling a wrap function.
DeleteString()	Deallocates storage associated with the structure et_string.
	<pre>void DeleteString, (et_string* the_string)</pre>

PDM Data Type

The PDM data structure et_pdm is defined as shown in the following examples:

```
typedef struct {
    externType et;
    et_matrix *iv;
    et_string *name;
    et_string *columnNames;
    et_string *rowNames;
    et_matrix *theData;
    int rows, columns;
}
```

The meaning of each member is described in the following PDM:

```
testpdm=pdm([1:3; 4:6; 7:9; 10:12],101:1:104,{rowNames = "leaves",
    columnNames = ["birch", "elm", "oak"], domainName = "time"}):
```

Figure 8-4 shows the PDM testpdm and the et_pdm struct mapped to its parts.

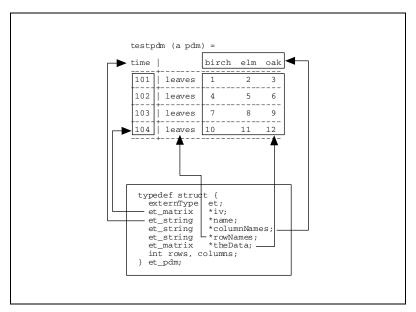


Figure 8-4. Mapping the et_pdm Structure to a PDM

Figure 8-5 shows how the information from testpdm is assigned to the fields of the et_pdm structure. Use AllocateMatrix() and AllocateStringMatrix() to build the PDM components, and WrapPDM() to form the PDM. For a summary of these functions, refer to Table 8-4.

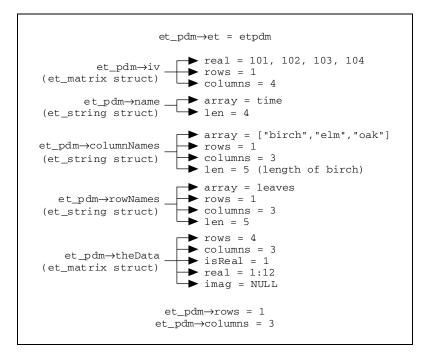


Figure 8-5. et_pdm Data Structure

Table 8-4. et_pdm Functions

Function	Description and Prototype
WrapPDM()	et_pdm* WrapPDM(et_matrix *iv, et_matrix *theData, int rows, int columns, et_string *name, et_string* columnNames, et_string* rowNames) Inputs must be previously defined using AllocateMatrix() and AllocateStringMatrix(). Like the other wrapping functions, no copying is done, so do not delete the input after the call.
DeletePDM()	Deallocates storage associated with the et_pdm input argument.
	<pre>void DeletePDM(et_pdm* the_pdm)</pre>

List Data Type

The externType et_list corresponds to a MathScript list object.

For a summary of et_list functions, refer to Table 8-5.

Table 8-5. et list Functions

Function	Description and Prototype
AllocateList(Allocates a list:
)	et_list* AllocateList(int N)
DeleteList()	Deallocates storage.
	<pre>void DeleteList(et_list* N)</pre>

Null Data Type

The NULL data type corresponds to the Xmath NULL value ([]).

Table 8-6. et_null Functions

Function	Description and Prototype
AllocateNull(Allocates a null:
)	et_null* AllocateNull()
DeleteNull()	Deallocates storage.
	<pre>void DeleteNull(et_null* N)</pre>
DeleteAny()	(Generic deallocation) Deallocates any externType you allocate.
	<pre>void DeleteAny(externType*)</pre>

LNX and UCI Functions

The functions available for use in LNX and UCI programs (described in *Building and Calling LNX and UCI* section) are described in the following sections. A summary of these functions appears in Table 8-7.

Table 8-7. LNX Functions

Function	Description
XmathMain() (for LNX only)	Sets up the communication facility and transmits information about the LNX back to Xmath; it then transfers control to your LNX function. Upon completion, the results are transmitted back to Xmath.
XmathCommand()	Executes Xmath commands and provides access to command and error output.
XmathDisplay()	Displays a message to the Xmath log window.
XmathError()	Allows you to report errors and make log entries. Severity levels are described in the file \$XMATH/include/xmathlib.h. The argument in error will be highlighted in the Command Window command area.
XmathExecute()	Executes Xmath commands. Xmath windows (except for the commands window and the debugger) are created as needed. XmathExecute() returns 0 if successful and an error string otherwise.
XmathGet()	Retrieves the value of a variable from Xmath. XmathGet () returns 0 if successful and an error string otherwise.
XmathLoad() (for any C or C++ program)	Creates externType values from an Xmath data file.
XmathPut()	Copies the contents of a data structure to the Xmath environment.
XmathSave() (for any C or C++ program)	Saves externType values to an Xmath data file.
XmathStart() (for UCI only)	Starts Xmath. option is a char* that is reserved for future Xmath invocation options. The option must be an empty string ("") for this version.
XmathStop() (for UCI only)	Terminates the Xmath process immediately. Modified variables will not be saved.

XmathMain() (for LNX only)

XmathMain() sets up the communication facility and transmits information about the LNX back to Xmath; it then transfers control to your LNX function. Upon completion of the LNX function, the results are transmitted back to Xmath. For an example, refer to Figure 8-1.

```
int XmathMain(int argc, char **argv, functionData*
fData, int flag);
```

The flag argument to XmathMain specifies whether the process remains resident. If this argument has the value LNX_RESIDENT, the process is *resident*. It remains in memory across invocation until Xmath is exited or the LNX is undefined by issuing the UNDEFINE command in Xmath. If the flag argument to XmathMain() is 0, the process is *nonresident*. It is terminated after each invocation and a new process started.

If an LNX function is called often, then it is advisable to make the process resident. If the user function allocates a large amount of memory and is called infrequently, then it is more memory efficient to make the LNX nonresident.

The functionData data structure is typically used as follows:

```
static functionData fdata[] ={
    {"userFun",userFun,minIn, maxIn,minOut,maxOut,help},
    {0}
}
```

Figure 8-1 shows functionData in relation to the rest of an LNX.

- fdata is the name of an array that holds the function data. Although it is an array, Xmath currently uses only the first element.
- "userFun" is the name of this LNX; the lowercase version of this name must match the filename of the executable LNX program.
- userFun is the pointer to the function itself.
- minIn, maxIn are the minimum and maximum number of input arguments, respectively. For example, if userFun must be called with no less than two, and no more than four inputs, minIn is 2, and maxIn is 4.
- minOut, maxOut are the minimum and maximum number of output arguments, respectively.

Every time userFun is called, Xmath automatically verifies that the number of input and output arguments is in the valid range.

• The optional help text entry is a char* pointer; 0 can be used if there is no help. The help text can span multiple lines (as shown in Example 8-1). For an additional example on formatting help, see \$XMATH/src/fasthilb.c.



Note You can provide a help file for your LNX just as you can for MSFs, MSCs, and MSOs in the same directory as your LNX. If Xmath finds no help file, it uses the optional help text within the LNX itself. Refer to the *Creating Online Help for User-Defined MSFs and MSCs* section of Chapter 6, *MathScript Programming* for details.

• The mandatory array terminator {0} comes last.

Example 8-1 Sample Help Text

```
/* Define the online help */
#define Help "\
Description: Produces an n x n matrix\n\
with each element multiplied by -1.\n\
n
Syntax:
            C = negate(A) \n
\n\
            A is a matrix or PDM.\n\
Inputs:
n
            C is a matrix or PDM.\n\
Outputs:
\n\
Examples: a = 1:10; negate(a) ?\n
\n\"
```

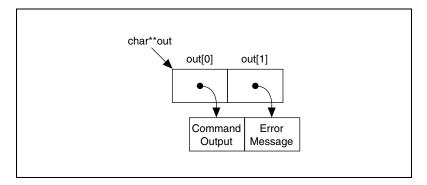
XmathCommand()

```
{\tt XmathCommand()} is an enhanced version of {\tt XmathExecute()} providing access to command and error output. The syntax is as follows:
```

```
char **XmathCommand(char *command,int options);
```

The return value of XmathCommand() is a static array of two pointers of type char*. The first pointer points to command output, or 0 if none or not

requested. The second pointer points to an error message caused by the command, or 0 if none or not requested. This can be illustrated as follows:



The options parameter is a bit mask defined with the following macros:

XMCMD_OUT

Returns command output.

XMCMD_ERR

Returns command errors.

Both of these macros are used in the following example:

```
char *xmcmd = "foo(bar)?";
char **out = XmathCommand(xmcmd,XMCMD_OUT|XMCMD_ERR);
if (out[0]) {
    printf("The output of \"%s\" is %s\n",xmcmd,out[0]);
    free(out[0]);
}
else
    printf("\"%s\" has no output\n",xmcmd);
if (out[1]) {
    printf("\"%s\" resulted in the error:
%s\n",xmcmd,out[1]);
    free(out[1]);
}
else
    printf("\"%s\" has no errors\n",xmcmd);
```



Note The error message string returned by XmathCommand() is memory allocated with the C library function malloc(). To free this string, use the C library function free().

XmathDisplay()

XmathDisplay() displays a message to the Xmath Log window. The syntax is as follows:

```
void XmathDisplay(char *message);
```

An example of using this function follows:

```
XmathDisplay("Have a nice day.");
```

This output appears in the Xmath log area.

XmathError()

XmathError() allows you to report fatal and warning errors as well as log entries. The syntax is as follows:

```
void XmathError(errorType error, char* message, int
arqNum)
```

Severity levels are described in the file \$XMATH/include/xmathlib.h. You can specify ERROR_FATAL, ERROR_WARNING or ERROR_LOG. You must also specify the input argument number that is in error (a scalar between 1 and the number of right-hand side arguments), or specify 0 to indicate the function itself. The argument in error will be highlighted in the Command Window command area.

The following code fragment uses XmathError() to check whether the first input is a matrix.

```
if (*rhs[0]!= ETMATRIX) {
    XmathError(ERROR_FATAL, "Input must be a matrix!",
1);
    return;
}
```

This code fragment checks if the matrix is real:

```
x=(et_matrix*)rhs[0]
if (!x->isReal) {
    XmathError(ERROR_WARNING, "Matrix is not real!", 1);
}
```

In the previous example, we cast the first input into x, an et_matrix pointer, then check to see if it is real.

XmathExecute()

XmathExecute() executes Xmath commands. Xmath windows (except for the commands window and the debugger) will be opened as needed.

XmathExecute() returns 0 if successful and an error string otherwise.

```
char *XmathExecute(char *cmd)
```

For example, this call opens the Graphics window:

```
XmathExecute("plot(random(2,3))?");
```

This call opens the help window:

```
XmathExecute("help bode;");
```



Note The command string must end with a question mark (?) or semicolon (;).

For an example of how to use XmathExecute(), refer to Example 8-2.



Note The error message string returned by ${\tt XmathExecute}(\)$ is memory allocated with the C library function ${\tt malloc}(\)$. To free this string, use the C library function ${\tt free}(\)$.

XmathGet() and XmathPut()

 ${\tt XmathGet(\)}\ and\ {\tt XmathPut(\)}\ retrieve\ and\ modify\ Xmath\ variable\ values.$

XmathGet()

 $\label{thmathGet} \begin{tabular}{ll} $\tt XmathGet()$ retrieves the value of an Xmath variable. It sets the second argument to {\tt externType*}. {\tt XmathGet()}$ returns 0 if successful and an error string otherwise. The syntax is as follows: \\ \end{tabular}$

```
char *XmathGet(char* name, externType** data)
```

For example:

```
er_string = XmathGet("data", (externType**)&data);
if (er_string != NULL)
    printf("ERROR: %s", er_string);
switch(*data) {
    case ETMATRIX:
        M = (et_matrix*)data;
        break;
case ETSTRING:
        S=(et_string*)data;
        break;
```

```
case ETPDM:
    P=(et_pdm*)data;
    break;
}
```

Notice how the externType pointer is dereferenced to determine the actual data type.

XmathGet() allocates storage for Xmath variables. If you re-use the variable, be sure to deallocate the storage prior to an XmathGet call. For an example of how to use XmathGet(), refer to Example 8-2.



Note The error message string (er_string) returned by XmathGet() is memory allocated with the C library function malloc(). To free this string, use the C library function free().

XmathPut()

XmathPut() creates or modifies an Xmath variable with a given data value. The first argument (name) must be a valid Xmath variable name. The second argument (data) is a pointer to one of the external types described in the externType Data Types section on. XmathPut() returns 0 if successful and an error string otherwise. The syntax is as follows:

```
char *XmathPut(char *name, externType* data)
```

For example:

```
/* allocate a real-valued Matrix struct */
x = AllocateMatrix(n, 1, 1);
/* fill up some local data */
ptx = x->real;
pty = y->real;
for (i = 0; i < n; i++) {
    *ptx = (double)i;
    *pty++ = sin(*ptx);
    *pty++ = cos(*ptx++);
}
/* send local x over to Xmath as variable x */
er_string = XmathPut("x", x);</pre>
```

```
if (er_string != NULL) {
   printf("ERROR: %s", er_string);
   free(er_string);
}
```

For an example of how to use XmathPut(), refer to Example 8-2.



Note The error message string (er_string) returned by XmathPut() is memory allocated with the C library function malloc(). To free this string, use the C library function free().

Example Using XmathGet(), XmathPut(), and XmathExecute()

Example 8-2 combines the use of the last three functions discussed.

Example 8-2 Using XmathGet(), XmathPut(), and XmathExecute()

```
n = 10:
y = AllocateMatrix(n, 2, 1);
/* fill up some local data */
pty = y->real;
for (i = 0; i < n; i++)
   *pty = (double)i;
/* copy data over to Xmath*/
er_string = XmathPut("y", y);
if (er_string != NULL) {
   printf("ERROR: %s", er_string);
   free(er_string);
/* execute the function */
er_string = XmathExecute("y = log(abs(y));");
if (er_string != NULL) {
   printf("ERROR: %s", er_string);
   free(er_string);
   }
/* Free up existing memory associated with y
   before executing XmathGet() */
DeleteMatrix(y);
er_string = XmathGet("y", (externType**)&y);
if (er_string != NULL) {
   printf("ERROR: %s", er_string);
   free(er_string);
   }
```

XmathSave() and XmathLoad()

XmathSave() and XmathLoad() make it possible for a C or C++ program to save and load files in Xmath format without starting Xmath. Both functions make use of the externVar data structure:

```
typedef struct {
   char *name;
   externType *value;
} externVar;
```

The variable name points to the full name of the Xmath variable, which consists of the partition name and the variable name (for example, main.var). value is the standard LNX data structure pointer.

XmathSave() and XmathLoad() both work with an array of pointers to externVars, one for each Xmath variable. The name field of the last element of such an array must be a NULL pointer.

XmathSave()

```
XmathSave() has the following prototype:
char *XmathSave (char *filename, externVar *data, int
type)
where
    filename is the name of the file to be saved
    data is an array of externVar defined previously
    type parameter is an integer that lets you select ASCII (value 0) or
    binary format (value 1)
```

XmathSave returns a NULL pointer for success. If this function fails, it returns a string that describes the error.

XmathLoad()

```
XmathLoad( ) has the following prototype:
char *XmathLoad (char *filename, externVar **data)
where
    filename is the name of the file to load
    data is an array of externVar defined previously
```

XmathLoad() loads the specified file and constructs an array of
externVars, one for each variable loaded, and stores the address of the
array into data.

XmathLoad() returns the NULL pointer for success. If this function fails, it returns a string that describes the error.

Standard Library Linkage

XmathSave() and XmathLoad() are declared in the LNX header file
and defined in the LNX library. Therefore, a C or C++ program that calls
XmathSave() and XmathLoad() should be built and invoked as an
LNX or UCI.

For an alternative method of library linkage on UNIX only, refer to the *Advanced Features and Notes* section.

Example of XmathSave and XmathLoad

The following example illustrates how to use XmathSave() and XmathLoad().

Example 8-3 XmathSave() and XmathLoad()

```
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include "xmathlib.h"
#define N
                 10
#define NAME
                "main.m1"
#define FILE_NAME "call5.xmd"
int main(void)
{
int k;
char
     name[] = NAME;
char * status;
et_matrix * matrix1;
externVar * my_data, * my_data_1;
/*== Allocate mem. for 2 data struct. type "externVar" ==*/
my_data = (externVar *)malloc (sizeof(externVar)*2);
/*== Backup the pointer ==*/
my_data_1 = my_data;
 MUST set field "name" of LAST (#2) structure to NULL
```

```
==========*/
 (my_data + 1) ->name = NULL;
 /*== Allocate mem. for field "name" of struct. "my_data" ==*/
my_data->name = (char *)malloc (sizeof(char) * (strlen(name)+1));
 /*== Copy str. NAME to field "name" of struct. "my_data" ==*/
strcpy (my_data->name, name);
 /*== Allocate mem. for "et_matrix" data struct. ==*/
matrix1 = AllocateMatrix(N, 1, 0);
 /*== Fill in some data ==*/
for (k = 0; k < N; k++) {
     (matrix1->real)[k] = k;
      (matrix1->imag)[k] = k+1;
/*== Fill in field "value" after cast to "externType" ==*/
my_data->value = (externType *)matrix1;
/*== Save matrix1 (Xmath format) in file = FILE NAME ==*/
if (status = XmathSave(FILE_NAME, my_data)) {
    printf ("status = %s\n", status);
    return 1:
}
/*== Free each field of every struct. type "externVar"
    Do it in for loop until field "name" = NULL
for (my_data = my_data_1; my_data->name; my_data++) {
    free (my_data->name);
    /*== Free mem. from AllocateMatrix() above ==*/
     DeleteAny(my_data->value);
}
 /*== Free array of "externVar" ==*/
free (my_data_1);
 return 0;
```

XmathStart() and XmathStop()

The file XMATH/include/xmathlib.h defines the XmathStart() and XmathStop(), which allow your program to communicate with Xmath. Each of the following routine description is followed by a prototype.

XmathStart()

XmathStart() starts Xmath. option is a char* that is reserved for future use. Currently, the option must be an empty string (""). This function returns the Xmath process ID (pid) if successful and 0 if unsuccessful.

```
int XmathStart(char *option)
```

XmathStop()

XmathStop() terminates the Xmath process immediately. Modified variables will not be saved. This function returns 0 if successful and 1 if unsuccessful.

```
int XmathStop()
```

Sample LNX Demonstrating Most Functions (myfun)

myfun () has one input and one output. The syntax to invoke myfun () is the same as for any other MathScript function:

```
y = myfun(x)
```

Example 8-4 provides sample code for most of the external program interface functions.



Note (UNIX) The filename for an LNX must be in lowercase letters.

Example 8-4 myfun.c

```
#include "xmathlib.h"
void myfun(int nlhs, externType **lhs, int nrhs,externType **rhs)
et_matrix *x, *y;
/* This function is written to indicate how you would use your
                                                                    * /
/* own C code to perform operations on Xmath data objects, and is*/
/* thus quite general. In this example, we manipulate the real
                                                                    * /
/* and imaginary components of the data separately. Note that
                                                                   * /
/* these elements are DOUBLES. The next line defines storage
                                                                   * /
/* variables for the real and imaginary components of the
                                                                   */
/* output data matrix.
                                                                    * /
double *val, *ival;
int i; /* a counter variable
                                                                    * /
/* Do some error checking.
                                                                    * /
```

```
if (*rhs[0] != ETMATRIX) {
   XmathError(ERROR_FATAL, "Input must be a matrix!",1);
   return:
   }
x=(et_matrix*)rhs[0];
if (x->columns !=1) {
   XmathError(ERROR_FATAL, "Can only work on column vectors!",1);
   }
if (x->isReal) {
   XmathError(ERROR_WARNING, "Need complex input!",1);
   x->imag=(double*)calloc(x->rows, sizeof(double));
   x->isReal = 0;
/* Pre-allocate the output y as a matrix having the same size
                                                                   * /
/* as input x. */
y=AllocateMatrix(x->rows, 1, x->isReal);
/* The following five lines assign the real and imaginary data
/* to the variables val and ival respectively. Then 2 is added
                                                                   */
/* to each of the real components and 3 to each of the imaginary */
/* components. Instead of using the dummy example here, you
                                                                   * /
/* replace these lines with a call to a more sophisticated
                                                                   * /
/* function of your own.
                                                                   */
val = y->real; ival = y->imag;
for (i = 0; i < x->rows; i++) {
  val[i] = 2.0+x->real[i];
   ival[i] = 3.0+x->imag[i];
   }
/* Return y as the first--and in this case, only--output of
                                                                   */
/* the left side of the function call.
                                                                   * /
lhs[0] = (externType*)y;
static char help[]={"This is the Help text.\n No Help yet."};
static functionData fdata[]={
   { "myfun", myfun, 1, 1, 1, 1, help},
  {0,0,0,0,0,0,0}
   };
main(argc,argv)
int argc;
char** argv;
```

Building and Calling LNX and UCI

In this section, we use the sample LNX file myfun.c (Example 8-4) to illustrate how to build an LNX. A UCI is built exactly the same as an LNX.

Building on a UNIX System

To build a makefile and call an LNX on a UNIX system:

 Copy the sample program myfun.c from \$XMATH/src to your working directory as follows:

```
copyfile "$XMATH/src/myfun.c"
```

\$XMATH/src/Makefile is the makefile used to build an LNX or UCI. Copy the makefile template to your working directory:

```
copyfile "$XMATH/src/Makefile"
```

3. Edit the template to put myfun.c on the NAME line and myfun.o on the USEROBJECTS line. In addition, specify the appropriate compiler command (for example, acc) on the LINK line and appropriate compiler libraries (for example, \$(CLIBS)) on the LIBS line.



Note You can skip this step and use the expanded form of the make command in the following step.

4. Enter the make command from the Xmath command area:

```
oscmd("make")
or
oscmd("make NAME=myfun USEROBJECTS=myfun.o
LIBS='-L$(XMATH)/lib -lXmath' LINK=acc")
```



Note Use the simple form only if you edited the makefile.

5. After the make has run successfully, you can call myfun() as a regular Xmath function:

```
myfun(1 + jay)
```

Sample makefile (UNIX)

Example 8-5 provides a sample makefile for an LNX or UCI. This example includes several lines that are user-editable, such as the NAME and DEFS lines. Comments in the example explain the required user inputs. In this sample, myfun.c is the name of the sample LNX. The required user-input fields appear in bold type, but these are normally blank and require your modification.

Example 8-5 Sample makefile for Solaris Platform

```
# Basic MAKEFILE for creating callable interface/lnx executable
# Following fields must be set (Makefile or command line)
# NAME
                Prefix name of program that uses the callable
                interface or of the lnx file you wish to create
                List of .o files you wish to link with
# USEROBJECTS
# LIBS
                Name of compiler-specific libraries (suggested
                Solaris SC4.0 libraries pre-defined in CLIBS, CCLIBS,
                and FLIBS
                Name of compiler or link editor
# LINK
# Following fields are user-settable
# USERLIBS
                List of library search paths and/or libraries
               (e.g. library, -Lpath, and/or -libname)
# DEFS
                C or C++ pre-processor define directive
               (e.g. -DXTFUNCPROTO)
               User CFLAGS, i.e. options the user wants sent to
# UCFLAG
               C compiler (e.g. -g)
# UCCFLAG
               User CCFLAGS, i.e. options the user wants sent to
               C++ compiler (e.g. -g)
               User FFLAGS, i.e. options the user wants sent to
# UFFLAG
               FORTRAN 77 compiler (e.g. -g)
# ULDFLAG
               User LDFLAGS, i.e. options the user wants sent to
               linker (e.g. -v)
# INCLUDE
               List of directories that are searched for
               #include files
# CC
               Name of C compiler
# CCC
               Name of C++ compiler
# FC
               Name of FORTRAN compiler
       NAME = myfun
USEROBJECTS = myfun.o
   USERLIBS =
        DEFS = -DSOLARIS
     UCFLAG =
```

```
UCCFLAG =
     UFFLAG =
    ULDFLAG =
    INCLUDE = -I. -I$(XMATH)/include
      CLIBS = -L$(XMATH)/lib -lXmath
     CCLIBS = -L$(XMATH)/lib -lXmath_cxx
# F77 and M77 are Solaris Fortran SC2.0 runtime libraries
      FLIBS = -L$(XMATH)/lib -lXmath_cxx -lF77 -lM77
# F77, M77, and sunmath are Solaris Fortran SC3.0 and SC4.0 runtime
# libraries
      FLIBS = -L$(XMATH)/lib -lXmath_cxx -lF77 -lM77 -lsunmath
       LIBS = \$(CLIBS)
         CC = acc
        CCC = CC
         FC = f77 - temp = $(HOME)
       LINK = $(CC)
     CFLAGS = $(DEFS) $(UCFLAG) $(INCLUDE)
    CCFLAGS = $(DEFS) $(UCCFLAG) $(INCLUDE)
     FFLAGS = $(UFFLAG) $(INCLUDE)
    LDFLAGS = $(ULDFLAG)
.SUFFIXES : .o .c .cxx .C .f .F
.c.o:
    $(CC) $(CFLAGS) -c $< -o $@
.cxx.o:
    $(CCC) $(CCFLAGS) -c $< -o $@
.C.o:
    $(CCC) $(CCFLAGS) -c $< -o $@
.f.o:
     $(FC) $(FFLAGS) -c $< -o $@
.F.o:
    $(FC) $(FFLAGS) -c $< -o $@
$(NAME): $(USEROBJECTS)
     $(LINK) $(LDFLAGS) -o $@.lnx $(USEROBJECTS) $(USERLIBS) $(LIBS)
$@echo " Done."
```

Building on a Windows System

Complete the following steps to build a makefile and call an LNX on a Windows system in Xmath:

1. Copy the sample program myfun.c from %XMATH%\src to your working directory as follows:

```
copyfile "%XMATH%\src\myfun.c"
```

2. Enter the following command from the Xmath command area:

```
oscmd("makelnx myfun.c")
```

In general, to build LNXs and UCIs for Xmath use on a Windows system, enter the makelnx command with the following syntax:

```
> makelnx -debug "file1 file2 ..."
```

For the previous command, the default is to build "nodebug" objects unless you specify the -debug option.

The previous command is a batch file that calls the makefile. Here is the path to the batch file and makefile:

```
%XMATH%\bin\makelnx.bat
%XMATH%\bin\makelnx.mk
```

Typically, you will not need to edit or change these files to perform routine build tasks. If you do need to customize your build procedures, you can copy these files to your local project directory and edit them as required.

If you do not specify a source module filename or list of filenames in the command area, the script by default will look in your local directory for a specific argument file containing the list of filenames. These default argument files require a filename extension of .arg and must have a name that matches the name of the corresponding build command. For example, makelnx.arg is used by makelnx.bat. In these argument files you include a list of your files to compile and link.

The filenames can be separated by spaces or placed on separate lines and any text on a line following '\' (backslash space) will be treated as comment text.



Note Filenames can be separated by spaces or placed on separate lines with a continuation character '\' appended at the end of the previous one.

All target filenames specified with the above "make" commands must have a suitable file extension because this determines the choice of compiler for each file. The default file extensions currently supported include:

C .c

C++ .cxx or .cpp or .cc

FORTRAN for or .f

Like most standard make facilities, the above "make" commands support conditional compilation and linking of files depending on file creation time and whether the necessary dependent files currently exist. This means that recompiles will only be done for files where source is newer than the corresponding object file. If you need to force recompilation of a source module, delete the corresponding object file.

The make commands automatically create a log in your current working directory. The log filename has an extension of .log (for example, makexxx.log). Upon completion of the make, a copy of this file remains in your local directory in case you need to review the contents of the make.

If you need to customize your builds, each of the make script source files described above contains a commented section highlighting several predefined macro strings that you can modify as needed to customize the build process. Follow the instructions provided in the files.

Undefining an LNX

If an existing resident LNX file is relinked while Xmath is running, use the undefine command to terminate the current LNX process so that the new LNX is used upon the next invocation.

Using the User-Callable Interface

The User Callable Interface (UCI) program uses the function XmathStart() to invoke Xmath. Any inputs that will be used in Xmath are copied from the user program to Xmath objects using XmathPut(). Once all inputs are copied over to the Xmath process, any Xmath statement can be executed using XmathExecute() or XmathCommand(). Any data transferred to Xmath and altered can be retrieved using XmathGet() or saved to a file using XmathSave(). The Xmath process is terminated using XmathStopy().

Building and Calling a UCI

A UCI is created in the same way as an LNX. A UCI is invoked by specifying the -call option to the command to start Xmath:

```
xmath -call myuci.ext
xmath -tty -call myuci.ext
where (UNIX) ext = lnx and (Windows) ext = exe
```

Any required arguments to myuci can be supplied at the end of the command line.

LNX Example

Example 8-6 provides an example of the LNX function negate(). The negate() function works exactly like the minus (–) operator on matrix and PDM inputs. The function returns an error if the input is a string.

Example 8-6 negate()

```
#include "xmathlib.h"
void negate(nlhs, lhs, nrhs, rhs)
int nlhs, nrhs;
/* lhs is a pointer to the return arguments */
/* rhs is a pointer to the input arguments */
externType **lhs, **rhs;
   int number_elem, i;
   et_matrix *input;
   et_pdm *in_pdm;
   double *in_data;
   switch(*rhs[0]) {
      case ETMATRIX: {
        input = (et_matrix *)rhs[0];
        in_data = input->real;
        number_elem = input->rows * input->columns;
        for(i=0; i < number_elem;i++, in_data++)</pre>
           *in_data = -(*in_data);
        lhs[0] = (externType*)input;
        break;
      }
      case ETPDM:{
        in_pdm = (et_pdm *)rhs[0];
        in_data = in_pdm->theData->real;
        number_ele
```

```
=in_pdm->theData->rows*in_pdm->theData->columns;
         for(i=0; i < number_elem; i++, in_data++)</pre>
             *in_data = -(*in_data);
         lhs[0] = (externType*)in_pdm;
        break:
      }
      default:
         XmathError(ERROR_FATAL,
             "Data Type not supported in this function",
1);
/* Define the online Help */
#define Help "No Help yet"
/* Holds the function information: */
static functionData fdata[] = {
   {"negate", negate, 1, 1, 1, 1, help},
   {0}
};
main(argc, argv)
int argc;
char **argv;
   int resident = 0;
   XmathMain(argc, argv, fdata, resident);
   return 0;
}
```

UCI Examples

Example 8-7 is a UCI program that uses the Xmath \log () function to calculate the logarithm of an input. This file is found in \$XMATH/src/call.c. Example 8-8 is a UCI example that uses Xmath graphics in an external C program.

Example 8-7 Xmath as a Computational Engine

```
#include <math.h>
#include <stdio.h>
#include "xmathlib.h"
int doMyProgram()
{
et_matrix *x, *y;
```

```
double *ptx, *pty;
int n, i;
n = 10;
/* allocate two matrix structs */
x = AllocateMatrix(n, 1, 1);
y = AllocateMatrix(n, 2, 1);
/* fill up some local data */
ptx = x->real;
pty = y->real;
for (i = 0; i < n; i++) {
    *ptx = (double)i;
    *pty++ = sin(*ptx);
    *pty++ = cos(*ptx++);
    }
/* send local x and y over to Xmath as variable y.
   Check for errors*/
er_string = XmathPut("y", y);
if (er_string != NULL)
  printf("ERROR: %s", er_string);
/* execute an Xmath function */
er_string = XmathExecute("y = log(abs(y));");
if (er_string != NULL)
    printf("ERROR: %s", er_string);
/* Get y back. have to delete the current y since we
* get a new one from XmathGet.*/
DeleteMatrix(y);
er_string = XmathGet("y", (externType**)&y);
if (er_string != NULL)
 printf("ERROR: %s", er_string);
/* Output the new y */
pty = y->real;
for (i = 0; i < n; i++)
    fprintf(stdout, "%g %g\n", *pty++, *pty++);
```

```
}
int main(argc, argv)
unsigned argc;
char** argv;
{
XmathStart("");
doMyProgram();
XmathStop();
return 0;
}
```

Example 8-8 Xmath as a Graphics Engine

```
#include "xmathlib.h"
#include <stdio.h>
/* Generate some test data */
    double data[8] = \{0.0, 1.0, 2.0, 3.0, 4.0, 3.0, 2.0, 1.0\};
    int number_points = 8;
int DisplayVector(vector, columns)
double *vector;
int columns;
   et_matrix *thedata;
  int real = 1;
   char *er_string;
/* Convert the data array to the data type et_matrix, so
   Xmath will recognize it*/
   thedata = WrapMatrix(1, columns, vector, 0);
/* Copy the data over to the Xmath child process */
   er_string = XmathPut("thedata", (externType*)thedata);
    if (er_string != NULL)
        printf("ERROR: %s", er_string);
   er_string = XmathExecute("plot(thedata)?");
    if (er_string != NULL)
        printf("ERROR: %s", er_string);
/* The plot is now drawn, and the user can interact with
   the window, adding text, changing colors, etc*/
```

```
XmathExecute("pause");
}
int main(argc, argv)
   unsigned argc;
   char** argv;
{
/* Start the Xmath process */
    XmathStart("");

/* Send data to be plotted */
    DisplayVector(data, number_points);5
/* Stop the Xmath child process */
    XmathStop();
   return 0;
}
```

Any plot can be saved to a PostScript or HPGL file using the hardcopy command:

```
XmathExecute("hardcopy file=\"mygraph\", {ps}");
```

The C escape character \ (backslash) is necessary for the embedded Xmath string.

Calling an LNX in Background Mode

If an LNX performs a long calculation, you can invoke the LNX in background mode so that you can continue to use Xmath for other tasks while the LNX runs.

Another scenario where a background LNX is useful is where the LNX is a GUI application. Refer to the *Advanced Background LNX Function* (*IPCWC*) section for information on how to communicate with a background LNX.

Example

To invoke the LNX myfun() in background mode, issue the following command:

```
[output] = (define myfun, {background})(1000);
```

The return value, output, will be "busy" during the background execution of the LNX. In this example, 1000 is the input argument to myfun().

Given the above example, typing the command WHO (which lists variables) in the Xmath window shows that output is busy:

```
who
output -- busy (job #13103)
```

After the background define command for the LNX process has been entered, the process will be spawned to run in background mode and the user will have immediate control of the Xmath command area.

Upon completion of the background LNX process, notification of the process termination status appears in the Xmath log area, after you press the <Return> key.

```
[out]=(define myfun, {background}) (1000);
(job 13103) has terminated normally.
```

Example 8-9 is an example of an LNX program that can run in either foreground or background mode.

Compile this sample LNX program using the steps described in the *Building on a UNIX System* section. To see how to run the sample program in background mode, refer to the *Advanced Background LNX Function* (*IPCWC*) section.

Example 8-9 getpi (Runs in Foreground or Background)

```
#include <stdio.h>
#include <stdlib.h>
#include <math.h>
#include "xmathlib.h"
/* This sample lnx program calculates the value of pi based on the */
/* number of randomly-generated (x,y) points that fall within the
                                                                     * /
/* upper right quarter of the unit circle.
                                                                     */
/*
                                                                     * /
/* Test using an input value between 500000 and MAXRANDOM.
                                                                     */
#define REAL1
#define MAXRANDOM((double) (exp(31 * log(2.0))-1)) /* (2**31) - 1 */
void getpi(nlhs, lhs, nrhs, rhs)
int nlhs, nrhs;
externType **lhs, **rhs;
{
   externType *data;
```

```
et_matrix *arg;
et_matrix *out;
long
           steps;
double
          x, y, r;
double
           p_i;
char
           buffer[255], *errstr;
int
           count; /* Number of random points inside unit circle */
if (nrhs != 1) {
   /* User did not provide an integer argument. Go to Xmath's */
   /* main partition and get the variable `step_number'.
   errstr = XmathGet("main.step_number", &data);
   if (errstr != NULL) {
      sprintf(buffer, "Error getting main.step_number : %s",
         errstr):
   XmathError(ERROR_FATAL, buffer, 1);
   free(errstr);
   return;
   }
if (*data != ETMATRIX) {
   XmathError(ERROR_FATAL, "Usage: getpi number", 1);
     return;
   }
   arg = (et_matrix*) data;
  XmathExecute("main.pi = 0;"); /*create the result variable*/
} else {
  /* User provided an integer argument to the lnx */
if (*rhs[0] != ETMATRIX) {
   XmathError(ERROR_FATAL, "This LNX requires a number!", 1);
  return;
arg = (et_matrix*) rhs[0];
srandom((int) time(0));  /* Start random number generator */
count = 0;
for (steps = 0; steps < (int) arg->real[0]; steps++) {
   /* Get x and y coordinate values between 0 and 1 */
   x = random() / MAXRANDOM;
   y = random() / MAXRANDOM;
   r = sqrt((x * x) + (y * y));
   if (r <= 1.0)
     count++;
```

}

```
p_i = 4.0 * count / steps;
   fprintf(stderr, "%ld steps: p_i = %f\n", steps, p_i);
   out = AllocateMatrix(1, 1, REAL);
   nlhs = 1;
   out->real[0] = p_i;
   lhs[0] = (externType*) out;
   if (nrhs != 1) {
      XmathPut("main.pi", (externType*) out);
      DeleteAny(data);
   }
}
functionData fdata[] =
{{"getpi", getpi, 0, 1, 0, 1, "Help text for getpi" }, {0} };
main(argc, argv)
int argc;
char **argv;
{
   fprintf(stderr, "Starting ...\n");
   XmathMain(argc, argv, fdata, 0);
   fprintf(stderr, "Stopping ...\n");
   return 0;
}
```

Removing an LNX Job

When an LNX is invoked in background mode, Xmath echoes a job number (which is really its process ID) to the log area. This job number can be used as input to the REMOVE JOB command.

```
REMOVE JOB job_number
```

The REMOVE $\,\,\mbox{\scriptsize JOB}$ command uses the specified job number to terminate the LNX.

Building an LNX to Link a FORTRAN Routine

Xmath provides two ways to create an LNX function based on FORTRAN code. The preferred approach is to use C as described in the previous sections and then transfer control to your FORTRAN subroutine from within C. The second method is to use the special FORTRAN interface to LNX described in this section. This approach is less complete due to limitations in FORTRAN, and it is recommended only for users who do not know C.

Calling FORTRAN from C LNX Files

There are three important points to remember when calling a FORTRAN routine from C: name linkage, argument linkage, and array ordering.

- (UNIX) In C, append an underscore (_) to the end of the name of the FORTRAN routine you need to call. You will need to define the FORTRAN function as a void external function within your C routine. Some architectures do not support underscores.
- 2. FORTRAN expects subroutine arguments to be passed by reference (address). Here is a sample FORTRAN subroutine:

```
subroutine fort(n, a)
double precision a(n)
integer n
```

To call the above subroutine from C, you need:

```
double *a;
int n;
fort_(&n, a)
```

Here you pass the address of n. Notice that the variable a is already an address.

3. FORTRAN stores two-dimensional arrays in column-major, as opposed to row-major, mode. This means that sequential elements of a FORTRAN array that comprise the columns and sequential elements of a C array run along the rows of the array.

Creating FORTRAN LNX Files

The C interface to LNX described in the previous selection is the preferred method of presenting external FORTRAN code as an Xmath function. However, for users who may not be familiar with the C language, a FORTRAN interface that does not require any C programming is also provided.

cmxin

To get started using FORTRAN LNX you may want to study the file template.f in \$XMATH/src. This file is an example of how to link a FORTRAN matrix-vector multiply routine into Xmath. You must supply an initialized common block named fdata declared as:

```
character *10 name
integer minIn, maxIn, minOut, maxOut
common /fdata/ minIn, maxIn, minOut, maxOut, name
```

The template does this by using a block data section where it initializes the common block with data statements. These parameters have the same meaning as the fields of the functionData structure in the *XmathMain()* (for LNX only) section. Currently the name is ignored, and the name of the LNX function will be the name of the generated LNX executable file.

You must also supply a subroutine named ftnlnx with the calling sequence. The template (\$XMATH/src/template.f) gives an example of a ftnlnx subroutine.

```
subroutine ftnlnx(thefun,
! nin, stkin, locin, cmxin, rowin, colin,
! nout, stkout, locout, cmxout, rowout, colout,
! howmuch, error)
  integer thefun
  integer nin,locin(nin),cmxin(nin),rowin(nin),colin(nin)
  integer nout,locout(nout),cmxout(nout),rowout(nout),colout(nout)
  integer howmuch, error
  double precision stkin(*), stkout(howmuch)
```

The meanings of the parameters are described in Table 8-8.

ParameterFunctionthefun:For future expansion. Set to 1 in this version.ninThe number of input arguments.stkinA "stack" of the input matrices.locinAn array indicating the index in stkin of each input matrix.For example, input argument 2 starts at position locin(2), so the (1,1) element of input argument 2 is stkin(locin(2)), and the (2,1) element is stkin(locin(2)+1).

Table 8-8. ftnlnx Parameters

cmxin(i) is 1 if input argument i is complex. Zero otherwise.

Table 8-8. ftnlnx Parameters (Continued)

Parameter	Function	
rowin	rowin(i) gives the number of rows of input argument i.	
colin	colin(i) gives the number of columns of input argument i.	
nout	The number of output arguments requested by the Xmath user.	
stkout, locout, cmxout, rowout, and colout are analogous to stkin, locin, cmxin, rowin, and colin, except that they pertain to the output arguments. You are responsible for setting these values completely and correctly.		
howmuch	Indicates how much space is reserved in stkout. That is, you should regard stkout as an array declared as double precision stkout(howmuch).	
error	<pre>a user-settable error flag. if error > 0 - fatal error if error < 0 - warning if error == 0 - no error</pre>	

The typical sequence in ftnlnx will be to:

- 1. Unpack the input stack (stkin).
- 2. Pass control to your desired FORTRAN subroutine.
- 3. Pack the output arguments in stkout (and set locout, cmxout, rowout, and colout).

The routines discussed in previous sections (XmathError, AllocateMatrix, and so on) are not available in FORTRAN LNX.

Debugging

Debugging procedures for LNXs and UCIs involve setting breakpoints and then analyzing errant behavior versus expected behavior as described in the following sections.

Debugging an LNX with dbx (on UNIX Systems)

1. Create an LNX called myfun.lnx with debug information.

You can modify the make command itself (refer to the *Enter the make command from the Xmath command area*: section) by adding the debug option (for example, UCFLAG = -g) or by changing the appropriate user-defined flag within the makefile itself (for example, UCFLAG = -g or UCCFLAG = -g) (refer to Example 8-5).

- 2. You must indicate that you want the debugger to ignore the USR1 interprocess signal handler.
 - **(SunOS)** For dbx create a file called .dbxinit with this line: ignore USR1
 - **(HP-UX)** Create a file called .xdbrc with this line:

z 16sr

3. Issue the Xmath DEBUG command:

debug myfun

4. Now call the function:

myfun(1+jay)

Xmath displays the debug LNX dialog window and then pauses. The debug message dialog will have a message similar to,

dbx ./myfun.lnx 8134

where dbx is followed by the LNX function and the process ID.

- 5. To start the dbx process with the LNX process attached, type or copy the previous command into a UNIX shell.
- 6. In dbx, set a breakpoint in myfun() with the command:

stop in myfun

- 7. Issue the dbx continue command by typing cont in the debugger.
- 8. Return to Xmath and dismiss the debug LNX dialog.

 Immediately, dbx breaks at the breakpoint previously set. You can start debugging the function.
- When you finish debugging the function, issue the dbx CONT command.

Xmath returns with the output of the LNX function.

10. When the debug session is complete, use the dbx DETACH command to detach the LNX process from dbx.

For resident functions, Xmath automatically turns off debug mode for LNXname after it returns. If you want to debug the LNX function with another set of inputs, call LNXname again. This time, however, Xmath will not display the debug dialog. On the other hand, if you have not removed the breakpoint in dbx, the LNX process will break at the same breakpoint. The function can then be debugged with the new inputs.

Specifying an LNX to be nonresident means that the LNX is automatically undefined after it finishes. Therefore, the debugging mode is forgotten.

This makes MSF and LNX debug mode behavior consistent, because undefining an MSF also makes Xmath forget everything about the MSF, including the debug mode.

Debugging LNXs (on Windows Systems)

To debug an LNX, complete the following steps:

 Create an LNX called myfun.exe with debug information as described in the *Building on a Windows System* section:

```
makelnx (-debug) myfun.c
```

This creates an LNX called myfun.exe.

2. Go to **Xmath Commands** window and call the LNX:

debug myfun

myfun(1+jay)

3. A dialog box (myfun.exe-Application Error) appears with the message:

A breakpoint has been reached. Click **Cancel** to go into the debugger.

Then another dialog appears with the message:

Break caused by hard coded breakpoint instruction.

Click **OK** in this dialog box.

4. Now, select **Debug»Breakpoints**.

A Breakpoints dialog appears.

- 5. In the Location area, enter myfun. Click **Add** to add the name to the breakpoints column. Click **OK** to dismiss the dialog.
- 6. Select **Debug**»**Go** from the Debug pull-down menu.

The debugger will now stop at the breakpoints you have specified.

When you are finished debugging, select **Debug»Breakpoints**.
 When the Breakpoints dialog appears, click **Clear All** to clear the breakpoints. Click **OK** to dismiss the dialog box. Select **Debug»Go**.

The LNX will run to completion.



Note Do not exit the debugger until the LNX runs to a completion.

8. To exit the debugger window, select **File**»**Exit**.

Debugging UCIs (on UNIX Systems)

To debug a UCI on a UNIX system, complete the following steps:

- Create a UCI with debug information as described in the Building on a UNIX System section.
- 2. Debug the UCI using dbx:

```
xmath -call dbx uci.lnx
```

3. Now, set a breakpoint in myfun.c with the command:

```
stop in myfun
```

For each function you want to debug.

4. Enter run.

The debugger will now stop at the breakpoints you have specified.

5. When you are finished debugging, clear the breakpoints and type cont to let the UCI run to completion.



Note Do not exit the debugger until the UCI runs to a completion.

6. To exit the debugger, type quit.

Debugging UCIs (on Windows Systems)

To debug a UCI on a Windows system, complete the following steps:

- Create a UCI with debug information as described in the *Building on a Windows System* section.
- 2. Debug the UCI using MSVC:

```
xmath -call msdev uci.exe
```

3. Now, select **Debug»Breakpoints**.

A Breakpoints dialog box appears.

- 4. In the Location area, enter the name of the function you want to debug. Click **Add** to add the name to the breakpoints column. Keep doing this for all of the desired breakpoints. Click **OK** when you have finished.
- 5. Select **Debug**»**Go**.

The debugger will now stop at the breakpoints you have specified.

6. When you are finished debugging, select **Debug»Breakpoints**. When the Breakpoints dialog appears, click **Clear All** to clear the breakpoints. Click **OK** to dismiss the dialog. Select **Debug»Go** from the **Debug** pull-down menu to let the UCI run to completion.

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Note Do not exit the debugger until the UCI runs to a completion.

7. To exit the debugger, select **File**»**Exit**.

Advanced Topics

Handling an Aborted LNX

The following MathScript command

```
set debugonerror off
```

allows a script to resume execution after an LNX that it calls terminates abnormally. Without using this command, a script will be aborted if the LNX that it calls terminates abnormally.

For example:

```
command callsegv
```

```
set debugonerr off  # allow this script to resume if segv() aborted
out = []  # assuming segv() never returns a []
out = segv()  # an LNX that terminates abnormally
if out == []  # if segv() aborted,
    display "segv() failed."
else
    display "segv() returned successfully."
endif
endcommand
```

If an LNX process terminates abnormally, Xmath prints out a message similar to the following:

```
Process name has terminated abnormally (Signal #)
```

The signal number is the UNIX error code. These codes are standard on UNIX systems and are described in the file /usr/include/sys/signal.h.



Note XmathPanic should be in the <Ctrl-C> signal handler of your LNX or UCI program to clean up after an abnormal stop. The syntax is as follows:

```
void XmathPanic()
```

Advanced Features and Notes

The following issues apply to UNIX systems only.

• When an XmathSave() or XmathLoad() link is called, an Xmath process called xmathsl is invoked. To avoid this overhead, you can link with the libxmsl.a library in addition to libXmath.a (libXmath.a must follow libxmsl.a in the link command). You will need the standard C++ library supported for your platform for the link, typically by including -1C in the link command line.

That is, the stand-alone saveload document references the last line of this file:

```
$(CC) -o $@.lnx $(USEROBJECTS) -L$(LIBS) $(USERLIBS)
-lXmath
```

which must be changed to the following:

```
$(CC) -o $@.lnx $(USEROBJECTS) -L$(LIBS) $(USERLIBS)
-lxms1
-lXmath -lC
```

• LNX and UCI use the signal USR1 as part of communications processes; do not modify the handler of this signal.

Advanced Background LNX Function (IPCWC)

IPCWC allows you to communicate with a background LNX process that is also a windows client. First, a message is sent to the LNX with the specified window ID (wid) and the process ID (pid). Additional data (the arguments listed) is then sent to the LNX (formatted according to the specifiers in the format string, as applicable). The calling syntax is:

```
IPCWC wid, pid, format_string, arg_list ...

wid Window ID (a number).

pid Process ID (a number).

format_string A string with format specifiers (as described below).

arg_list The values to be sent. You can have as many values as you like, as long as they are separated by commas and each one maps to a format specifier in format_string.
```

- The format specifiers are codes consisting of the percent sign (%) and a character. They are:
 - %c A single character.
 - %d A decimal number.
 - %s A string.
- All non-format specifiers are sent as individual characters.
- The LNX process receives data with the calls shown in Table 8-9.
 XmathIPCgets returns a malloc'ed string. Remember to free it when done.

Table 8-9. Background LNX Functions

Function	Description and Prototype
XmathIPCgetc()	XmathIPCgetc() returns a character from the IPC stream to the LNX process.
	char XmathIPCgetc()
XmathIPCgeti()	XmathIPCgeti() returns an integer from the IPC stream to the LNX process.
	<pre>int XmathIPCgeti()</pre>
XmathIPCgets()	XmathIPCgets() returns a malloc string from the IPC stream to the LNX process. Remember to free the string when you are done.
	char *XmathIPCgets()

• \$XMATH/include/xmathlib.h contains the definition for optional flags, such as LNX_USE_IPC. In a background call, XmathReleaseIPC() detaches an LNX. The last argument in the XmathMain() call sets the LNX_USE_IPC flag. The callback LNX function, defined in the functionData structure, is responsible for calling XmathReleaseIPC().

Sample IPCWC Calling Sequence

The following sample IPCWC calling sequence sends the character H followed by the number 104 to an LNX that has window ID 9999 and process ID 99:

```
ipcwc 9999, 99, "H%d", 104
```

The next step is to send the character B followed by character A, the string "Test1", and then the ID number 5 to an LNX that has window ID 9999 and process ID 99.

```
ipcwc 9999, 99, "B%c%s%d", "A", "Test1", 5
```



Note To ensure proper handshaking between the client and server in sophisticated LNXs, the client program should wait for a status from the client; when the client has finished reading it should return the status via XmathIPCputs (). For example:

```
ipcwc 9999, 99, "B%c%s%d&s", "A", "Test1", 5, status
```

Example 8-10 shows a pseudocode LNX example that uses some of the XmathIPCget call. Example 8-11 is pseudo-code for a sample LNX program using IPCWC.

Example 8-10 Sample Usage of ipcwc to Communicate with a Background LNX

```
#
# action = SaveFile or LoadFile
#
Command SendAction action, file_name
wid = 9999;
pid = 99;
if (!is(action, {string}))
    error("Argument 'action' must be a string", "F")
endif
if (!is(file_name, {string}))
    error("Argument 'file_name' must be a string", "F")
endif
ipcwc wid, pid, "%c %s", stringex(action, 1, 1), file_name
endCommand
```

Example 8-11 Pseudo-Code for an LNX that Responds to ipcwc

```
#ifdef UNIX
#include <X11/Xlib.h>

/* This is how the ipcwc command actually sends to the client window */
void Send_ipcwc_window_message(Window wid)
{
    XEvent xclient;
    extern Display *dpy;
```

```
xclient.xclient.message_type = 0;
  xclient.xclient.type = ClientMessage;
  strcpy(xclient.xclient.data.b, "XMATH");
  xclient.xclient.format = 8;
  XSendEvent(dpy, wid, 0, NoEventMask, &xclient);
  XFlush(dpy);
}
/* This is how to detect a window message sent by the ipcwc command */
/* The following is a typical X event loop
                                                                   * /
XEvent event;
switch (event.type) {
case ClientMessage:
if (Is_ipcwc_window_message(&event)) {
  action = XmathIPCgetc()
  switch (action) {
     case 'S':
     savefile = XmathIPCgets()
     case 'L':
      loadfile = XmathIPCgets()
     default:
   }
}
else {
   /* other ClientMessage messages
                                                                      * /
}
int Is_ipcwc_window_message(XEvent *event)
extern Display *dpy;
XClientMessageEvent *xclient;
Atom wmpAtom, wmdAtom;
xclient = (XClientMessageEvent *) event;
wmpAtom = XInternAtom( dpy, "WM_PROTOCOLS", True );
wmdAtom = XInternAtom( dpy, "WM_DELETE_WINDOW", True );
return ((wmpAtom == None | | wmdAtom == None | |
xclient->message_type != wmpAtom ||
xclient->data.1[0] != wmdAtom)
&& !strcmp( "XMATH", xclient->data.b ));
```

Graphical User Interface

This chapter introduces the fully programmable graphical user interface (PGUI or GUI) of Xmath.

The GUI is available on all MATRIXx platforms. The GUI allows arbitrary windows to be created and manipulated using only Xmath source code (MathScript). GUI windows might contain, for example, sliders, buttons, menus, and plot areas, all of which can accept user input from the mouse. Xmath simultaneously supports user interaction in any number of newly created GUI windows, as well as through each of its standard windows.

The GUI provides a number of predefined dialogs that can be used to interact with the user. These dialogs are a collection of modal dialogs that are used by most applications. When called they suspend command execution until the user responds to the dialog. Once the user responds, the response is returned and command execution resumes.

Finding Out About the GUI

Whether you are a GUI tool user or a developer, you will want to learn about the GUI, although the ultimate learning will be at different levels.

GUI Tool Users

GUI tools are simple and intuitive to use, but there are a few basic things you should know. You should run guidemo and look at some of the examples, especially leadlag, to get a feel for the features and capabilities of GUI tools. Each GUI tool has extensive help menus describing its use. Browsing through help messages is a good way to learn what a tool does.

GUI Developers

You might also want to develop your own GUI tools. For example, you might add a graphical user interface to an existing Xmath command script. Programming with the GUI is more difficult than writing your own Xmath commands and functions, so delay trying this until you are quite comfortable programming in Xmath and using GUI tools.

To develop your own simple tools using the GUI, we recommend that you run the GUI demos while looking at the corresponding source code, which is in \$XMATH/demos/gui. The next step is to read the help entries for the GUI functions in the *MATRIXx Help*. Each function has an example, consisting of an Xmath command that creates a PGUI tool. Start with uiToolCreate(). For this and other examples where an Xmath command is defined:

- Use a text editor to create a new Xmath command file.
- Copy the example command script into the file.
- Name the file *commandname*.msc and save it to a folder included in the lookup path.
- Execute the command by typing its name in the Xmath command area.

For example, to run the uiToolCreate() example, copy the entire ex_uiTool command to a file named ex_uiTool.msc. Save that file to a folder in your lookup path. In the Xmath command area, type ex_uiTool and press <Enter>.

Running the GUI Demos

To see a menu of Programmable GUI examples, type guidemo in the Xmath command area. Then, complete the following steps to run a demo.

- 1. Select a demo (for example, Variable Binding).
- 2. Click **OK**.

In a few seconds the demo appears. Your window manager may require you to position the window(s) generated by the demo.

Each demo has a help menu in its menu bar (near the upper right side of the window). The help messages explain how to interact with the demo and what it does. It may be helpful to read the rest of this chapter before (or while) you try the demos.

To exit a demo, select Special»Exit or File»Exit from the individual demo window.

To see another example of a GUI implementation, type ifilter in the Commands window command area.

Interacting with a GUI Application

This section describes the mechanics of interacting with GUI windows. First, we create an example dialog and then we discuss the various kinds of GUI objects that you can place in a dialog or window and how to use them.

Creating an Example Dialog

Tools that use the GUI create windows that contain control elements such as buttons, sliders, pull-down menus, plots, and lists. Some of these elements are shown in Figure 9-1, the PGUI Example dialog.

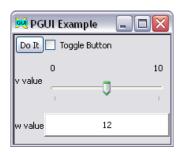


Figure 9-1. PGUI Example Dialog

If you are a user only, you might want to just create the dialog without paying much attention to the individual commands that follow. If you are a developer, this is another example from which you can learn.

To create the dialog in Figure 9-1, type the following in the Xmath command area:

```
tl = uiToolCreate("guiexhelp");
mw = uiWindow(tl,{title="PGUI Example"});
tb = uiTable(mw,{height = 140, width = 200, columns = 2});
void = uiButton(tb,{ text = "Do It"});
void = uiButton(tb,{ type = "toggle", text = "Toggle Button"});
void = uiLabel(tb,{ text = "v value"});
void = uiSlider(tb, {varname = "main.v", min = 0, max = 10});
void = uiVarEdit(tb, {varname = "main.w", text = "w value", height=30});
void = uiShow(mw);
main.v = 5;
main.w = 12;
```

To kill the dialog in Figure 9-1 type:

uiDestroy("quiexhelp")

Controlling GUI Objects

You can control most functions with the left mouse button. For example, you can activate a button by placing the cursor anywhere on the button and clicking the left mouse button. The **PGUI Example** dialog has two buttons: **Do It** and **12**.

Other objects behave as follows:

- A *toggle button* (square shaped) is either on or off. Its indicator is filled in when it is on. It can be toggled by pointing and clicking the left mouse button. The toggle button shown in Figure 9-1 is off. Activating a toggle button causes some action to be performed.
- *Radio buttons* (diamond shaped) are a group of buttons with radio behavior. Like the station selection buttons on a radio, selecting one button automatically turns off any other button that is on.
- A pull-down menu is displayed by depressing and holding the left mouse button. As the mouse is dragged, the various menu selections (usually buttons) are highlighted. Releasing the mouse activates the selected button.
 - A *cascade menu* is indicated by a small arrow to the right of the text in the button. The cascade menu is displayed by moving the mouse to the right.
- A text entry area behaves like the command input area in Xmath. Input
 is terminated by a newline character. Before you can type into a text
 entry area, you must focus on the area by placing the cursor in the area
 and clicking the left mouse button. Focus is indicated by a border
 highlight.
- A *list* is a vertical list of items (strings) that can be selected (highlighted). Depending on the application, a list can be configured to allow various types of selection:
 - A single-selection list allows only a single line to be selected.
 Clicking the left mouse button selects a line.
 - A multiple-selection list allows multiple lines to be selected. The selection of a single line is toggled by clicking with the left mouse button.
 - An extended-selection list also allows multiple lines to be selected. A contiguous range of items can be selected by clicking the left mouse button, dragging the mouse, and releasing. Pressing the <Shift> key while clicking the left mouse button selects all the items from the current item to the previous item that was selected with the left mouse button. Pressing the <Control> key while clicking the left mouse button augments (rather than replaces) the existing selections. This allows discontiguous ranges of items to be selected. This type of list is used in the history sorting and history column dialogs in the leadlag demo.

Once you select one or more items from a list, you then choose some action such as Delete or Display.

 A dialog is a small window that can contain a message and one or more buttons. For example, a dialog might have a single button and a message giving a warning or indicating an error.

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- Usually a dialog is *modal*—that is, you cannot interact with any other GUI or Xmath window until the dialog has been closed. If you find you cannot interact with Xmath or other GUI windows, then look for a modal dialog that might have been accidently covered by another window.
- Help messages are often listed under a help pull-down menu at the
 top-right of the GUI window. The help message appears in a new
 window that provides scrollbars as needed. The scrollbars are operated
 with the left and middle mouse buttons. The window is dismissed by
 selecting the Close button.
- A *variable edit box* appears in a GUI window as a button that displays some value. The value can be changed by selecting the button, whereupon a text entry area appears in place of the button. You can type a new value followed by <Return>. If the GUI tool does not like your new value, it reserves the right to change it to an acceptable value that is displayed again on the button.

The button labeled 12 shown in Figure 9-1 is a variable edit box (displaying the value of the variable w). If you click this button, it is replaced by the w value text entry area as shown in Figure 9-2. After entering a value from the keyboard, the text entry area is replaced by a button that contains the new value.

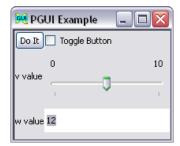


Figure 9-2. PGUI Example Dialog after Pressing the 12 Button

 A slider resembles a linear potentiometer and its value is changed by a linear motion of the handle. The position of the slider handle represents its value. Usually the limits of the slider are shown at its ends. Figure 9-2 shows a slider with minimum value 0 and maximum value 10. Its current value is about 6. You can change the value of a slider in several ways:

- Place the cursor on the handle, click the left mouse button, and drag the handle to the desired location. Some GUI tools might do something (for example, change a plot) as you drag the handle. In other cases, nothing happens until you release the handle at the new value.
- Click the middle button at the new value.
- Click the left button away from the handle to increase or decrease the value a small amount. Holding the button down makes the handle steadily move towards the cursor.

Often a value is displayed with a slider and a variable edit box (for example, the leadlag demo). This allows the value to be changed either by dragging the slider or entering a new value via the keyboard.

- *Plots*, which can accept graphical input from the user, can also appear in GUI windows. You can use the left mouse button for graphical input, the middle for plot zooming, and the right for plot data value viewing:
 - The function of the left mouse button depends upon the particular tool and plot. Often a tool allows a curve to be grabbed and dragged by clicking the left mouse button with the cursor near the curve, dragging the mouse with the button down, and then releasing at a new position.
 - Clicking the middle mouse button anywhere in the plot creates a
 box containing a magnification of a small area of the plot centered
 at the cursor. The middle mouse button can be held down and
 dragged, which creates an effect similar to dragging a magnifying
 glass across the plot. The center of the zoomed window
 corresponds to the tip of the cursor.
 - Pressing the <Ctrl> key while clicking the middle mouse button increases the size of the magnified box. Pressing the <Shift> key while clicking the middle mouse button increases the zoom factor. Pressing <Shift-Ctrl> with middle mouse button yields a large zoom box with a large magnification factor.
 - By pointing at or near a curve or object in a plot and clicking the right mouse button, a small window appears; it identifies the curve or object and gives the coordinates and index of the nearest data value.
 - If you click and drag the right mouse button, the selected curve is tracked, even if another curve comes close.

 Pressing the <Shift> key while clicking the right mouse button allows the user to get values on the piecewise line curve that interpolates the data values. In this case index 45.7 means that the selected plot point is between the 45th and 46th curve index entries.

GUI Programming Overview

The Programmable GUI allows you to perform the following tasks:

- Design the layout and appearance of windows.
- Create, destroy, and manipulate these windows.
- Bind Xmath variables to various objects in the windows.
- Arrange for Xmath code to be executed when the user interacts with the windows.

These tasks are accomplished as follows:

- Windows are created, destroyed, and manipulated using a number of Xmath functions.
- Bindings between Xmath variables and sliders, buttons, plotted curves, and other objects in the GUI windows are specified by setting the appropriate widget attribute.
- The execution of particular pieces of Xmath code when the user interacts with a GUI window is also specified by setting the appropriate widget attribute.

These tasks are described in more detail later in this chapter and in the *MATRIXx Help*.

Concepts and Terminology

A single GUI application is called a tool. The components that make up a complete tool are described in the following section. Usually a user explicitly starts a tool by sending a command (MSC) to Xmath. The MSC calls some Xmath functions that tell the GUI to create a new tool, one or more windows, and their children widgets. This is what happens when you type guidemo. After the MSC creates one or more initial windows, the MSC returns and Xmath is again idle. Tools can be launched in other ways. For example, an MSF, script file, or another tool can launch new tools.

Once a tool is created, it is then used as the parent of all subsequent windows created. Each window is then in turn used as the parent of each

widget in that window. In this way a hierarchy of the tool is defined. As it is created, each object is given various attributes that define different aspects of appearance and behavior, including the binding hooks back to Xmath. The binding of variables to various objects on a window is a key feature of the GUI. For example, a variable can be bound to a slider in a window. Whenever the user moves the slider, the Xmath variable is updated. Similarly, whenever the Xmath variable is updated, the slider moves. Variables can also be bound to plotted curves: whenever the variable is changed, the plotted curve changes accordingly. With variable binding, you do not have to explicitly update a display; merely changing the value of the variable (reassigning it) causes all displays bound to the variable to update automatically.

A second key feature of the GUI is the Xmath callback. In itself, updating a variable when the user moves a slider is not useful. Every time the user interacts with a window (that is, moves a slider or selects a button), you can specify certain Xmath code to be executed through an Xmath callback. An Xmath callback simply means that the MSC of the tool is called with arguments that describe what the user just did. Based on these arguments, the MSC can take whatever action is required.

The GUI is event driven. Normally, Xmath is idle. When the user does something to a GUI window, variables, if any, are updated, and Xmath callback(s), if any, are executed. Once the Xmath callbacks finish (that is, the MSC returns), Xmath is again idle, waiting for a new event.

Conceptual Example

A conceptual example can show how these features work together to form a simple tool. Suppose we have some Xmath code <code>computey.msc</code> that computes some value y given some parameter value x. Our tool arranges for the variable y to be bound to a read-only slider and the variable x to be bound to an interactive slider. The tool arranges for the Xmath code <code>computey.msc</code> to be executed when the interactive slider is released.

When our tool is invoked, a window containing the sliders appears. When the user moves and releases the interactive slider, the variable \times is first updated (assigned its new value) and then the Xmath code is executed (using the new value of \times). The Xmath code assigns a new value to the variable y. Since y is bound to the read-only slider, the read-only slider changes to reflect the new value of y.

It is interesting to compare the original Xmath code with the tool described above from the point of view of the user. The user interacts with the original code by repeatedly typing commands into the Xmath Command window such as x=3. 2 followed by computey followed by y, which prints the new value of y to the Xmath log area. Thus, user input and output are via the Xmath command and log areas, respectively, and both are alphanumeric in form.

In contrast, the user interacts with the tool described above by simply grabbing and moving the interactive slider. After it is released, the new value of y is displayed on the read-only slider. Thus, user input and output are via the sliders in the tool window and graphical in form. In effect, we have implemented a completely graphical interface for our original Xmath code computey.msc. In fact, once the graphical tool is running, we can iconify all of the standard Xmath windows, and someone completely unfamiliar with Xmath can use the code computey through the slider and bargraph.

Anatomy of a GUI Tool

It is possible to type commands directly in the Xmath Command window that instruct the GUI to create a tool and windows. Usually, however, a GUI tool consists of MathScript Command files (MSCs), MathScript Function files (MSFs), and a help file (.hlp):

- An MSC contains the code for starting the GUI tool and all the code for the Xmath callbacks. An Xmath callback simply calls the MSC with particular arguments, and the MSC takes the corresponding action based on these arguments. If the tool is smaller, the MSC may also contain all the widget creation code as well. A large tool can consist of multiple MSCs. Usually though all the tool callbacks are in one MSC. The MSC filename of the tool is the tool name followed by the extension. msc.
- MSFs are often used if the tool is quite large. An MSF can help organize and group widget creation code to a particular window or functionality. The MSC can call an MSF at the appropriate time to create portions of the tools GUI as needed.
- A help file contains one or more help messages or strings. The help file of the tool is the tool name followed by the extension, .hlp.

These files are described in more detail in the following sections. Refer to the GUI demos in \$XMATH/demos/gui for examples of each of these files. Each of the demos is implemented as an MSC script, possibly an MSF script, and an ASCII file that contains the help message text and global plot options. You can develop and debug GUI applications rapidly with the interactive environment and debugger in Xmath.

MSC File

The MSC of the tool is declared with three arguments:

```
command MSC_name {fragname, widgetname, instance}
```

When an Xmath callback occurs, the MSC is called with two strings (fragname and widgetname), and an integer (instance). The string fragname is the name of the Xmath code fragment to execute. The string widgetname is the name of the widget that caused the callback (usually this will be ignored, unless a single Xmath code fragment needs to handle user input into different widgets). Finally, the instance number uniquely identifies multiple instances of the same window. For example, if two identical windows are instantiated (refer to the *uiWindow* topic of the *MATRIXx Help*) and the user selects a button on each window, one Xmath callback will have instance = 1, and the other will have instance = 2.

Usually each Xmath code fragment is executed using goto, so each Xmath code fragment name is written as a goto label. Also, when the MSC is invoked with no arguments, it is often convenient (but not necessary) to arrange that the tool itself be launched. Therefore, a template MSC appears as follows:

```
Command MSC_name {fragName, widgetName, instance}
if (exist(fragName))
    goto *fragName;
                         # start tool
else
    [CODE LAUNCH TOOL GOES HERE]
    return;
endif
                         #executed when fragname == "ButtonPressed"
<ButtonPressed>
    [CODE TO EXECUTE WHEN BUTTON IS PRESSED]
    return;
<SliderMoved>
                         #executed when fragname == "SliderMoved"
    [CODE TO EXECUTE WHEN SLIDER IS MOVED]
    return;
                         # executed when fragname == "DoQuit"
<DoQuit>
    [CODE TO QUIT TOOL]
    return;
endCommand
```

The help file of the tool is where the help messages are stored. Each help message (or help fragment) is preceded by a name or label. The name is used to refer to the particular help fragment. The order of the help fragments in the help file is not important. The help file can be quite large if necessary; fragments are read only when needed.

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Each help fragment has the form:

<helpFragName>

```
This is the Help text that will be displayed.

The Help text can contain many lines. The indent of the initial line is stripped from all lines.

# comment lines (lines starting with '#') are ignored,

# although an embedded '#' will not be treated

# specially. Use '\#' at the start of a line if

# you need a '#' at the start of a non-comment line.
```

The help fragment name helpFragName is any string of your choice. The indent of the initial line of the help fragment will be stripped off all the lines in the help fragment when the help fragment is displayed. This assists in the legibility of the help file.

One help fragment can be included inside another with an include directive:

```
<helpFrag1>
   Note that:
   !#include <helpFrag1>
        That's all folks!
<helpFrag2>
   This Help text contains two lines.
```

The extra indent of the include line is applied to the entire included fragment, so the above is equivalent to:

```
<helpFrag1>
   Note that:
        This Help text contains two
        lines.
   That's all folks.
```

The include facility is useful for grouping help messages on specific topics into a single large *overview* message. For an example, see the help file for the leadlag demo (\$XMATH/demos/gui/leadlag.hlp).

The help fragment name can be followed by an optional title:

```
<helpFragName> Help Dialog title
This is the Help text that will be displayed.
The Help text can contain many lines.
```

Depending on the windowing system you use, the title should be displayed in the top border of the Help window.

The help file is really a database of strings accessed by name. The help file can be used to store strings or string arrays that a tool needs. Long options to the uiPlo() function, for example, can be placed in the help file. This feature is shown in the binding1 demo (\$XMATH/demos/gui/binding1.hlp).

Xmath GUI Functions

The Xmath GUI functions are categorized as follows:

- uiToolCreate()—creates a function for a tool.
- uiWindow()—creates a function for a top-level window of a tool.
- uiPanel(), uiTab(), and uiTable()—create container regions in a window or other container.
- uiMenu() and uiMenuItem()—create menu bars, pull-down menus, context menus, and menu items.
- uiButton(), uiComboBox(), uiList(), uiSeparator(), uiSlider(), uiText(), uiVarChoic()e, uiVarEdit(), uiVarView(), and uiLabel()—are controls for windows and containers for user interaction and displaying data.
- uiPlotArea()—creates a special control for displaying two-dimensional graphical plots.
- uiDestroy(), uiExist(), and uiHandle()—are PGUI object operations for checking existence, handle/name conversions, and generic destruction.
- uiHide() and uiShow()—display and hide a PGUI object.
- uiGetValue() and uiSetValue()—get or set the resources of a PGUI object.
- uiFlush()—forces the update of the objects displayed.
- uiTimer()—invokes an Xmath callback after a given amount of time has elapsed.

 uiPlot() and uiPlotGet()—are commands for generating two-dimensional plots in a uiPlotArea and getting user input to the plot.

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- uiFileSelection(), uiMessage(), and uiPrompt()—are
 predefined dialogs for selecting files, displaying messages, and
 prompting the user for input.
- uiWindowDeiconify() and uiWindowIconify()—deiconify and iconify a window.
- uiWindowLower() and uiWindowRaise()—lower and raise a window.

For more information on PGUI functions, refer to the *MathScript Programming, Programmable GUI* topic of the *MATRIXx Help*.

Tutorial

In this section we discuss two tools: the button and the calculator examples. These tools perform trivial functions; the point is not their purpose but their operation.

Pushbutton

Example 9-1 shows the ex1.msc file, located in the XMATH/demos/guidirectory.

Example 9-1 Button Creation

```
command ex1 {fragname, widgetname, instance}
alias T "ex1"

if( exist(fragname) )
   goto *fragname;
else
   t1 = uiToolCreate("ex1");
   wn = uiWindow(t1, {name = "win", title = "Tutorial"});
   void = uiButton(wn, {
        text = "Press This Button",
        xmath = "ButtonPress"});
   main.count = 1;
   void = uiShow(wn);
        return;
endif
```

```
<ButtonPress>
   main.count = main.count + 1;
   display sprintf("Button Press count: %d",
main.count);
   if(main.count >= 5)
       void=uiDestroy("ex1");
endif;
return;
endcommand
```

When the user types ex1, The ex1 tool window appears.

When the user types ex1, the MSC ex1.msc is invoked with no arguments. Therefore, the if conditional if (exist(fragname)) fails, and the else clause is executed. The statement tl = uiToolCreate("ex1"); creates the new tool ex1. (If the tool already existed, this step would first destroy the tool and all its windows before creating a new tool.) The value returned and stored in tl is the handle of the tool. All GUI creation routines return an object handle that is used when creating the tool windows; the object handle can also be used to reference the tool for other GUI functions, such as uiExist() and uiDestroy(. In addition to the handle, some operations on a tool can also be invoked with the tool name.

The next statement:

```
wn = uiWindow(tl, {name = "win", title = "Tutorial"});
```

actually creates a new window. The keyword arguments provide attribute information about a widget, the window in this case. You can provide a widget name—win in this case—so that you can reference the widget by its name instead of its handle.

creates a single button as a child of the window. Since no type keyword is specified, the default type button is created. The text keyword specifies the text to appear on the button face and the xmath keyword designates the callback fragment to execute when the button is clicked.

At this point, the window is still not visible. The call to uiShow() makes the window appear when desired. In this case, note that the call to uiShow() takes the handle returned from the uiWindow() call. The call to uiShow() could just as well appear as follows, which uses the name passed into the uiWindow() function:

```
uiShow("ex1", "PushBWin")
```

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Finally, the MSC initializes a global variable that is used to count button clicks and then returns:

```
main.count = 1;
return;
```

When the user clicks the button, the button checks to see if it has a value for its xmath attribute. In this case it is set to "ButtonPress" so the button will invoke the tool MSC as:

```
ex1 "ButtonPress", "Push"
```

We use the term *Xmath callback* to describe the calling of the tool MSC in this way. The first argument is the argument value set as the xmath attribute, the second argument is the button name, and the third argument is the instance number of the window, which will always be 1, unless we create multiple instances of the same window. Therefore, when the user activates the button, it is equivalent to typing:

```
ex1 "ButtonPress", "Push"
```

When called with these arguments, the MSC executes the code

```
main.count = main.count + 1;
display sprintf("Button press count: %d", main.count);
if(main.count >= 5)
    void = uiDestroy("ex1");
endif;
return;
```

This increments the count variable and displays a message in the Xmath log area. If the button has been clicked five times, you can see the following messages in the log area:

```
Button press count: 2
Button press count: 3
Button press count: 4
Button press count: 5
```

Then the tool is destroyed, which causes the window to disappear.

We use a global variable (main.count) so that its value is maintained between calls to the tool MSC. Local variables in an MSC disappear when the MSC returns. You might notice that most GUI tools create their own partitions for storing all their global variables.

Calculator

Example 9-2 shows the ex2.msc file, located in the \$XMATH/demos/guidirectory.

Example 9-2 Calculator

```
command ex2 {fragname, widgetname, instance}
alias T "ex2"
if( exist(fragname) )
   goto *fragname;
else
   tl=uiToolCreate("ex2")
   wn=uiWindow(tl, {name = "win", title="Tutorial"});
   tb=uiTable(wn, {columns = 2});
  void = uiLabel(tb, {text = "Operand 1"});
  void = uiSlider(tb, {varname = "op1",
            xmath="NewOperand",
            xmathdrag="NewOperand", flags = "hdm",
            min = -1, max = 1)
  void =uiVarChoice(tb, {text="Operation",
            xmath="NewOperation",
            varname= "operation", flags = "H",
            items=["plus", "minus", "times"],
            values=[1,2,3]});
  void = uiLabel(tb, {text="Operand 2"})
  void = uiSlider(tb, {varname = "op2",
            xmath="NewOperand",
            xmathdrag="NewOperand", flags = "hdm",
            min = -1, max = 1)
  void = uiSeparator(tb, {colspan = 2});
   void = uiLabel(tb, {text="Result"})
  void = uiSlider(tb, {varname = "result",
            xmath="NewOperand",
            xmathdrag="NewOperand", flags = "bhdms",
            readonly, min = -2, max = 2)
  void = uiSeparator(tb, {colspan = 2});
   void = uiButton(tb, {text = "Quit",
            col = 1, xmath = "DoQuit"});
  main.op1=0;
  main.op2=0;
  main.operation=1;
   ex2 "NewOperation";
  void = uiShow(wn);
```

```
return:
endif
<NewOperation>
<NewOperand>
   if ( main.operation == 1 )
            main.result = main.op1 + main.op2;
   elseif ( main.operation == 2 )
            main.result = main.op1 - main.op2;
   elseif ( main.operation == 3 )
            main.result = main.op1 * main.op2;
   endif
   return;
<DoOuit>
uiDestroy("ex2");
return:
endcommand
```

When the user types

ex2

a window showing a selectable operation between two operands appears. This window is created using the same steps as the previous tutorial. However, it uses a few more widgets, the first of which is the uiTable(). A table is used for laying out a number of other objects in regular rows and columns.

```
tb = uiTable(wn, {columns=2});
```

The keyword columns does two things:

- It sets the number of columns the table will have
- It specifies that the table will fill rows first

Widgets will be added across the table, one per column.

```
void = uiLabel(tb,{text = "Operand 1"});
```

creates a label containing text string, "Operand 1".

creates a slider bound to the Xmath variable op1. Each time the user sets the slider to a new value, and each time the slider is dragged, the variable op1 is updated and the Xmath callback NewOperand is called. (Similarly, if the variable op1 is set to a new value, the slider moves to the

corresponding position.) The flag hdm specifies that the slider is horizontal. The Xmath variable is updated as the user drags the slider, and the minimum and maximum of -1 and 1 are enforced (even if the Xmath variable is set by the programmer to a value outside this interval).

creates two entries in the table:

- A label containing the text "Operation"
- A box containing three radio buttons with the choices "plus",
 "minus", and "times" bound to the Xmath variable operation.

When the user selects one of these choices, the values 1, 2, and 3, respectively, are assigned to the variable operation. Similarly, if the variable is set to one of these values, the corresponding radio button is set.

Whenever the user selects a new toggle button, the Xmath callback NewOperation is called.

```
void = uiLabel(tb, {text="Operand 2"})
```

creates a label containing the text string, "Operand 2."

creates a slider bound to the Xmath variable op2. This slider is otherwise the same as the first.

```
void = uiSeparator(tb, {colspan = 2});
```

draws a horizontal line in the row. The colspan = 2 keyword expression causes it to occupy both columns in the table.

```
void = uiLabel(tb,{text="Result"})
```

creates a label containing the text "Result."

creates a read-only slider bound to the Xmath variable result. The user cannot drag this slider because of the readonly keyword, but, whenever

the Xmath variable result is set to a new value, the slider changes accordingly. The limits of this slider are -2 and 2.

When the user sets the Operand 1 slider to a new value, the variable op1 is set to the new value, and the Xmath callback NewOperand is called. If the new value is, for example, 0.75, these operations are identical to the user typing the statements:

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```
main.op1 = 0.75;
ex2 "NewOperand", "dontcare",1;
```

The actual widgetname argument will be different, but this is not relevant to the discussion.

This callback causes the following Xmath code to be executed:

```
<NewOperation>
<NewOperand>
   if( main.operation == 1 )
       main.result = main.op1 + main.op2;
elseif ( main.operation == 2 )
       main.result = main.op1 - main.op2;
elseif ( main.operation == 3 )
       main.result = main.op1 * main.op2;
endif
   return;
```

Based on the operation, the new result is computed. Since the variable main.result is bound to the bottom slider, the new value is automatically displayed when the variable is assigned. Similarly, when the user changes the operation, the same Xmath code is called to compute the new result.

For additional examples and descriptions, see the MATRIXx Help.

Translating Version 5.X GUI Files to Version 6.X PGUI Files

This section describes the two utilities for translating Version 5.X GUI files to Version 6.X PGUI files, instructions on executing these scripts, details on using the translator, and some minor limitations.

Overview

Due to the significant changes in the Xmath Programmable GUI (PGUI) syntax in MATRIXx Version 6.X, the to60pgui utility has been created to facilitate the transition of old graphical tools to the new syntax (refer to the *Anatomy of a GUI Tool* section). This utility consists of a pair of Perl scripts that convert the resource and MSC or MSF files from Version 5.X syntax to the Version 6.X syntax.



Note MSC and MSF files are translated in place. Make sure you have a backup.

Execution

The easiest way to execute these Perl scripts is to copy them to a working directory. Ensure that Perl is in your path and copy the tool to be translated to that working directory. Then execute the main script with the following command:

perl to60pgui.pl Mytool mytool.msc

where Mytool is the X resource file used by mytool.msc. A resource file is a collection of resource settings that describe the appearance of the windows,



Note The tool could also be an MSF in which case you provide the appropriate name and extension.

This script modifies the original <code>mytool.msc</code> file (make sure you have a backup) and creates a new file named <code>mytool_build.msf</code> from the resource file. You can then compare the files and make any needed modifications. After that you should be able to run the MSC as before.

The Perl script restopgui.pl converts the X resource file, Mytool, to an MSF file in the new format. To run the resource translator restopgui.pl independently, use the following syntax:

perl restopgui.pl Mytool

where Mytool is the X resource file.

This script creates a new MSF file with the name mytool_build.msf.

Details

The MSC translator scans through an MSC file and changes any Version 5.X GuiFunction() to a Version 6.X uiFunction() with the exception of GuiShellCreate() and GuiDialogCreate(). These functions have no counterpart in the Version 6.X PGUI because there is no need to create a shell separately from creating a window. However, in the old GUI these calls caused the window and its children to be created, so they are not just omitted from the new file. Instead they are changed to a call to an MSF file that is generated from the tool X resource file. This call to the new MSF file has the same result as calling GuiShellCreate() or GuiDialogCreate() in that the window specified and its children are created.

```
For example, in our Fourier tool a GuiShellCreate() call such as: GuiShellCreate("fourier", "MainWin", "Fourier Tool", "fourier tool"):
```

becomes

```
Fourier_build("fourier", "MAINWIN", "Fourier Tool",
"fourier tool");
```

Notice that the second argument is converted to uppercase because the second argument in the fourier_build.msf file is used as the fragment label. The third and fourth arguments are optional as they are in GuiShellCreate(). Refer to the *Limitations* section.

The resource file conversion results in a new MSF file named resourcefile_build.msf. For example, Fourier becomes fourier_build.msf. The resource file conversion is the biggest task of the translator. It takes all of the X resource specifications and creates a hierarchy of Xmath calls to build the desired user interface. The commands in the resulting MSF file are grouped by window and indented to show the hierarchy. Fragment labels separate the code associated with each window so each window can be created as needed.

Limitations

The PGUI translators have some minor limitations because some features are not supported by PGUI or X resource settings need human intervention to be properly assigned. More specifically, X resources set in a global sense, such as a Motif class of widget, are not handled. Also, X resources set to affect all children of a certain widget are not handled. Examples of these are:

```
*MyTool*background: red

and

*MyTool*MainWin*background: redvisible
```

Specific X resources, such as the following, are not supported:

```
*MyTool*MyText.marginwidth: 4
```

In general, anything that cannot automatically be translated is set as a comment using uiSetValue. The generic comments appear in the beginning of the MSF file and the more specific ones appear after the creation of the widget in question.

Within an MSC, calls to GuiSetValue() are not translated if they are of the form

```
GuiSetValue(T, "resource block");
```

where resource block is one or more X resource settings to be applied to the resource database. For both GuiSetValue() and GuiGetValue(), if the resource block is not known, then the command is not translated.



Xmath HP-GL Driver

Xmath supports Hewlett-Packard Graphics Language (HP-GL) hardcopy devices. You can choose to either print to a file (that is, save the output in a file), or print to a printer. To write an HP-GL file, go to the graphics window and select **File»Save** to print to a file or **File»Print** to print to an output device, or use the hpg1 keyword in the HARDCOPY command.



Note The HPGL driver does not support hidden surfaces. For 3-dimensional plots, you must remove the surfaces by suppressing the face keyword (!face or face=0).

Supported Devices

All devices supporting the HP-GL language (for example, HP plotters models HP7550A, 7470, 7475, 7580, 7585, and 7586) should be able to plot the .hp file created by Xmath. The following plotters have been tested: HP7440A, HP7575, and the ENCAD SP2800 plotter.

Setting the Aspect Ratio

Xmath assumes a paper size of 8.5 by 11 inches on the HP7440A, corresponding to a plotting area of 25 by 18.1 cm. The aspect ratio of the hardcopy output might change if you use a different plotter or paper size. You can use the Print Scale options in the Print dialog box to change the aspect ratio of the plot.

Color Pen Specifications

Xmath expects the following color pens to be in the specified stalls in the pen carousel, as indicated in Table A-1.

Table A-1. Color Pen Specifications

Pen Number	Expected Color
1	black
2	blue

Table A-1. Color Pen Specifications (Continued)

Pen Number	Expected Color
3	green
4	cyan
5	red
6	magenta
7	yellow
8	digitizing sight

Xmath attempts to map plot colors to these eight colors.



Xmath for Users of the MathWorks, Inc. MATLAB® Software

Xmath is a numerical problem-solving application similar to The MathWorks, Inc. MATLAB® software and other numerical software. While many of the constructs for storing and manipulating data are similar to those for the MATLAB environment, you will find that Xmath extends both the amount of information stored with a given object and the number of actions a command or function can take, depending on the type of data passed. The Xmath work environment retains the configurable nature you are accustomed to in the MATLAB environment, but there are small variations in the syntax.

This appendix describes changed features, explains the motivation for changes, and in general helps smooth your transition from the MATLAB environment to Xmath. The *Syntactic Differences* section describes basic changes in the punctuation and syntax used in the software. The *Object Differences* section describes objects that were represented as vectors or matrices in the MATLAB environment but are represented as full-fledged data types in Xmath. The *Interpretation Differences* section describes differences that affect environment settings, data representations, and programming issues. The *Comparison of Frequently Used Commands* section provides a comparison between Xmath and the MATLAB environment of frequently used commands. Moreover, tables illustrating equivalent expressions in the MATLAB environment and Xmath appear throughout this appendix.

Syntactic Differences

This section details Xmath features that have the same functionality as MATLAB features, but are invoked in a slightly different way.

Continuation

If an m-file script cannot fit onto a single line in the MATLAB environment, it can be split over multiple lines with two adjacent periods to signal a continuation.

In Xmath, a continuation is seldom needed; if an unmatched parenthesis or brace exists, or the line ends in a comma, Xmath assumes that the expression will continue. Aside from this, the Xmath command area can take a line of nearly infinite length (2^31-1). Most users break their instructions for readability rather than necessity. Xmath uses an ellipsis (...) when an explicit continuation is required. Because strings must be complete on a line, they are the most frequent candidates for continuation. Table B-1 shows examples of command continuation in the MATLAB environment and Xmath.

The MATLAB Environment	Xmath
plot(1:10,'b')	<pre>plot (1:10, {!grid, title="An Easy Plot"})</pre>
title('An Easy Plot')	<pre>plot(x, {title="A very"+</pre>

Table B-1. Command Continuation Examples

Output Display

In the MATLAB environment, variables are by default displayed to the MATLAB Command window as soon as they are created; output is suppressed if a semicolon is placed at the end of the expression that generated the variable.

The default display mode in Xmath behaves similarly. This mode can be explicitly set with the command set display on.

Alternatively, you can specify set display off. In display-off mode, any variable created with an expression containing an equality sign is not displayed to the **Xmath Commands** window log area. For example, A=sin(pi) does not generate any output in the commands window log area if the display is Off. If you want to display a value as soon as it is created, place a question mark (?) at the end of the expression. If you want to see the value of a previously-created variable, type its name; because the name is not an expression (does not contain an equality sign), its value is displayed. Table B-2 shows examples of output display in the MATLAB environment and Xmath.

 The MATLAB Environment
 Xmath (set display on)
 Xmath (set display off)

 A = SIN(PI);
 A = sin(pi);
 A = sin(pi)

 A = SIN(PI)
 A = sin(pi)
 A = sin(pi)?

 A
 A
 A

Table B-2. Output Display Examples

Matrix Punctuation

Matrices are created and entered in the same basic manner, with one important difference—all matrix elements in Xmath must be separated by commas, as shown in Table B-3, whereas commas are optional in the MATLAB environment.

Table B-3. Matrix Punctuation Examples

The MATLAB Environment	Xmath
A = [1 -1 2;-4 3 12]	A = [1, -1, 2; -4, 3, 12]
or	
A = [1, -1, 2; -4, 3, 12]	

When you specify matrix elements separated only by spaces, it is unclear whether the element specification [1-1] represents two separate numbers or the single number 0 (the result of the arithmetic operation 1-1=0). Because matrix elements in Xmath must be explicitly delineated by commas, the value of a given element is always clear both to you and to the Xmath interpreter. You still use semicolons and new lines to mark the end of a matrix row.

String Punctuation

To avoid confusion with the transpose operator, Xmath uses double quotation marks rather than the single quotation marks used in the MATLAB environment. Table B-4 illustrates.

Table B-4. String Punctuation Examples

The MATLAB Environment	Xmath
str = 'This is a string'	str = "This is a string"

The treatment of string variables is discussed in more detail later in this appendix.

Logical Not

In the MATLAB environment the operator denoting a logical not is a tilde (~); in Xmath it is an exclamation point (!). To express an inequality relation in Xmath, use <> (the greater-than and less-than signs); in the MATLAB environment ~= (tilde-equality sign) denotes inequality. Table B-5 shows the logical not operators for the MATLAB environment and Xmath.

The MATLAB Environment

if ~(A > 0)
 disp('A is negative')
end

A ~= B

A <> B

Table B-5. Logical Not Operators

Comments

% line individually in MATLAB.

The single-line comment symbol has been changed from % in the MATLAB environment to # in Xmath. Unlike the MATLAB environment, Xmath supports block comments, which are delineated with # { at the beginning and } # at the end. Instead of beginning each line of a section of comments with #, you can place the # { marker at the beginning of the first comment line and the } # marker at the end of the last comment line. Table B-6 shows comment examples for the MATLAB environment and Xmath.

The MATLAB Environment

% This is a comment.

% Should you feel the need
% to describe what you have
% written at greater length
% you have to comment each

* This is a comment.

This is a block comment. Anything inside the markers is interpreted as a comment. Most programming languages support this construct.}#

Table B-6. Comment Examples

Function Names

Xmath tends to preserve the full names of functions performing a given operation. Where the Hessenberg-decomposition and random-value generation functions in the MATLAB environment are <code>HESS()</code> and <code>RAND()</code>, respectively, the Xmath equivalents are <code>hessenberg()</code> and <code>random()</code>. These names are less cryptic and more descriptive to the new user.

For your convenience, however, Xmath also recognizes a function called using only the first four letters of its name, or as many more as needed to specify the function uniquely. For example, you can call random() as rand(), but would need to use polyn() to distinguish polynomial() from polyfit().

In addition, you can take advantage of the alias command to alias lengthy function names or command statements to shorter ones of your choosing. For example:

alias sdon set display on

Refer to the *Useful Aliases* section for a listing of aliases that you might want to have predefined in a startup file.

RAND, ONES, ZEROS, and EYE

Another syntax change concerns the matrix-building functions RAND(), ONES(), ZEROS(), and EYE(). These functions operate in one of two ways depending on the type of input provided. They either create a random, ones, or identity matrix of the same size as the input, or a matrix of the dimensions specified in the input. This causes some ambiguity when the function argument is a scalar—should the output matrix also be a scalar, or should it be a square matrix whose dimensions have the same value as the scalar?

When these functions are used with one argument in Xmath, the output matrix always has the same dimensions as the input object. Table B-7 illustrates.

The MATLAB
Environment Xmath

RAND(1) random(4) # (a 1x1 matrix)

Table B-7. Examples With RAND

The MATLAB
Environment

RAND(4)

RAND(2,3)

Tandom(4,4) # (a 4x4 matrix)

RAND(2,3) # (a 2x3 matrix)

Table B-7. Examples With RAND (Continued)

IF, FOR, and WHILE

In executable files, MathScript functions, commands, the IF...END, FOR...END, and WHILE...END loops, and conditional structures have been modified slightly. Conditional statements starting with If in Xmath should be closed with endIf, rather than END. Because functions and commands are case-insensitive, any capitalization scheme will work with these constructs. Similarly, Xmath For and While loops terminate with endFor and endWhile, making it much easier for a user reading MathScript to decipher which ending statements close which loops. Table B-8 shows examples of conditional statements in the MATLAB environment and Xmath.

The MATLAB Environment Xmath For variable=vector FOR variable=vector DO, commands: commands endFor END WHILE expression DO, While expression commands; commands endWhile END If relation1 IF relation1 THEN. commands commands: ELSEIF relation2 THEN elseIf relation2 commands commands ELSE, else commands commands; endTf END

Table B-8. Conditional Statement Examples

Pure Imaginary Number

The variable representation of the pure imaginary number—the square root of -1—is jay in Xmath, following engineering standards, as opposed to i in the MATLAB environment.

Several objects that were represented as vectors or matrices in the MATLAB environment are represented as full-fledged data types in Xmath.

Appendix B

Strings

Real character strings in Xmath can be manipulated more easily than strings implemented in the MATLAB environment, which are essentially vectors of ASCII values. For example, in Xmath you can append one string to another one of any length using the + operator. You can also create matrices where elements are all strings of differing sizes. This is a handy way to create a table where text entries are neatly aligned.

Table B-9. String Examples

The MATLAB Environment	Xmath
STR='A string'	str = "A string"

Polynomials

In Xmath, polynomial coefficients and roots are stored as one of two types of polynomial objects instead of vectors. When you create a polynomial, both the roots and the coefficients of that polynomial are stored internally for use in future computations for greatest efficiency and accuracy. Table B-10 gives examples of polynomial creation in the MATLAB environment and Xmath.

Table B-10. Polynomial Examples

The MATLAB Environment	Xmath
<pre>% Creating a polynomial by % listing its coefficients: CP = [1 4 4]</pre>	<pre># Creating a polynomial by # listing its coefficients: cp = makepoly([1,4,4])</pre>
<pre>% Creating a polynomial by % listing its roots: RP = POLY([-2 -2])</pre>	<pre># Creating a polynomial by # listing its roots: rp = polynomial([-2,-2])</pre>

Dynamic Systems

Xmath stores dynamic systems as single objects containing all state-space or numerator/denominator information, as well as any sampling rate information. In the MATLAB environment you need to keep track of different commands for building different types of systems. In Xmath, everything is grouped in the system object. A brief comparison of these representations is shown in Table B-11.

Table B-11. Dynamic Systems Examples

The MATLAB Environment	Xmath
% For statespace systems sys = ss(A, B, C, D);	# Creating a system from # matrices A, B, C, and D:
<pre>% For transfer function sys = tf(num, dem);</pre>	<pre>sys = system(A,B,C,D) # Same command for</pre>
	<pre>transfer fn sys = system(num, dem);</pre>

The system(), makepoly(), and polynomial() functions are far more flexible, and can encompass more information, than their equivalents in the MATLAB software. Refer to the *MATRIXx Help* for a complete reference on these functions.

Interpretation Differences

The differences described in this section are by-products of the complete Xmath user environment. In general, these are conceptual changes that involve learning new terms rather than word-for-word syntax changes.

Environment Commands

Xmath has a highly customizable user environment. Many environment settings in Xmath replace functionalities that existed as individual commands in the MATLAB environment. These include creating session and command diaries, changing display format in the commands window, setting random number distribution and generator seeds and more. In Xmath, settings are treated as parameters that are changed with the SET command; each parameter is a keyword. Help for the SET command describes many new capabilities not included in the MATLAB environment. Read the *MATRIXx Help* to understand the full range of

settings available. A setting remains in its current mode until it is explicitly changed. To see the status of a particular environmental setting, you can use SHOW. For example:

```
show echo #(default is off) set echo on
```

The settings discussed below map closely to capabilities in the MATLAB software you are probably familiar with.

Creating Diaries

Once a diary file has been created, it collects input from your Xmath or MATLAB software session until it is closed. The presence or absence of a diary is thus a mode of operation. The DIARY() function used to start a diary session in the MATLAB environment has been replaced with the set sessiondiary and set commanddiary syntax shown in Table B-12.

The MATLAB Environment

% Creating diaries
DIARY 'stamen'
DIARY off
% MATLAB can't
% keep a
% command diary

"cdname"
remove commandDiary

Table B-12. Creating Diaries

Random Seeds and Distribution

The MATLAB software RAND () function is ambiguous because it returns an output like a standard function when called with purely numeric input, but also takes string input and uses it to set the distribution mode and initial seed. In these cases there is no logical function output. The way Xmath handles these functionalities through the SET command is more consistent, as shown in Table B-13. The Xmath ${\tt random}(\)$ function always returns purely numeric output.

The MATLAB Environment	Xmath
% Setting random % number seed randn('SEED',100)	# Setting random # number seed set seed 100
% Setting distribution randn('NORMAL')	# Setting distribution set distribution normal

Table B-13. Random Seeds and Distribution Examples

The default seed is 0 and the default distribution is uniform.

Number Formatting

The Xmath equivalent to the MATLAB software commands SHORT, SHORT E, LONG, LONG E, HEX, BANK, COMPACT, LOOSE and RAT is set format formatname. An advantage of the Xmath syntax is that it allows a wider range of formatting options without the need to add a new command each time. Table B-14 gives an example.

Table B-14. Number Formatting Examples

The MATLAB Environment	Xmath
% Set number format long % or format long	# Set number format set format long

The Xmath format names are: compact (the default format), engineering, fixed, long, longe, scientific, short, and shorte. Note that the format can also be set interactively using the **Options**» **Format** menu option in the Commands window.

Note that fixed is slightly different in that you must set *two* parameters; you must specify the format name fixed, and the precision:

```
set precision 4; set format fixed
```

The precision is the number of characters allowed. Remember that both settings remain the same until you reset them; if you use the previous settings and then set another format, the precision will still be 4 the next time you SET format to fixed.

User-Defined Functions and Commands

While the MATLAB environment allows you to define optional arguments to a user-defined function or command, delineating them with single quotation marks, Xmath offers related but much richer ways to extend the user input to a MathScript function or command.

In Xmath, optional arguments and keywords are specified following the required argument list when the function is declared.

- Keywords must be delineated with curly braces {}. They can take any values and be specified in any order, but the name of the keyword must always be used so that the Xmath interpreter knows which keyword is being sent. If you are writing your own function or command using keywords, you should provide default values for any keywords where values are not user-supplied. Refer to the Command and Function Calling Syntax section of Chapter 3, MathScript Basics, for more on function syntax.
- Optional arguments can be specified by their value or variable name alone, and are assigned to the optional variables in the order that they are listed. When a function is called with optional arguments, they are listed directly after the required arguments and are not enclosed in curly braces.

In both the MATLAB environment and Xmath, you can define functions and commands that override existing functions and commands, including intrinsic ones. In Xmath, you can place the function or command in the search path or use the DEFINE command to determine which one you want to use (refer to the *Using User-Defined MSFs and MSCs* section of Chapter 6, *MathScript Programming*); in the MATLAB environment, a user-defined function has priority over a function supplied by the MATLAB software.

plot()

In Xmath, plot () is a function that returns an output variable (a graphics object, as discussed in the *Using the plot() Function* section of Chapter 4, *Graphics*). This variable can be subsequently replotted to regenerate a plot, kept to form a background or template for subsequent plots, and augmented via interactive changes to the graphics.

MATLAB software option strings are replaced in Xmath by plot () keywords. Referring to the online Help will give you a good idea of the scope of plot () parameters that you can set in Xmath, but Table B-15 illustrates briefly.

 Table B-15.
 Plot Examples

The MATLAB Environment	Xmath
PLOT(1:10, 'b')	<pre>plot(1:10,{line_color=4}) # or plot(1:10,{line_color="Blue"})</pre>

Transpose Operators

The transpose operator is interpreted differently in Xmath. The MATLAB environment offers only one transpose operator, the apostrophe ('). When used with a complex matrix, the transpose operator performs a Hermitian, or complex-conjugate transpose.

Xmath offers two transpose operators:

- The Xmath apostrophe operator (') performs a regular transpose, leaving complex values untouched.
- The Xmath complex-conjugate transpose operator is the asterisk-apostrophe (*').

For purely real matrices these two transpose operators perform the same function.

Table B-16 illustrates Xmath and the MATLAB software equivalents.

Table B-16. Transpose Operator Examples

The MATLAB Environment	Xmath
A = [1+i 1+2*i; 3-6*i 2+9*i] A'	A = [1+jay,1+2*jay; 3-6*jay,2+9*jay] A*'
CONJ(A')	A'

Convolve

The CONV() function, which performs polynomial and vector convolution in the MATLAB environment, has been replaced by the convolve() function and the * operator in Xmath. convolve() is equivalent to CONV() when used on two vectors or two polynomial objects; however, the * operator performs exactly the same operation on polynomials as convolve() does and is easier to use.

The MATLAB software functions SERIES () and PARALLEL () have been replaced by the Xmath operators * and + respectively, when these operators are used with dynamic systems. You will find the Help and the *Using Operators with Dynamic Systems* section of Chapter 5, *Data Objects and Operators*, useful for a quick but thorough overview of the extended role operators play in Xmath.

Appendix B

Simulation

The MATLAB software continuous- and discrete-time simulation primitives LSIM and DLSIM have been replaced with the <code>system*PDM</code> construct. The parameter-dependent matrix [PDM] is a highly useful data type unique to Xmath. It allows you to store multiple sets of matrix information (input values) that are dependent on a parameter [time]. For a complete explanation of PDMs, refer to the <code>Parameter-Dependent Matrix (PDM)</code> section of Chapter 5, <code>Data Objects and Operators</code>. This construction finds the system response to the input values contained at each point in the PDM. The syntax inherits from terminology frequently used in the linear systems field: Y = H*U, where U represents system input, H represents the mathematical model of the system dynamics, and Y is the output of the system. This is a brief description. For more information, refer to the <code>Time Response</code> section of Chapter 5, <code>Data Objects and Operators</code>.

Note that where the MATLAB environment generally offers two separate functions for discrete- and continuous-time system representations, Xmath only offers one. This is because sampling-rate information (which is by default zero, thus describing a continuous system) is stored with the system object itself. For example, the Xmath function bode (), which encompasses all the functionality of the MATLAB software functions BODE () and DBODE (), automatically checks whether your system is continuous or discrete and then performs the appropriate operations in either case. You can write similarly flexible MathScript functions.

Eval (Executable Strings)

Xmath offers a facility (similar to the MATLAB software EVAL () function) that allows you to create strings containing valid Xmath commands and then execute the contents of the strings. It can be used for creating macros or customizing functions. You can create strings directly or append them using the + operator, then use the EXECUTE command in Xmath. The only constraint is that the string must form a complete Xmath statement by itself and be terminated by a semicolon or question mark to indicate its end. Table B-17 illustrates.

Table B-17. Executable String Examples

As mentioned in the *String Punctuation* section, the MATLAB environment does not allow string concatenation. In Xmath, the + operator is overloaded to perform string concatenation. In addition, numbers can be converted to strings using the string() function.

Executable Files

Executable files (often referred to as script files in Xmath) function similar to script.m files in the MATLAB environment. A small change is that the names of these files must terminate with the extension .ms in Xmath. The syntax to execute files is slightly different as well, as shown in Table Executable Filename Examples, for an executable file called testexec.ms in Xmath and testexec.m in the MATLAB environment.

Table B-18. Executable Filename Examples

The MATLAB Environment	Xmath
TESTEXEC	execute file="testexec"

Finding Files

Xmath has the ability to use files that are not in the working directory. It does this in a more flexible manner than that employed in the MATLAB environment. In the MATLAB environment, the MATLABPATH environment symbol defining the accessible directories is generally set up before you start your MATLAB software session. The MATLABPATH could be changed during a session using the MATLABPATH command, but it had to be completely changed at once. In Xmath you can alter the directory search path at any time during your Xmath session, and you can add or remove paths separately, without having to redefine the entire path each time a modification is desired.

SET path is used to specify a list of directories that Xmath will automatically search to find MathScript functions and commands (MSFs and MSCs). You can use the corresponding REMOVE path command to remove paths you no longer want or need.

If you write an MSF in one of the directories in the path, you can call it immediately from within Xmath. When you call a function you have written, Xmath searches your current directory and all the directories in your path until it finds a function file where name matches the function you called. Upon finding the file, Xmath compiles it to a low-level operational code and it runs immediately. If a function or command file is not in a directory listed as one of your path directories, you need to define it explicitly and specify the directory where it resides.

Table B-19 compares these facilities in Xmath and the MATLAB environment. The operating system commands shown are for a version of the MATLAB software running under a UNIX operating system.

The MATLAB Environment

!pwd show directory

!cd /home/new set directory =
 "/home/new"

!echo \$MATLABPATH % or matlabpath

matlabpath set path = "~me/myfuns"

(no analogous feature) remove path 2

Table B-19. Examples of Finding Files

In the MATLAB environment, the exclamation-point notation (!) can be used to send out an operating-system command and display its output. Xmath offers an analogous oscmd function, as shown in Table B-20.

Table B-20. Operating System Command Examples

The MATLAB Environment	Xmath
!ls -1	oscmd("ls -l")

Debugging Files (on UNIX systems)

The MATLAB software debugging facility consists primarily of keyboard commands. Xmath provides an interactive debugger for MathScript files. It can be used in either of two modes:

 The Xmath debugger is automatically invoked when you try to run a function containing a syntax error. The offending statement is

- highlighted. You can fix the mistake, save the file, and rerun the function, all from the debugger window.
- The second debugging mode is useful when you have written a function and want to halt execution at some point to examine variable values. To do this, type debug functionName in the Xmath Commands window. The debugger will then appear when you call the function, allowing you to step through any portion of the MSF one statement at the time, or to set breakpoints and jump to them. You can use the Commands window to look at local variable values or evaluate expressions.

For more on the debugger window, refer to the *Using the Xmath Debugger* section of Chapter 6, *MathScript Programming*.

Save and Load

The commands for saving and loading data also differ somewhat. The MATLAB environment offers flags that enable you to save data in either a binary format or a short or long ASCII format produced by the MATLAB software. The Xmath SAVE command has a number of keywords associated with it to determine what type of format to use to save the data. The Xmath LOAD command can be used to load in data saved by Xmath or MATRIXx (FSAVE-format data). Table B-21 compares the commands.

The MATLAB Environment	Xmath
SAVE 'filename' VAR1 VAR2	<pre>save var1 var2 file = "filename" {keyword} # The keyword is optional and # may be set for binary, ASCII, # or MATRIXx formatted saves</pre>
LOAD 'filename'	load "filename"
No equivalent feature	load a b "filename"

Table B-21. Save and Load Examples

In Xmath, as in the MATLAB environment, if a list of variables to be saved or loaded is omitted, all variables are saved or loaded. Xmath data files terminate with the suffix .xmd (the MATLAB environment uses the .mat suffix). The MATLAB environment always loads all the data stored in a .mat file; Xmath can load either all or part of the data stored in a .xmd file.

Appendix B

The load command cannot directly load data from the MATLAB environment; however, as described in Chapter 8, *External Program Interface*, you can create a linked executable (LNX) that can. \$XMATH/src/matload.c is a sample LNX that loads MATRIXx 3.X format, which is similar to older MATLAB software formats, into Xmath data objects. This file is commented to assist you in making any changes. To make a local copy of matload.c in the Xmath log area and create a local copy, go to the command area and type:

copyfile "\$XMATH/src/matload.c"

Loading In External Data (read)

Loading in data generated by external programs other than Xmath, MATRIXx, and the MATLAB environment is also possible. If you have data written to a non-Xmath file by another program and you know the size and type of the data in the file, you can use the read() function to read from the data file into an Xmath matrix variable. The input arguments you pass to read() describe how large the matrix should be, the format of the data in the external file, and how many bytes of data (if any) you choose to skip before reading data into the target variable. This allows you to create data files that are easily readable by a variety of programs, not necessarily just Xmath. This function is described in more detail in the Xmath Help, and the \$XMATH/demos directory contains sample files that you can use to test read().

Writing Data to an External File (print, fprintf)

In addition to the Xmath-formatted SAVE command, Xmath provides two other functions that are useful for writing data to external files—print() and fprintf().

print () writes any Xmath data object to an external file you specify. The data is written exactly as it appears when displayed in the Commands window log area.

fprintf() converts scalar numeric values to a string representation, then writes them to the file you specify. A wide range of format specifiers (identical to the ones used for the C-language fprintf() function) can be used to specify field width, zero-padding, tabs, and new lines, among other formatting options.

Useful Aliases

You may want to define the following aliases in a startup.ms file so that you can use familiar names for the following Xmath commands. Some examples follow.

alias	clear	delete
alias	ss2tf	numden
alias	tf2ss	abcd

The MATLAB software function names <code>lyap()</code> and <code>conv()</code> invoke their Xmath counterparts <code>lyapunov()</code> and <code>convolve()</code>, but the Xmath functions have a different set or order of inputs. Along these lines, Xmath has both a <code>rootlocus()</code> and <code>rlocus()</code> function. <code>rlocus()</code> is the one analogous to <code>rootlocus()</code> in the MATLAB environment. To create an alias enter the following:

```
alias rlocus rootlocus
```

Xmath versions do not necessarily take exactly the same inputs in exactly the same order as their equivalents in the MATLAB software. When in doubt, refer to the *MATRIXx Help*.

You are, of course, not limited to these aliases. Xmath commands and functions tend to be as descriptive as possible without being excessively long. As you acquire expertise with Xmath, you will probably want to alias other frequently used commands, as well. To obtain a list of all the aliases currently set up in an Xmath session, type alias on a line by itself in the command area.

Notice that aliases can cause some problems; for example, if you have clear defined as an alias for delete, you will not be able to use clear as a keyword in a function. We recommend that you use aliases to speed your transition from the MATLAB environment to Xmath, and then learn the Xmath syntax as you go along.

Comparison of Frequently Used Commands

Table B-22 summarizes some of the most frequently used Xmath and corresponding MATLAB software commands. Both Xmath and MATLAB software commands are case insensitive.

Table B-22. Xmath and MATLAB Software Summary of Frequently Used Commands

Xmath Command or Operator	MATLAB Software Command or Operator	Description
cond(A)	cond(A)	Finds the condition number.
convolve or *	conv	Performs polynomial and vector convolution.
cos(x)	cos(x)	Calculates the trigonometric cos function.
bode	bode or dbode	The Xmath function bode checks whether your system is continuous or discrete and then performs the appropriate operation.
det(A)	det(A)	Finds the determinant.
eig(A)	eig(A)	Computes eigenvalues and eigenvectors for real and complex square matrices.
execute	eval	Xmath and MATLAB software versions perform similar functions. Refer to the <i>MathScript Batch Files</i> section of Chapter 3, <i>MathScript Basics</i> .
execute file	file.m	Executable files are similar. Refer to the <i>MathScript Batch Files</i> section of Chapter 3, <i>MathScript Basics</i> . In the MATLAB environment, execution of a script can be done directly from the script name. In Xmath, execution must be done with
		the execute() function. (This prevents ambiguous code or accidental execution.)

 Table B-22.
 Xmath and MATLAB Software Summary of Frequently Used Commands (Continued)

Xmath Command or Operator	MATLAB Software Command or Operator	Description
exp(x)	exp(x)	Computes the exponent of (x).
		For matrix exponentiation, the MATLAB environment requires the format expm(A).
eye(A)	eye(A)	Generates the identity matrix.
GuiPlotGet	ginput	Get the current pointer selection and coordinates.
hessenberg	hess	Converts a matrix to Hessenberg form.
hilbert(n)	hilb(n)	Creates a Hilbert ill-conditioned matrix.
hilberttransform	No equivalent	{Apparently this command is available but not documented.}
inv(A)	inv(A)	Finds the inverse matrix.
load	load	Xmath and MATLAB software versions perform similar functions. Refer to the <i>Saving and Loading Data</i> section of Chapter 3, <i>MathScript Basics</i> .
log(x)	log(x)	Computes natural logarithm.
makepoly	No corresponding command	Create a polynomial from its coefficients. The MATLAB environment reformats polynomials by using the corresponding vector with its coefficients.
norm	norm	Calculates the norm of a vector, matrix, or PDM (Xmath only).
No corresponding command?	null	The NULL (A) command in the MATLAB environment calculates an orthonormal basis for the null space of A.

Table B-22. Xmath and MATLAB Software Summary of Frequently Used Commands (Continued)

Xmath Command or Operator	MATLAB Software Command or Operator	Description
ones	ones	Xmath and the MATLAB environment have some minor syntactical differences. For information about the Xmath command, refer to the <i>ones</i> topic of the <i>MATRIXx Help</i> .
ortho	orth	Used as ortho(A) to give the orthonormal basis for A.
pinv	pinv	Used as pinv(A) to give the pseudoinverse for A.
plot(0:10)	plot(0:10)	The basic plot command is the same, but the keyword syntax is different.
polyfit	polyfit	Both commands fit a polynomial, but the Xmath command uses a PDM as input. PDMs are not supported in the MATLAB environment.
polynomial	poly	Create a polynomial from its roots.
polyval	polyval	Evaluates a polynomial.
No corresponding command	quad8 quad -dblquad	Estimates an integral numerically.
random	rand	Generates random numbers or matrices.
residue(sys)	residue(b,a)	Expands a partial fraction.
roots(p)	roots(p)	Returns the roots of a polynomial.
round	round	Round matrix values to the nearest integer.
rref	rref	Transforms a matrix into reduced echelon form.

 Table B-22.
 Xmath and MATLAB Software Summary of Frequently Used Commands (Continued)

Xmath Command or Operator	MATLAB Software Command or Operator	Description
save	save	Xmath and MATLAB software versions perform similar functions. Refer to the <i>Saving and Loading Data</i> section of Chapter 3, <i>MathScript Basics</i>).
schur	schur	Calculates the Schur factorization.
set format name	format name short, short e, long, long e, hex, bank, compact, loose, rat	Xmath format names are compact (the default), engineering, fixed, long, longe, scientific, short, and shorte.
set seed num	rand('seed', num)	Setting the random number seed. In MATLAB Release 5, rand('State), j) gives the jth state. rand('State', s) makes the actual state equal to s (state = s).
sin(x)	sin(x)	Calculates the trigonometric sin() function.
sqrt(x)	sqrt(x)	Calculates the square root of x.
zeros	zeros	Generates a matrix of zeros.
./,.*,	./,.*,	Point preceding operator means elementwise operation.
' and *'	.' and '	Transpose operators. The operators on the left (' and .') are for regular transpose and The operators on the right are for complex-conjugate transpose.
+	parallel	The overloaded Xmath + operator performs the same function as the MATLA software B parallel() function.

Table B-22. Xmath and MATLAB Software Summary of Frequently Used Commands (Continued)

Xmath Command or Operator	MATLAB Software Command or Operator	Description
*	series	The overloaded Xmath * operator performs the same function as the MATLAB software series() function.
# # or # #	8	Indicates a comment. MATRIXx supports block comments that span multiple lines. The second # is only needed for a multiple-line comment.
"string"	'string'	MATRIXx uses double quotes to avoid confusion with the transpose operator.
A <> B	A~=B	Logical NOT EQUAL operators.
! A	~A	Logical NOT operators.
x = A\b	x = A\b	Computes the least squares approximation $(Ax = b)$.



Xmath to Mathematica Interface

This appendix describes how to set up and use the Xmath to Mathematica Interface.

Overview

Mathematica is a powerful symbolic manipulation program from Wolfram Research, Inc. (WRI). It performs operations such as differentiation and integration symbolically, achieving exact general solutions to many problems. This capability can be coupled with the powerful numerical analysis and design capabilities of Xmath, resulting in a very strong joint analysis tool.

Xmath was developed with an open architecture, which simplifies communication with other programs and processes. The interface between Xmath and Mathematica is based on the Xmath LNX (link external) capability and Mathematica's Mathlink facility. When Mathematica is first invoked from Xmath, Mathematica's Mathlink facility establishes a process running Mathematica, and maintains a link to that process for all subsequent calls from the same Xmath session, allowing Xmath the use of intermediate variables in Mathematica. Furthermore, the Mathlink facility allows Mathematica to be invoked on a different computer than the Xmath host. This is completely transparent to the user.

When a valid Mathematica command is entered in the Commands window command area, a separate Mathematica process computes the answer (commands that produce graphics should never be used). The resulting text output that would normally appear in Mathematica is converted to an Xmath string object that is displayed in the Commands window log area. If the answer is a numeric matrix, it can be passed directly to Xmath. Matrices can also be passed from Xmath to Mathematica. All Mathematica warnings and other messages are transmitted to Xmath and displayed in the Commands window message area.

For a more detailed explanation of the LNX process, refer to Chapter 8, *External Program Interface*. The source for the Xmath to Mathematica interface can be found in \$XMATH/src/mathlink.c.

Setup

These instructions apply to setting up Xmath, and the Xmath to Mathematica interface on an Xmath host. If you encounter problems related to Mathematica functionality, contact Wolfram Research, Inc. Their Web site is http://www.wri.com, their e-mail address is support@wolframi.com, and their Technical Support phone number in the USA is 217-398-6500.

To use the Xmath to Mathematica interface the following conditions must be met.

- Mathematica must be installed and accessible to you, the Xmath user.
 The Mathematica version must be 3.0 or later.
- Only UNIX versions of Xmath and Mathematica are supported.
- Your UNIX execution path must include the path to your Mathematica installation directory. For example,

set path = (\$path /home/Mathematica/Executables/SPARC)
 where the above path points to the Mathematica installation at
 your site.

Because the Mathematica interface LNX must be linked with the local Mathlink libraries on your target system, National Instruments cannot deliver an executable interface. However, we have provided all of the necessary routines to quickly create an executable interface LNX.

To allow all users access to the Xmath to Mathematica interface, a system administrator must perform the steps in the *Setting Up the Xmath to Mathematica Interface for All Users* section. Users who do not have system privileges can perform the steps in the *Creating a Local LNX* (*Single User*) section to create a local LNX.

Setting Up the Xmath to Mathematica Interface for All Users

These instructions assume the \$MTXHOME environment variable was properly set at installation time to the path to the root MATRIXx product family installation.

- 1. Change directory to \$MTXHOME/platform/xmath/src.
- 2. Edit the mma . mk file as follows:
 - a. Define the XMATH variable to be \$ (MTXHOME) / platform/xmath.
 - b. Replace PATH_TO_libML.a with the path to the Mathlink libraries. Ror example:
 - */Mathematica/AddOns/MathLink/DevKits/SPARC/CompilerAddOns
- 3. To create mmalnx.lnx, run the makefile as follows:

```
make -f mma.mk
```

 Copy mmalnx.lnx to \$MTXHOME/platform/xmath/modules/ mathematica.

All Xmath users will now be able to use the Xmath to Mathematica interface.

Creating a Local LNX (Single User)

Although it is preferable to have a system administrator set up the Xmath to Mathematica interface, a user with no root privileges can set up an LNX for his personal use. To use the Mathematica interface without modifying the Xmath source directories, the user can copy \$MTXHOME/platform/xmath/src/mma.mk and mathlink.c to a local directory, and then perform steps 2 and 3 described in the Setting Up the Xmath to Mathematica Interface for All Users section. However, before using the interface, the user must tell Xmath not to look in the modules directory for the LNX. To do this type the following Xmath commands in the Xmath Commands window command area:

```
undefine mma
define mma {directory="path_to_lnx"}
```

For future usability, these lines can be placed in your personal Xmath startup.ms file, along with a set path command that points to the location of your local mmalnx.lnx file, so that if you start Xmath from another directory you will still be able to use the LNX. For example:

```
set path="path_to_lnx"
```

Refer to the *startup.ms* (on *UNIX systems*) section of Chapter 3, *MathScript Basics*, for more on startup.ms, and the *Search Paths* section of Chapter 6, *MathScript Programming*.

Syntax

Xmath provides three functions, which perform the following tasks:

1. Send a command to Mathematica (a Mathematica session is started if one does not exist):

```
mma("valid_Mathematica_cmd")
mma is actually an accepted abbreviation for mmaexecute.
```

2. Transfer a matrix from Xmath to Mathematica:

```
mmaput("mma_matrix_name", xmath_matrix_name)
```

3. Transfer a matrix from Mathematica to Xmath:

```
xmath_matrix_name = mmaget("mma_matrix_name")
```

Note that you can assign the output of a Mathematica command to a Mathematica variable and an Xmath variable in one step:

```
xmath_var = mmaget("var=Mathematica_numerics_cmd")
```

4. Close the Mathematica session:

```
mma("quit")
```

The lowercase string "quit" causes the LNX to close the Mathematica process. However, the LNX stays resident and active. If you issue another Mathematica command, the existing LNX will restart Mathematica. When you exit Xmath, the LNX will be killed.

Passing Xmath Data to Mathematica

You can pass scalars, vectors, or matrices from Xmath to Mathematica. These forms all qualify as matrix objects in Xmath.

Mathematica assumes all incoming values are matrices and places them in nested Lists. For example, the Xmath matrix [1,2;3,4] is represented as $\{\{1,2\},\{3,4\}\}$ when passed to Mathematica, and the Xmath scalar 7.2 is represented as $\{\{7,2\}\}$.

Xmath vectors should always be passed to Mathematica as *row* vectors. If a column vector is passed, the resulting nested list will not be as readily useful. After a row vector is passed to Mathematica, it can be extracted from a nested List to a single List using x=x[[1]]. Scalars can be extracted from a nested List to a true scalar using s=s[[1,1]].

Lists or nested Lists can be passed to Xmath from Mathematica. The Lists can only contain numerical data, never symbolic data. In the case of nested Lists, the component List lengths must be equal so that Xmath can convert the List to a matrix.

Appendix C

A Mathematica symbolic matrix can be converted to a numerical equivalent using the command x=N[x], and the result can then be passed to Xmath. For example:

```
mma("x = Table[EllipticK[i], {i, 0, 2/3, 1/6}]")
x=mmaget("N[x]")
```

To pass a scalar to Xmath it must first be placed in a List of length one. This can be done using the command $a=\{a\}$.

Examples

The following Xmath inputs and Mathematica responses demonstrate how data is passed between the applications.

When we ask for the Mathematica version, Xmath receives a string:

```
mma("$Version")
ans (a string) = SPARC 3.0 (April 26, 1997)
```

The following call to Mathematica asks for a numeric result with a precision of 40.

```
str=mma("N[EulerGamma, 40]")
str (a string) =
0.5772156649015328606065120900824024310422
```

We can convert this simple string to a number in Xmath and compare the displays. First, we set the format to longe, the longest output Xmath can display. Then we can convert the string to a scalar with makematrix:

```
set format longe
s=makem(str)
s (a scalar) = 5.772156649015329e-01
```

Symbolic output (strings containing superscripts or a mixture of text and numbers) can be viewed in the **Xmath Commands** Window log area, but not used as Xmath inputs:

Create a matrix in Xmath and send it to Mathematica:

You can use Mathematica functions to manipulate the matrix and pass numeric versions of the matrix manipulations back to Xmath:

```
mRev=mmaget("mRev=N[Reverse[m],9]");
mRot=mmaget("mRot=N[RotateLeft[m,2],9]");
```

Display the matrices (in compact form):

mRev?

```
17 Inf 0.02
7 2.22507e-308 6
3.14159 42 0
```

mRot?

mRot (a square matrix) =

```
3.14159 42 0
17 Inf 0.02
7 2.22507e-308 6
```

For more examples, execute the following files \$XMATH/demos/mathematica/mma.ms and \$XMATH/demos/mathematica/elliptic.ms.



Technical Support and Professional Services

Visit the following sections of the National Instruments Web site at ni.com for technical support and professional services:

- **Support**—Online technical support resources at ni.com/support include the following:
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If you searched ni.com and could not find the answers you need, contact your local office or NI corporate headquarters. Phone numbers for our worldwide offices are listed at the front of this manual. You also can visit the Worldwide Offices section of ni.com/niglobal to access the branch office Web sites, which provide up-to-date contact information, support phone numbers, email addresses, and current events.

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